

$$\ddot{x} + x + \epsilon(x^2 - 1)\dot{x} = 0$$

$$\text{let } x = x_0(\tau, \epsilon) + \epsilon x_1(\tau, \epsilon) + \epsilon^2 x_2(\tau, \epsilon) + O(\epsilon^3)$$

$$\omega / \begin{matrix} \tau = \epsilon t \\ \tau = t \end{matrix}$$

$$\Rightarrow \partial_{\tau\tau} x_0 + \epsilon(\partial_{\tau\tau} x_1 + 2\partial_{\tau T} x_0) + O(\epsilon^2)$$

$$+ x_0 + \epsilon x_1 + \epsilon(x_0^2 - 1)(\partial_{\tau} x_0 + O(\epsilon)) = 0$$

$$\Rightarrow \partial_{\tau\tau} x_0 + \epsilon(\partial_{\tau\tau} x_1 + 2\partial_{\tau T} x_0) + x_0 + \epsilon x_1 + \epsilon(x_0^2 - 1)\partial_{\tau} x_0 + O(\epsilon^2) = 0$$

$$\Rightarrow \mathcal{O}(1) \quad \partial_{\tau\tau} x_0 + x_0 = 0$$

$$\mathcal{O}(\epsilon) \quad \partial_{\tau\tau} x_1 + x_1 = -2\partial_{\tau T} x_0 - (x_0^2 - 1)\partial_{\tau} x_0$$

$$\text{let } x_0 = r(\tau) \cos(\tau + \phi(\tau)) \quad \text{put in } \mathcal{O}(\epsilon) \text{ eq}$$

$$\partial_{\tau\tau} x_1 + x_1 = -2\partial_{\tau} (-r(\tau) \sin(\tau + \phi(\tau))) - (r^2 \cos^2(\tau + \phi) - 1)(-r \sin(\tau + \phi))$$

$$= 2[r'(\tau) \sin(\tau + \phi(\tau)) + r(\tau) \cos(\tau + \phi(\tau)) \phi'(\tau)]$$

$$= -r \sin(\tau + \phi) [r^2 \cos^2(\tau + \phi) - 1]$$

$$= -2[r' \sin(\tau + \phi) + r \cos(\tau + \phi) \phi'] + r \sin(\tau + \phi) \cos^2(\tau + \phi)$$

using trig identity. get

$$\partial_{\tau\tau} x_1 + x_1 = 2[r' \sin(\tau + \phi) + r \cos(\tau + \phi) \phi'] + r \sin(\tau + \phi) \cos^2(\tau + \phi)$$

$$\partial_{\tau} x_1 + x_1 = 2 \left[r' \sin(\tau + \phi) + r \cos(\tau + \phi) \phi' \right] + r \sin(\tau + \phi) - \frac{r^3}{4} \left[\sin(\tau + \phi) + \sin 3(\tau + \phi) \right]$$

$$= \left(2r' + r - \frac{r^3}{4} \right) \sin(\tau + \phi)$$

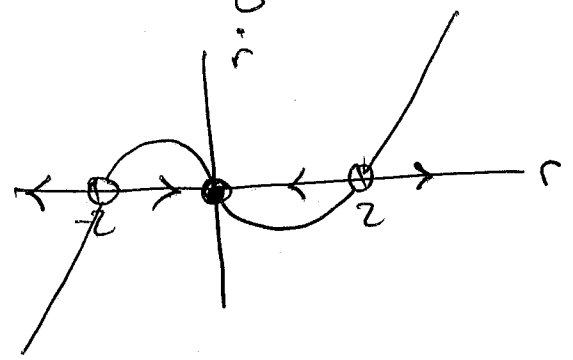
$$+ (2r\phi') \cos(\tau + \phi) + \underbrace{-\frac{r^3}{4} \sin(3(\tau + \phi))}_{\text{not secular}}$$

$$\Rightarrow 2r' + r - \frac{r^3}{4} = 0$$

$$2r\phi' = 0$$

$$r' = \left(\frac{r^3}{4} - r \right) \frac{1}{2} = \frac{1}{2} \cdot \frac{r}{4} (r^2 - 4) = \frac{r}{8} (r^2 - 4)$$

$$= \frac{r}{8} (r - 2)(r + 2)$$



$$\overset{\infty}{x} + x + \epsilon h(x, \overset{\infty}{x}) = 0$$

~~Q~~ Solve using 2 timing $\tau = t$
 $T = \epsilon t$

$$x = x_0(\tau T) + \epsilon x_1(\tau T) + \epsilon^2 x_2(\tau T) + O(\epsilon^3)$$

$$\overset{\circ}{x} = x_{0T} + \epsilon(x_{0T} + x_{1T}) + O(\epsilon^2)$$

$$\overset{\circ}{x} = x_{0TT} + \epsilon(x_{0TT} + x_{1TT}) + \epsilon x_{0TT} + O(\epsilon^2)$$

$$= x_{0TT} + \epsilon(x_{1TT} + 2x_{0TT}) + O(\epsilon^2)$$

put in (45)

$$x_{0TT} + \epsilon(x_{1TT} + 2x_{0TT}) + x_0 + \epsilon x_1 + O(\epsilon^2)$$

$$+ \epsilon h(x_0 + \epsilon x_1 + \dots, x_{0T} + \epsilon(x_{0T} + x_{1T}) + \dots) = 0$$

$$\Rightarrow \overline{x_{0TT} + \epsilon x_1}$$

$$x_{0TT} + x_0 + \epsilon(x_{1TT} + 2x_{0TT} + x_1) +$$

$$\epsilon h(x_0, x_{0T}) + O(\epsilon^2) = 0$$

$$O(1) \quad x_{0TT} + x_0 = 0$$

$$O(\epsilon^2) \quad x_{1TT} + x_1 = -2x_{0TT} - h$$

7.3.8

change (r, θ) to (x, y)

$$\dot{r} = r(1-r^2) + \mu r \cos \theta \quad \dot{\theta} = 1$$

into $x + y \quad r^2 = x^2 + y^2$

$$2r\dot{r} = 2x\dot{x} + 2y\dot{y}$$

$$\dot{r} = \frac{x}{r}\dot{x} + \frac{y}{r}\dot{y}$$

~~Equation~~

$$\dot{\theta} = \frac{x\dot{y} - y\dot{x}}{r^2} = 1$$

$$x\dot{y} - y\dot{x} = r^2 = x^2 + y^2$$

$$\frac{x\dot{x} + y\dot{y}}{r}$$

$$x\dot{x} + y\dot{y} = r^2(1-r^2) + \mu r^2 \cos \theta + x\dot{y} - y\dot{x} = x^2 + y^2 = r^2$$

Mult 1st eq by y

+ 2nd eq by x ↓ ↓ ↓

$$\underbrace{(y^2 + x^2)}_{r^2} \dot{y} = yr^2(1-r^2) + y\mu r^2 \cos \theta + rx^2$$

$$\dot{y} = y(1-r^2) + y\mu \cos \theta + x$$

2

• Mult 1st eq by $-x$

2nd eq by y + All

$$\Rightarrow -x^2 \dot{x} + -y^2 \dot{x} = ~~xxx~~ -xr^2(1-r^2) + yr^2 \cos \theta (-x) + r^2 y$$

$$\Rightarrow \dot{x} = x(1-r^2) + r^2 \cos \theta (-x) - y$$

∴ eqs below

$$\dot{y} = y(1-x^2-y^2) + \frac{xyx}{\sqrt{x^2+y^2}} + x$$

$$\dot{x} = x(1-x^2-y^2) + \frac{xyx}{\sqrt{x^2+y^2}} - y$$

7.6.10

$$\sin \theta \cos^2 \theta = \left(\frac{e^{i\theta} - e^{-i\theta}}{2i} \right) \left(\frac{e^{i\theta} + e^{-i\theta}}{2} \right)^2$$

$$\begin{aligned} \text{Ma} \\ &= \frac{1}{4} \left(\frac{e^{i\theta} - e^{-i\theta}}{2i} \right) + \frac{1}{4} \left(\frac{e^{3i\theta} - e^{-3i\theta}}{2i} \right) \end{aligned}$$

$$= \frac{1}{4} \quad \checkmark \quad \checkmark$$

7.6.15

$$(a) \quad \ddot{x} + \sin x = 0 \quad \approx \quad \ddot{x} + x - \frac{1}{6}x^3 = 0$$

Try Poincaré method

$$x(t) = x_0(T) + \epsilon x_1(T) + \dots$$

$$T = \omega t$$

$$= (1 + \epsilon\omega_1 + \epsilon^2\omega_2 + \dots)t$$

Then $\dot{x} = \omega \frac{dx}{dT}$

put in DE

$$\omega^2 \frac{d^2 x}{dT^2} + x - \frac{1}{6}x^3 = 0$$

$$\Rightarrow \left(1 + 2\omega_1\epsilon + 2\omega_2\epsilon^2 + \omega_1^2\epsilon^2 + \dots \right) \left[\frac{d^2 x_0}{dT^2} + \epsilon \frac{d^2 x_1}{dT^2} + \epsilon^2 \frac{d^2 x_2}{dT^2} + \dots \right]$$

$$+ x_0 + \epsilon x_1 + \epsilon^2 x_2 + \dots - \frac{1}{6} (x_0^3 + 3x_0^2 x_1 \epsilon + 3x_0 x_1^2 \epsilon^2 + \dots)$$

1st small Δ let in $x_0 + x - \frac{1}{6} x^3 = 0$

$$x = \epsilon \tilde{x}$$

$$\text{Then } \epsilon \tilde{x}_0 + \epsilon \tilde{x} - \frac{1}{6} \epsilon^3 \tilde{x}^3 = 0$$

$$\Rightarrow \tilde{x}_0 + \tilde{x} - \frac{1}{6} \epsilon^2 \tilde{x}^3 = 0 \quad \text{Then let } \epsilon' = \epsilon^2 \quad \downarrow$$

to get basic eq

$$\tilde{x}_0 + \tilde{x} - \frac{1}{6} \epsilon' \tilde{x}^3 = 0$$

Then Apply power method as above



$$\begin{aligned}
& (x_0 + \epsilon x_1 + \Sigma)^3 \\
&= (x_0 + \epsilon x_1 + \Sigma)(x_0 + \epsilon x_1 + \Sigma)(x_0 + \epsilon x_1 + \Sigma) \\
&= \left((x_0 + \epsilon x_1)^2 + 2(x_0 + \epsilon x_1)O(\epsilon^2) + O(\epsilon^4) \right) (x_0 + \epsilon x_1 + \Sigma) \\
&= (x_0 + \epsilon x_1)^3 + 2(x_0 + \epsilon x_1)^2 \overset{O(\epsilon^2)}{O(\epsilon^2)} + O(\epsilon^4) + O(\epsilon^2) + O(\epsilon^4) \\
&\qquad\qquad\qquad + O(\epsilon^6)
\end{aligned}$$

Ans Q14:

$$\Rightarrow \frac{d^2 x_0}{dt^2} + \epsilon \left(\frac{d^2 x_1}{dt^2} + 2\omega_1 \frac{dx_0}{dt} \right) + \epsilon^2 \left(\quad \right) + \dots$$

$$+ x_0 + \epsilon x_1 + \epsilon^2 x_2 + \dots$$

$$- \frac{1}{6} \left(x_0^3 + 3x_0^2 x_1 \epsilon + \dots \right)$$



O(1)

$$\frac{d^2 x_0}{dt^2} + x_0 = 0 \Rightarrow x_0(t) = Ae^{it} + A^* e^{-it}$$

O(\epsilon)

$$\frac{d^2 x_1}{dt^2} + x_1 = -2\omega_1 \frac{d^2 x_0}{dt^2} + \frac{1}{6} x_0^3$$

$$= +2\omega_1 [Ae^{it} + A^* e^{-it}] + \frac{1}{6} [A^3 e^{3iT} + 3AA^* e^{iT} + 3AA^{*2} e^{-iT} + A^{*3} e^{-3iT}]$$

$$= \frac{1}{6} [A^3 e^{3iT} + A^{*3} e^{-3iT}] + \left[2\omega_1 A + \frac{A^2 A^*}{2} \right] e^{iT}$$

$$+ \left[2\omega_1 A^* + \frac{A^{*2} A}{2} \right] e^{-iT}$$

pick $\omega_1 = -\frac{AA^*}{4} = \frac{-|A|^2}{4}$

Then sol

$$x(t) = Ae^{i(1 - \frac{|A|^2}{4})t} + A^* e^{-i(1 - \frac{|A|^2}{4})t}$$

7.6.18

$$\ddot{x} + (\alpha + \epsilon \cos t)x = 0 \quad \alpha \approx 1$$

$$T = \epsilon^2 t$$

Should this be power series in ϵ^2 ?
Don't think so.

$$x = X(t, T) = x_0(t, T) + \epsilon x_1(t, T) + \epsilon^2 x_2(t, T) + \dots$$

$$\frac{dx}{dt} = \frac{\partial x}{\partial t} + \epsilon^2 \frac{\partial x}{\partial T} =$$

$$\frac{d^2 x}{dt^2} = \frac{\partial^2 x}{\partial t^2} + 2\epsilon^2 \frac{\partial^2 x}{\partial t \partial T} + \epsilon^4 \frac{\partial^2 x}{\partial T^2} \quad \text{put in above}$$

~~$$= \frac{\partial^2 x_0}{\partial t^2} + 2\epsilon^2 \frac{\partial^2 x_0}{\partial t \partial T} + \epsilon^4 \frac{\partial^2 x_0}{\partial T^2} + \epsilon \left(\frac{\partial^2 x_1}{\partial t^2} + 2\epsilon^2 \frac{\partial^2 x_1}{\partial t \partial T} + \epsilon^4 \frac{\partial^2 x_1}{\partial T^2} \right) +$$~~

$$\frac{\partial^2 x_0}{\partial t^2} + \epsilon \frac{\partial^2 x_1}{\partial t^2} + \epsilon^2 \frac{\partial^2 x_2}{\partial t^2} + \epsilon^3 \frac{\partial^2 x_3}{\partial t^2} + \dots$$

$$+ 2\epsilon^2 \left(\frac{\partial^2 x_0}{\partial t \partial T} + \epsilon \frac{\partial^2 x_1}{\partial t \partial T} + \epsilon^2 \frac{\partial^2 x_2}{\partial t \partial T} + \dots \right)$$

$$+ \epsilon^4 \left(\frac{\partial^2 x_0}{\partial T^2} + \epsilon \frac{\partial^2 x_1}{\partial T^2} + \epsilon^2 \frac{\partial^2 x_2}{\partial T^2} + \dots \right) + \alpha (x_0 + \epsilon x_1 + \epsilon^2 x_2 + \dots)$$

$$+ E \cos t (x_0 + \epsilon x_1 + \epsilon^2 x_2 + \dots) = 0.$$

2

$$\Rightarrow \left(\frac{\partial^2 x_0}{\partial t^2} + a x_0 \right) + \epsilon \left(\frac{\partial^2 x_1}{\partial t^2} + a x_1 + x_0 \cos t \right) + \epsilon^2 \left(\frac{\partial^2 x_2}{\partial t^2} + 2 \frac{\partial^2 x_0}{\partial t \partial T} + x_1 \cos t \right)$$

$$+ \epsilon^3 \left(\frac{\partial^2 x_3}{\partial t^2} + 2 \frac{\partial^2 x_1}{\partial t \partial T} + a x_3 + \cos t x_2 \right) + \dots = 0$$

7.6.18

$$\ddot{x} + (a + \epsilon \cos t)x = 0 \quad a \geq 1$$

two terms

$$x = x_0(t, T) + \epsilon x_1(t, T) + \dots = \sum_{k=0}^{\infty} \epsilon^k x_k(t, T)$$

$$\dot{x} = \frac{\partial}{\partial t} x + \epsilon^2 \frac{\partial}{\partial T} x = \sum_{k=0}^{\infty} \epsilon^k \frac{\partial x_k}{\partial t} + \sum_{k=0}^{\infty} \epsilon^{k+2} \frac{\partial x_k}{\partial T}$$

put in

$$\ddot{x} = \left(\frac{\partial^2}{\partial t^2} + 2\epsilon^2 \frac{\partial^2}{\partial t \partial T} + \epsilon^4 \frac{\partial^2}{\partial T^2} \right) x = \sum_{k=0}^{\infty} \epsilon^k \frac{\partial^2 x_k}{\partial t^2} + 2 \sum_{k=0}^{\infty} \epsilon^{k+2} \frac{\partial^2 x_k}{\partial t \partial T} + \sum_{k=0}^{\infty} \epsilon^{k+4} \frac{\partial^2 x_k}{\partial T^2}$$

$$\sum_{k=0}^{\infty} \epsilon^k \frac{\partial^2 x_k}{\partial t^2} + 2 \sum_{k=0}^{\infty} \epsilon^{k+2} \frac{\partial^2 x_k}{\partial t \partial T} + \sum_{k=0}^{\infty} \epsilon^{k+4} \frac{\partial^2 x_k}{\partial T^2} + a \sum_{k=0}^{\infty} \epsilon^k x_k + \cos t \sum_{k=0}^{\infty} \epsilon^{k+1} x_k = 0$$

$$\frac{O(1)}{\epsilon^2} \frac{\partial^2 x_0}{\partial t^2} + a x_0 = 0$$

$$\Rightarrow x_0(t; T) = A(T) e^{i\sqrt{a}t} + A^*(T) e^{-i\sqrt{a}t}$$

0(t)

$$\frac{\partial^2 x_1}{\partial t^2} + a x_1 + \omega \sin x_0 = 0$$

$$\frac{\partial^2 x_1}{\partial t^2} + a x_1 = - [$$

7.6.19

$$x'' + x + \epsilon x^3 = 0$$

$$x(0) = a$$

$$x'(0) = 0$$

(a) $\tau = \omega t$

$$\frac{d^2}{dt^2} = \omega^2 \frac{d^2}{d\tau^2}$$

$$\Rightarrow \omega^2 \frac{d^2 x}{d\tau^2} + x + \epsilon x^3 = 0.$$

(b) $x(\tau, \epsilon) = \sum_{k=0}^{\infty} \epsilon^k x_k(\tau)$

$$\Rightarrow (1 + \omega_1 \epsilon + \omega_2 \epsilon^2 + \dots)^2 \sum_{k=0}^{\infty} \epsilon^k x_k''(\tau) + \sum_{k=0}^{\infty} \epsilon^k x_k(\tau) + \epsilon \left(\sum_{k=0}^{\infty} \epsilon^k x_k \right)^3 = 0$$

$$\Rightarrow (1 + 2\omega_1 \epsilon + 2\omega_2 \epsilon^2 + \omega_1^2 \epsilon^2 + \dots) \sum_{k=0}^{\infty} \epsilon^k x_k'' + \sum_{k=0}^{\infty} \epsilon^k x_k + \epsilon \left(x_0^3 + 3x_0^2 x_1 \epsilon + 3x_0 x_1^2 \epsilon^2 + \dots \right)$$

Q(1)

$$x_0'' + x_0 = 0$$

Q(ε)

$$x_1'' + 2\omega_1 x_0'' + x_1 + x_0^3 = 0 \quad \checkmark$$

(c) I.C. $x_0(0) = a$
 $x_k(0) = 0 \quad k \geq 1$

$$\dot{x}(0) = \omega \frac{dx(0)}{dt} = (1 + \epsilon \omega_1 + \dots)(x_0' + \epsilon x_1' + \dots)$$
$$= x_0' + \epsilon(\omega_1 x_0' + x_1') + \dots$$

$$x_0'(0) = 0 \quad \omega_1 x_0'(0) + x_1'(0) = 0 \quad = \quad x_1'(0) = 0 \quad = \quad x_1'(0) = 0$$



(d) I.C $x_0(\tau) = a \cos \tau$

(e) O.C

$$x_1'' + x_1 = +2\omega_1 a \cos \tau - \frac{a^3}{8} (e^{i\tau} + e^{-i\tau})^3$$

$$\parallel$$

$$- \frac{a^3}{8} (e^{3i\tau} + 3e^{i\tau} + 3e^{-i\tau} + e^{-3i\tau})$$

$$- \frac{a^3}{4} (\cos 3\tau + 3\cos \tau)$$

$$= (2\omega_1 a - \frac{3}{4} a^3) \cos \tau - \frac{a^3}{4} \cos 3\tau$$

Pick $\omega_1 = \frac{3a^2}{8}$

$$x_{1 \text{ part}} = - \frac{a^3}{4} \left[\frac{e^{3i\tau}}{-8} + \frac{e^{-3i\tau}}{-8} \right] = \frac{a^3}{16} [\cos 3\tau]$$

$$x_1(\tau) = B + \frac{a^3}{16} = 0 \Rightarrow B =$$

$$= \frac{a^3}{16} \cos 3\tau - \frac{a^3}{16} \cos \tau$$

$$\therefore x(t) = a \cos \left(1 + \frac{3a^2}{8}t\right) + \frac{a^3}{16} \left(\cos 3\left(1 + \frac{3a^2}{8}t\right) + \cos \left(1 + \frac{3a^2}{8}t\right) \right)$$

7.6.20

$$x'' + x + \epsilon x^3 = 0 \quad x(0) = a, \quad \dot{x}(0) = 0$$

Q11

$$x(t) = \sum_{k=0}^{\infty} \epsilon^k x_k(t)$$

$$x_0'' + x_0 = 0$$

$$x_0(t) = a \cos t$$

O(ϵ)

$$x_1'' + x_1 + x_0^3 = 0$$

$$x_1'' + x_1 = -\frac{a^3}{8} \left[e^{3it} + 3e^{it} + 3e^{-it} + e^{-3it} \right]$$

$$x_{1, \text{part}} = -\frac{a^3}{4} \left[\frac{1}{8} (2 \cos 3t) \right] - \frac{3a^3}{4} \left[\frac{1}{D^2 + 1} (e^{it} + e^{-it}) \right]$$

$$= \frac{(2)}{32} \cos 3t - \frac{3}{4} \left[\frac{1}{(D-i)(D+i)} e^{it} + \frac{1}{(D+i)(D-i)} e^{-it} \right] \quad 2$$

$$= \frac{1}{16} \cos 3t - \frac{3}{4} \left[\frac{1}{2i} \frac{1}{D-i} e^{it} (1) + \frac{-1}{2i} \frac{1}{D+i} e^{-it} \right] \quad \left. \begin{array}{l} \text{Mult} \\ \text{All} \\ \text{by } a^3 \end{array} \right\}$$

$$= \frac{\cos 3t}{16} - \frac{3}{2 \cdot 4} \left[e^{it} t - e^{-it} t \right]$$

$$= \quad \text{"} \quad - \frac{3}{4} t \sin t.$$

Q. + I.C $x_1(0) = 0 \quad \dot{x}_1(0) = 0$

$$\Rightarrow x_1(t) = -\frac{1}{16} \cos t + \frac{\cos 3t}{16} - \frac{3}{4} t \sin t$$

$$\therefore x(t) = a \cos t + e a^3 \left[\frac{1}{16} (\cos 3t - \cos t) - \frac{3}{4} t \sin t \right]$$

7.6.24

$$\ddot{x} + \epsilon(x^2 - 1)\dot{x} + x = 0$$

let $\tau = \omega t = (1 + \omega_1 \epsilon + \omega_2 \epsilon^2 + \dots) t$

$$\frac{dx}{dt} = \frac{d\tau}{dt} \frac{dx}{d\tau} = (1 + \omega_1 \epsilon + \omega_2 \epsilon^2 + \dots) \frac{dx}{d\tau}$$

$$\frac{d^2x}{dt^2} = (1 + \epsilon \omega_1 + \epsilon^2 \omega_2 + \dots)^2 \frac{d^2x}{d\tau^2}$$

I.C. $x(0) = a$ if $x = x_0 + \epsilon x_1 + \epsilon^2 x_2 + \dots$

$\Rightarrow x_0(0) = a \quad x_n(0) = 0 \quad \forall n \geq 1$

$$\dot{x}(0) = b \quad \frac{dx}{dt} = (1 + \omega_1 \epsilon + \omega_2 \epsilon^2 + \dots) \frac{dx}{d\tau} = (1 + \omega_1 \epsilon + \omega_2 \epsilon^2 + \dots) \left(\frac{dx_0}{d\tau} + \epsilon \frac{dx_1}{d\tau} + \epsilon^2 \frac{dx_2}{d\tau} + \dots \right)$$

$$\Rightarrow \frac{dx_0}{d\tau} + \epsilon \left(\omega_1 \frac{dx_0}{d\tau} + \frac{dx_1}{d\tau} \right) + \epsilon^2 \left(\omega_2 \frac{dx_0}{d\tau} + \omega_1 \frac{dx_1}{d\tau} + \frac{dx_2}{d\tau} \right) + \dots$$

$$= \frac{dx_0}{d\tau} \Big|_{\tau=0} = b \quad \omega_1 \frac{dx_0}{d\tau} + \frac{dx_1}{d\tau} \Big|_0 = 0 \quad \Rightarrow \frac{dx_1(0)}{d\tau} = -\omega_1 b$$

$$\frac{dx_2(0)}{dt} = -w_2 b - w_1(-w_1 b) = (-w_2 + w_1^2) b \dots$$

pt in DE

$$(1 + \epsilon w_1 + \epsilon^2 w_2^2 + \dots)^2 \left(\frac{dx_0}{dt} + \epsilon \frac{dx_1}{dt} + \epsilon^2 \frac{dx_2}{dt} + \epsilon^3 \frac{dx_3}{dt} + \dots \right)$$

$$+ \epsilon \left[(x_0 + \epsilon x_1 + \epsilon^2 x_2 + \epsilon^3 x_3 + \dots)^2 - 1 \right] (1 + w_1 \epsilon + w_2 \epsilon^2 + w_3 \epsilon^3 + \dots) \left(\frac{dx_0}{dt} + \epsilon \frac{dx_1}{dt} + \epsilon^2 \frac{dx_2}{dt} + \dots \right)$$

$$+ x_0 + \epsilon x_1 + \epsilon^2 x_2 + \epsilon^3 x_3 + \dots = 0$$

$$= (1 + \epsilon(w_1) + \epsilon^2(w_2 + w_1^2) + \epsilon^3(w_3 + 2w_1 w_2) + \dots) (x_0'' + \epsilon x_1'' + \epsilon^2 x_2'' + \epsilon^3 x_3'' + \dots)$$

$$+ \epsilon \left[x_0^2 + \epsilon(2x_0 x_1) + \epsilon^2(2x_0 x_2 + x_1^2) + \epsilon^3(2x_0 x_3 + 2x_1 x_2) + \dots - 1 \right]$$

$$\left[x_0' + \epsilon(x_1' + w_1 x_0') + \epsilon^2(\cancel{w_1} w_2 x_0' + w_1 x_1' + x_2') + \epsilon^3(\dots) \right]$$

$$+ x_0 + \epsilon x_1 + \epsilon^2 x_2 + \dots = 0$$

$$x_0'' + \epsilon(x_1'' + 2\omega_1 x_0'') + \epsilon^2((2\omega_2 + \omega_1^2)x_0'' + 2\omega_1 x_1'' + x_2'') + O(\epsilon^3)$$

$$+ \epsilon \left[\begin{array}{c} x_0^2 x_0' \\ -1 \end{array} + \epsilon(2x_1 x_0 x_0' + x_0^2 x_1' + \omega_1 x_0^2 x_0') + O(\epsilon^2) \right]$$

$$+ \sum \epsilon^t x_t = 0.$$

O(1)

$$x_0'' + x_0 = 0$$

$$x_0(\tau) = A \cos(\tau) + B \sin(\tau)$$

$$A = a.$$

$$B = +b.$$

$$x_0(\tau) = a \cos \tau + b \sin \tau. \quad \text{put in.}$$

O(\epsilon)

$$x_1'' + 2\omega_1(-a \cos \tau - b \sin \tau) + (a \cos \tau + b \sin \tau)^2(-a \sin \tau + b \cos \tau) - 1$$

$$+ x_1 = 0.$$

$$x_1'' + x_1 = 2\omega_1 a \cos \tau + 2\omega_1 b \sin \tau + 1$$

$$+ (a \sin \tau - b \cos \tau) (a^2 \cos^2 \tau + 2ab \cos \tau \sin \tau + b^2 \sin^2 \tau)$$

$$= 2\omega_1 a \cos \tau + 2\omega_1 b \sin \tau + 1$$

$$+ a^3 \sin \tau \cos^2 \tau + 2a^2 b \cos \tau \sin^2 \tau + ab^2 \sin^3 \tau - a^2 b \cos^3 \tau$$

$$- 2ab^2 \cos^2 \tau \sin \tau - b^3 \cos \tau \sin^2 \tau.$$

7.6.21

pg 238 Strogatz

$$\ddot{x} + \epsilon(x^2 - 1)\dot{x} + x = 0$$

Poincaré

$$\text{let } x(t) = \sum_{k=0}^{\infty} \epsilon^k x_k(T)$$

$$T = \omega t = (1 + \omega_1 t + \omega_2 t^2 + \dots) t$$

$$dt = \omega dT$$

$$\frac{\partial T}{\partial t} \frac{\partial}{\partial T} = \omega \frac{\partial}{\partial T}$$

$$\text{Then } \ddot{x} = \omega^2 \frac{\partial^2}{\partial T^2}$$

\therefore get

$$(1 + \epsilon \omega_1 + \dots)^2 \sum \epsilon^k \frac{\partial^2 x_k}{\partial T^2}(T) + \epsilon((x_0^2 + 2x_0 x_1 \epsilon + \dots) - 1) = 0$$

$$(1 + \epsilon \omega_1 + \dots) \sum \epsilon^k \frac{\partial^2 x_k}{\partial T^2} + \sum \epsilon^k x_k = 0$$

Then

$$\Rightarrow (1 + 2\epsilon\omega_1 + \epsilon^2\omega_1^2 + \dots) \sum e^{kT} \partial_T^2 x_k + \epsilon (\underline{x_0}^2 + 2x_0 x_1 \epsilon + \dots - 1) = 0$$

$$(1 + \epsilon\omega_1 + \dots) \sum e^{kT} \partial_T^2 x_k + \sum e^{kT} x_k = 0$$

O(1)

$$\partial_T^2 x_0 + x_0 = 0 \Rightarrow x_0 = Ae^{iT} + A^* e^{-iT}$$

O(\epsilon)

$$\partial_T^2 x_1 + 2\omega_1 \partial_T^2 x_0 + x_0^3 + x_1 = 0$$

$$\begin{aligned} \partial_T^2 x_1 + x_1 &= -2\omega_1 [-x_0] - x_0^3 \\ &= 2\omega_1 (Ae^{iT} + A^* e^{-iT}) - (Ae^{iT} + A^* e^{-iT})^3 \end{aligned}$$

just need some terms to compute ω_1

$$\therefore 2\omega_1 A e^{iT} - O(e^{3iT}) + 3A^2 A^* e^{iT} + \text{c.c.}$$

$$\Rightarrow 2\omega_1 A = -3A^2 A^*$$

$$\Rightarrow \omega_1 = -\frac{3|A|^2}{2}$$

7.6.28

$$\ddot{x} + x + \epsilon x^2 = 0 \quad x(0) = a \quad \dot{x}(0) = 0.$$

Poincaré

$$x(t) = \sum \epsilon^k x_k(T) \quad T = \omega t$$

$$= (1 + \omega_1 \epsilon + \omega_2 \epsilon^2 + \dots) t$$

Then

$$\dot{x}(t) = \omega \frac{d}{dT} x(T) = (1 + \omega_1 \epsilon + \omega_2 \epsilon^2 + \dots) \sum \epsilon^k \dot{x}_k(T)$$

$$= \dot{x}_0(T) + \epsilon (\omega_1 \dot{x}_0(T) + \dot{x}_1(T)) + \epsilon^2 (\omega_2 \dot{x}_0(T) + \omega_1 \dot{x}_1(T) + \dot{x}_2(T)) + \dots$$

|
T=0

$$\dot{x}_0(0) = 0$$

$$\dot{x}_1(0) = 0$$

$$\dot{x}_k(0) = 0$$

put in

$$(1 + 2\omega_1 \epsilon + \dots) \sum \epsilon^k x_k''(T) + \sum \epsilon^k x_k$$

$$+ \epsilon (x_0^2 + 2\epsilon x_0 x_1 + \dots) = 0$$

0(1):

$$x_0'' + x_0 = 0 \Rightarrow \omega / \text{I.C.} \quad x_0(T) = a \cos T$$

0(\epsilon)

$$2\omega_1 x_0'' + x_1'' + x_1 + x_0^2 = 0$$

$$\begin{aligned} \circ x_1'' + x_1 &= +2\omega_1(x_0) - x_0^2 \\ &= 2\omega_1 a \cos T - a^2 \left(\frac{1}{2} + \frac{1}{2} \cos 2T \right) \end{aligned}$$

$$\Rightarrow \omega_1 = 0$$

Then
$$x_{1, \text{part}}(t) = -\frac{a^2}{2} - \frac{a^2}{2} \frac{\cos 2T}{(-4+1)}$$
$$= -\frac{a^2}{2} \left[1 + \frac{1}{3} \cos 2T \right]$$

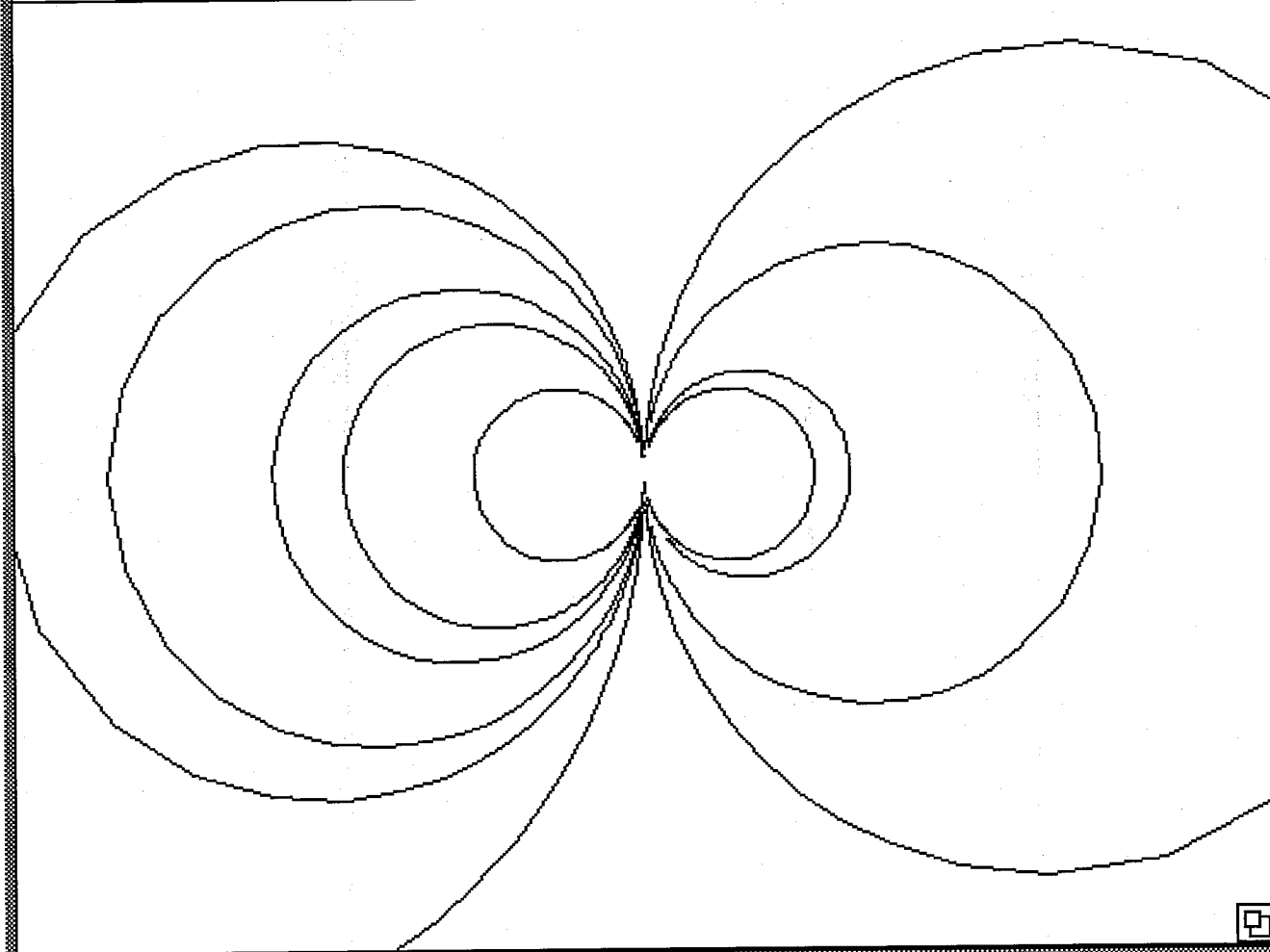
$$x_1(t) = B + -\frac{a^2}{2} \left(\frac{2}{3} \right) = 0 \quad \Rightarrow B = \frac{a^2}{3}$$

$$x_1(t) = \frac{a^2}{3} \cos T - \frac{a^2}{2} + \frac{a^2}{6} \cos 2T$$

Then $O(t^2)$

File Edit Change Tasks Settings Clear

$dx/dt=2*x*y$ $dy/dt=y^2-x^2$



a = 0
b = 0

low x:

-10

high x:

10

low y:

-7.5

high y:

7.5

OK

Cancel



m2-032-11.MIT.EDU:wax

prob6.1.11.ps

Tue Oct 15 23:03:12 1996

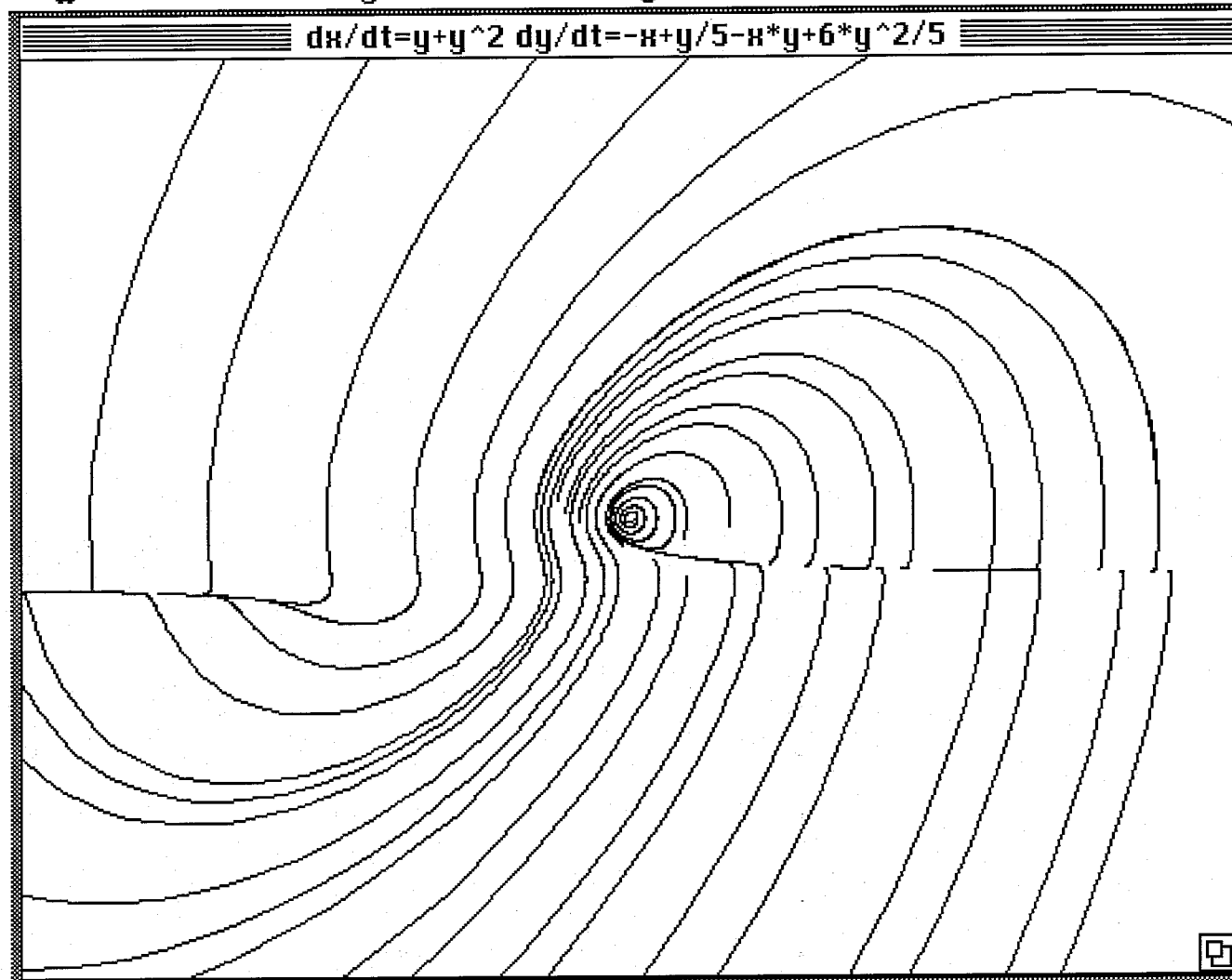
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corfu m2-032-11.MIT.EDU:wax Job: prob6.1.11.ps Date: Tue Oct 15 23:03:12 1996



$$\frac{dx}{dt} = y + y^2 \quad \frac{dy}{dt} = -x + y/5 - x*y + 6*y^2/5$$

a = 0
b = 0

low x:

high x:

low y:

high y:



Pg 243 Skizze

$$abx^2 - x + ab = 0$$

$$x = \frac{1 \pm \sqrt{1 - 4a^2b^2}}{2ab}$$

$$\dot{x} = -ax + y$$

$$\dot{y} = \frac{x^2}{1+x^2} - by$$

$$\dot{x} = 0 \Rightarrow y = ax$$

$$\dot{y} = 0 \Rightarrow y = \frac{1}{b} \frac{x^2}{1+x^2}$$

$$A = \begin{pmatrix} -a & 1 \\ \frac{2x}{1+x^2} - \frac{x^2(2x)}{(1+x^2)^2} & -b \end{pmatrix} = \begin{pmatrix} -a & 1 \\ \frac{2x + 2x^3 - 2x^3}{(1+x^2)^2} & -b \end{pmatrix}$$

$$= \begin{pmatrix} -a & 1 \\ \frac{2x}{(1+x^2)^2} & -b \end{pmatrix}$$

$$\Delta^2 - 4\Delta = a^2 + 2ab + b^2 - 4ab = 0 \Rightarrow (a-b)^2 = 0$$

$$\Delta = ab - \frac{2x^*}{(1+x^{*2})^2} = ab \left[1 - \frac{2x^*}{(1+x^{*2})} \right] = ab \left[\frac{1+x^{*2} - 2}{1+x^{*2}} \right]$$

$$= ab \left[\frac{x^{*2} - 1}{1+x^{*2}} \right]$$

$$\text{As } \Delta = ab - \frac{2x^*}{(1+(x^*)^2)^2} < ab \text{ if } x^* > 1$$

$$\text{Thus } \tau^2 - 4\Delta > (a+b)^2 - 4ab = (a-b)^2 > 0$$

$$\tau = \mu \quad \Delta = -(\mu+2)$$

$$\begin{aligned} \text{If } \Delta < 0 \text{ then saddle } \Rightarrow & -(\mu+2) < 0 \\ & \mu+2 > 0 \\ & \mu > -2 \end{aligned}$$

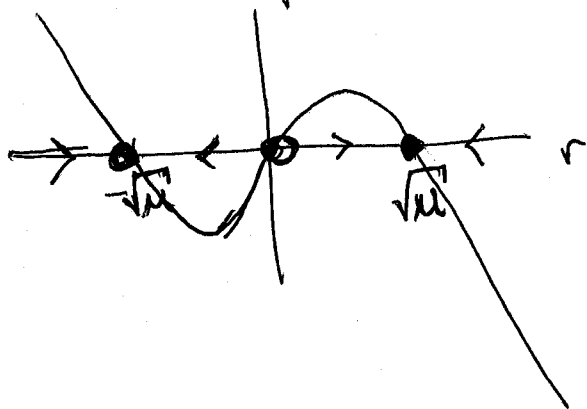
$$\text{If } \mu < -2 \quad \Delta > 0 \quad \text{then } \tau < 0$$

$$\begin{aligned} \tau^2 - 4\Delta &= \mu^2 + 4(\mu+2) = \mu^2 + 4\mu + 4 + 4 = \\ &(\mu+2)^2 + 4 > 0 \quad \text{then stable node} \end{aligned}$$

Pg 250 Strogatz

$r' = \mu r - r^3 = r(\mu - r^2)$ if $\mu < 0$ $\mu - r^2 < 0 \forall r$.
 then $r=0$ is globally stable.

for $\mu > 0$ ~~is stable~~ ~~fixed at the origin~~ $\mu - r^2 = (\sqrt{\mu} - r)(\sqrt{\mu} + r)$



$$\begin{aligned} \dot{x} &= \dot{r} \cos \theta - r \dot{\theta} \sin \theta \\ &= (\mu r - r^3) \cos \theta - r(\omega + br^2) \sin \theta \\ &= (\mu - r^2) r \cos \theta - (\omega + br^2) r \sin \theta \\ &= (\mu - r^2) x - (\omega + br^2) y \\ &= (\mu - x^2 - y^2) x - (\omega + bx^2 + by^2) y \\ &= \mu x - \omega y + \end{aligned}$$

$$\begin{aligned} \dot{y} &= \dot{r} \sin \theta + r \dot{\theta} \cos \theta \\ &= (\mu - r^2) r \sin \theta + (\omega + br^2) r \cos \theta \end{aligned}$$

$$\begin{aligned} \Rightarrow \dot{y} &= (u - r^2)y + (\omega + br^2)x \\ &= (u - (x^2 + y^2))y + (\omega + b(x^2 + y^2))x \\ &= uy + \omega x + \text{cubic terms} \end{aligned}$$

$$A = \begin{pmatrix} u & -\omega \\ \omega & u \end{pmatrix}$$

$$\det(A - \lambda I) = \lambda^2 - 2u\lambda + (u^2 + \omega^2) = 0$$

$$\lambda = \frac{2u \pm \sqrt{4u^2 - 4u^2 - 4\omega^2}}{2} = u \pm \frac{1}{2}\sqrt{-4\omega^2}$$

$$= \text{~~scribble~~} \quad u \pm i\omega$$

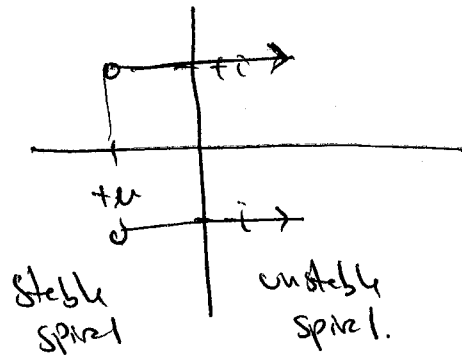
Char eq is:

pg 253 ~~Shogate~~

$$\lambda^2 - 2u\lambda + (u^2 + 1) = 0$$

$$\lambda = \frac{2u \pm \sqrt{4u^2 - 4(u^2 + 1)}}{2} = \frac{2u \pm \sqrt{-4}}{2}$$

$$= u \pm i$$



$$\text{let } x = r \cos \theta$$

$$y = r \sin \theta$$

$$r^2 = x^2 + y^2$$

$$\begin{aligned} 2r\dot{r} &= 2x\dot{x} + 2y\dot{y} \Rightarrow r\dot{r} = x\dot{x} + y\dot{y} \\ &= x(\mu x - y + xy^2) \\ &\quad + y(x + \mu y + y^3) \end{aligned}$$

$$\Rightarrow r\dot{r} = \mu x^2 - xy + x^2 y^2 + xy + \mu y^2 + y^4$$

$$= \mu(x^2 + y^2) + y^2(x^2 + y^2)$$

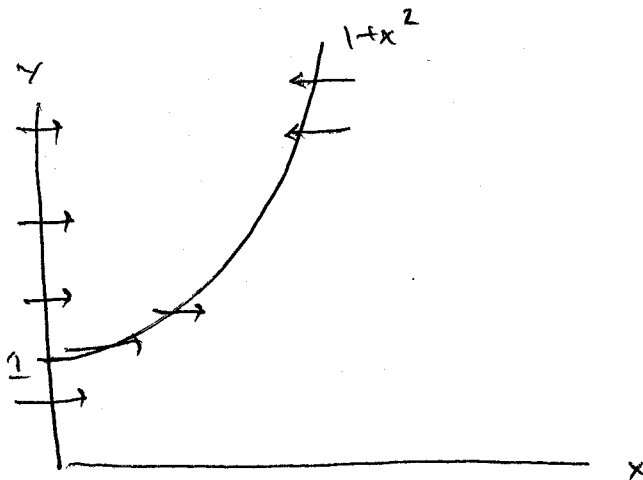
$$= \mu r^2 + r^2 y^2 \Rightarrow \dot{r} = \mu r + r y$$

pg 257 Stages 2

$$\dot{x} = 0$$

$$\Rightarrow x - a = -\frac{4xy}{1+x^2} \Rightarrow \frac{(1+x^2)(a-x)}{4x} = y$$

$$\dot{y} = 0 \Rightarrow x = 0 \text{ or } y = 1+x^2$$



$$\text{or } x = 0 \quad \dot{x} > 0$$

$$\text{or } y = 1+x^2$$

$$\dot{x} = a - x - 4x = a - 5x$$

$$x \text{ large} = \dot{x} < 0$$

$$x \text{ small} = \dot{x} > 0$$

$$\dot{x} = a - x - \frac{4xy}{1+x^2}$$

$$\dot{y} = bx \left(1 - \frac{y}{1+x^2}\right)$$

$$J = \begin{pmatrix} -1 - \frac{4y}{1+x^2} + \frac{8x^2 y}{(1+x^2)^2} & -\frac{4x}{1+x^2} \\ \cancel{bx} & bx \left(\frac{-1}{1+x^2}\right) \\ b\left(1 - \frac{y}{1+x^2}\right) + bx \left(+ \frac{2yx}{(1+x^2)^2}\right) & \end{pmatrix}$$

$$= \frac{1}{1+x^2} \begin{pmatrix} -1-x^2-4y + \frac{8x^2 y}{(1+x^2)^2} & -4x \\ b(1+x^2-y) + \frac{2bx^2 y}{1+x^2} & -bx \end{pmatrix}$$

eqs for eq pts are

$$\frac{4x^* y^*}{1+x^{*2}} = a - x^*$$

$$y^* = 1 + x^{*2}$$

$$J_{x^*, y^*} = \frac{1}{1+x^{*2}} \begin{pmatrix} -5y^* + \frac{8x^{*2}}{1+x^{*2}} & -4x^* \\ 2bx^{*2} & -bx^* \end{pmatrix}$$

$$= \frac{1}{1+x^{*2}} \begin{pmatrix} -5 + 3x^{*2} & -4x^{*} \\ 2bx^{*2} & -bx^{*} \end{pmatrix}$$

$$\Delta = \frac{5bx^{*} - 3bx^{*3} + 8bx^{*3}}{(1+x^{*2})^2} = \frac{5bx^{*} + 5bx^{*3}}{(1+x^{*2})^2}$$

$$= \frac{5bx^{*}}{1+x^{*2}}$$

$$\tau = \frac{-5 - bx^{*} + 3x^{*2}}{1+x^{*2}}$$

For $\tau > 0$

$$\Rightarrow -5 - bx^{*} + 3x^{*2} > 0$$

$$\Rightarrow -5 - b\frac{a}{5} + \frac{3a^2}{25} > 0$$

$$\Rightarrow \frac{ab}{5} < \frac{3a^2}{25} - 5$$

$$b < \frac{3a}{5} - \frac{25}{a}$$

Pg 260 Slogetz

$$\Delta = \frac{5\left(\frac{3a}{5} - \frac{25}{a}\right)\left(\frac{a}{5}\right)}{1 + \left(\frac{a}{5}\right)^2} = \frac{a(3a^2 - 5 \cdot 25)}{5a\left(1 + \left(\frac{a}{5}\right)^2\right)}$$

$$\frac{5(3a^2 - s - s^2)}{s^2 + a^2} = \frac{15a^2 - s^4}{a^2 + s^2}$$

pg 261 Strogatz

$$\dot{r} = \mu r + r^3 - r^5 \quad \text{if } \mu < 0$$

$$= r(\mu - r^2 - r^4)$$

Zeros of $r^4 + r^2 - \mu = 0$

$$r^2 = \frac{-1 \pm \sqrt{1+4\mu}}{2}$$

Has 2 real solutions if

$$1+4\mu > 0$$

$$\Rightarrow 4\mu > -1$$

$$\mu > -\frac{1}{4}$$

Thus if $\mu < -\frac{1}{4}$ ~~has~~ has no real solution.

Can't take Taylor series about $\mu = -\frac{1}{4}$ as not analytic there.

$$\left\{ \begin{array}{l} -\frac{1}{2} \pm \frac{1}{2} \sqrt{1+4\mu} \end{array} \right. \quad \text{let } \mu = -\frac{1}{4} +$$

$$\underbrace{\mu > -\frac{1}{4}}$$

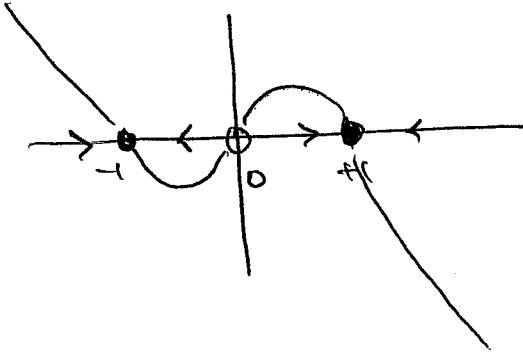
$$\left\{ \begin{array}{l} -\frac{1}{2} \pm \frac{1}{2} \sqrt{1+4(\mu + \frac{1}{4} - \frac{1}{4})} \end{array} \right.$$

$$= -\frac{1}{2} \pm \frac{1}{2} \sqrt{4(\mu + \frac{1}{4})} = -\frac{1}{2} \pm \sqrt{\mu + \frac{1}{4}}$$

$$r = -\frac{1}{2} \pm$$

Pg 262 Strogatz

$$\dot{r} = r(1-r^2) = r(1-r)(1+r)$$



$$\theta = \frac{\pi}{2} \quad \sin \theta = 1$$

Pg 264 Strogatz

$$\ddot{x} + x + \epsilon x \dot{x}^2 - \epsilon \dot{x} = 0$$

$$\text{let } v^2 = \epsilon x^2 \Rightarrow v = \sqrt{\epsilon} x \Rightarrow x = \frac{v}{\sqrt{\epsilon}}$$

$$\textcircled{B} \frac{\ddot{v}}{\sqrt{\epsilon}} + \frac{v}{\sqrt{\epsilon}} + v^2 \frac{\dot{v}}{\sqrt{\epsilon}} - \epsilon \frac{\dot{v}}{\sqrt{\epsilon}} = 0$$

~~Pg 2~~

Pg 266 Skizze

$$\tilde{t} = \left(\frac{2eI_c}{\hbar c} \right)^{1/2} t$$

$$I = I_B / I_c \quad \alpha = \frac{\hbar}{2eR}$$

$$\frac{\hbar}{2e} \phi'' + \frac{1}{\left(\frac{2eI_c}{\hbar c} \right)^{-1}} \phi' + \frac{\hbar}{2eR} \left(\frac{2eI_c}{\hbar c} \right)^{1/2} \phi + I_c \sin \phi$$

$$= I_B$$

$$\Rightarrow I_c \phi'' + \frac{\hbar}{2eR} \frac{1}{\left(\frac{\hbar c}{2eI_c} \right)^{1/2}} \phi' + I_c \sin \phi = I_B$$

$$\Rightarrow I_c \phi'' + \frac{\hbar}{2eR} \frac{(2eI_c)^{1/2}}{(\hbar c)^{1/2}} \phi' + I_c \sin \phi = I_B$$

$$\Rightarrow I_c \phi'' + \frac{I_c^{1/2} \hbar}{\sqrt{2} \sqrt{e} R \sqrt{e}} \phi' + I_c \sin \phi = I_B$$

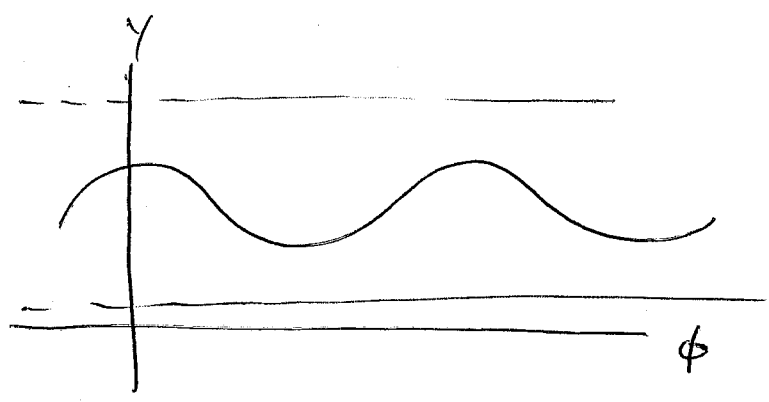
$$\phi'' + \underbrace{\frac{\sqrt{\hbar}}{\sqrt{2} I_c^{1/2} \sqrt{e} R \sqrt{e}}}_{\alpha} \phi' + \sin \phi = I$$

$$J = \begin{pmatrix} 0 & 1 \\ \cos \phi^* & -\alpha \end{pmatrix}$$

$$\tau = -\alpha, \quad \Delta = \cos \phi^* = \pm \sqrt{1 - I^2}$$

$$\Delta > 0$$

$$\tau^2 - 4\Delta = \alpha^2 - 4\sqrt{1 - I^2} = \frac{h}{2eI_c R^2 C} - 4\sqrt{1 - \frac{I_0^2}{I_c^2}}$$



$$\text{If } y > \alpha^{-1}(I - \sin \phi)$$

~~$$I - \sin \phi - \alpha y < 0$$~~
$$I - \sin \phi - \alpha y < 0 \quad \text{flow down and}$$

$$\text{If } y < \alpha^{-1}(I - \sin \phi) \Rightarrow \quad \quad \quad > 0$$

~~$$y_1 < \alpha^{-1}(I - \sin \alpha) < \alpha^{-1}(I - 1)$$~~

~~$$y_2 > \alpha^{-1}(I - \sin \alpha)$$~~

Pg 269 Shogetz

1

Is (5) the energy for (3) or (4)?

Is E conserved along trajectory

$$\begin{aligned}\dot{E} &= \gamma \dot{\gamma} + \sin \phi \dot{\phi} = \gamma (I - \sin \phi - \alpha \gamma) + \sin \phi \gamma \\ &= I \gamma - \alpha \gamma^2 \neq 0\end{aligned}$$

~~~~~~~~~

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Pg 277 Shogetz

$$\omega^* = \frac{\omega_2(k_1 + k_2) + k_2(\omega_2 - \omega_1)}{k_1 + k_2} = \frac{k_1 \omega_2 + \omega_1 k_2}{k_1 + k_2}$$

$$\Delta \omega_2 = \omega_2 - \omega^* = \frac{\omega_2(k_1 + k_2) - k_1 \omega_2 - k_2 \omega_1}{k_1 + k_2} = \frac{k_2(\omega_2 - \omega_1)}{k_1 + k_2}$$

$$\begin{aligned}\Delta \omega_1 &= \omega_1 - \omega^* = \frac{\omega_1 k_1 + \omega_2 k_2 - k_1 \omega_2 - k_2 \omega_1}{k_1 + k_2} \\ &= \frac{k_1(\omega_1 - \omega_2)}{k_1 + k_2}\end{aligned}$$



2

$$\text{Then } \left| \frac{\Delta w_1}{\Delta w_2} \right| = \left| \frac{f_1}{f_2} \right|$$

Pg 283 Stogolz

$$\phi_i(t) = \phi^*(t) + \eta_i(t)$$

$$\dot{\phi}_i = \Omega + a \sin \phi_i + \frac{1}{N} \sum_{j=1}^N \sin \phi_j$$

Then eq is:

$$\dot{\phi}^*(t) + \dot{\eta}_i(t) = \Omega + a \sin(\phi^* + \eta_i) + \frac{1}{N} \sum_{j=1}^N \sin(\phi^* + \eta_j)$$

$$\Rightarrow \dot{\phi}^*(t) + \dot{\eta}_i = \Omega + a \sin \phi^* + a \cos \phi^* \eta_i + O(\eta_i^2)$$

$$+ \frac{1}{N} \sum_{j=1}^N (\sin \phi^* + \cos \phi^* \eta_j + O(\eta_j^2))$$

$$\Rightarrow \cancel{\dot{\phi}^*} + \dot{\eta}_i = \cancel{\Omega} + \cancel{a \sin \phi^*} + (a+1) \sin \phi^* + [a \cos \phi^*] \eta_i + \frac{\cos \phi^*}{N} \sum_{j=1}^N \eta_j$$

$$\Rightarrow \dot{\eta}_i = (a \cos \phi^*) \eta_i + \cos \phi^* \frac{1}{N} \sum_{j=1}^N \eta_j$$

$$\text{let } \mu = \frac{1}{N} \sum_{j=1}^N \eta_j$$

$$r_i = r_{i+1} - r_i$$

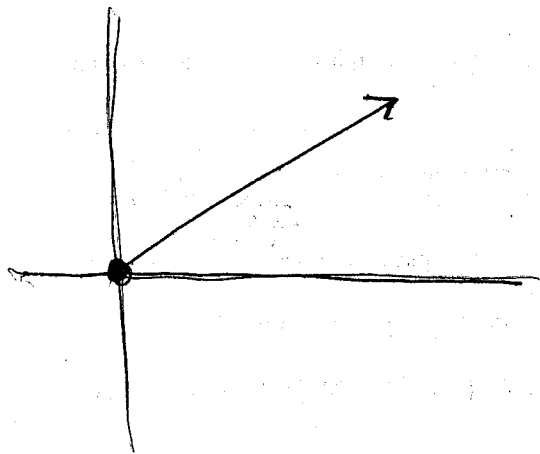
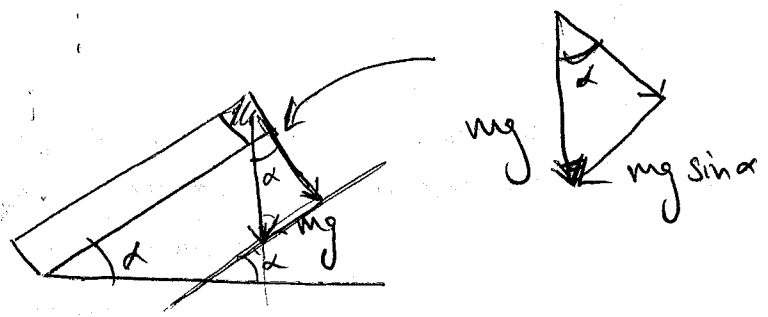
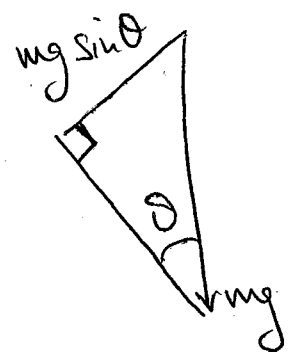
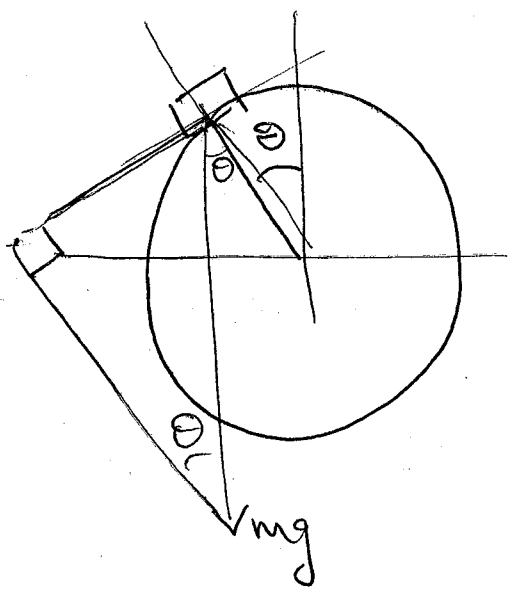
$$\dot{r}_i = \dot{r}_{i+1} - \dot{r}_i = (a \cos \phi^*) \dot{\phi}^* r_i$$

$$\frac{d r_i}{r_i} = \frac{a \cos \phi^* d\phi^*}{Q + (a+1) \sin \phi^*}$$

$$\oint \frac{d r_i}{r_i} = \int_0^{2\pi}$$

$$\ln \frac{r_i(T)}{r_i(0)} =$$

pg 307 Shoggett



eq (2)  $\frac{\partial m}{\partial t} = Q - km - w \frac{\partial m}{\partial \theta}$

$$\Rightarrow \sum_{n=0}^{\infty} \dot{a}_n(t) \sin(n\theta) + \dot{b}_n \cos(n\theta) = -w \sum_{n=0}^{\infty} a_n \cos n\theta - b_n n \sin n\theta + \sum_{n=0}^{\infty} q_n \cos n\theta - k \sum$$

$$\Rightarrow \cancel{a_n = \omega b_n - k b_n}$$

$$a_n = \omega b_n - k a_n$$

$$b_n = -\omega a_n + q_n - k b_n$$

Pg 309 Strogozet

$$a_1 = \frac{\omega b_1}{k}$$

$$\omega a_1 = -k b_1 + q_1$$

$$a_1 = \frac{\omega \omega}{\pi g r}$$

$$\left. \begin{array}{l} \\ \\ \end{array} \right\} \Rightarrow$$

$$\omega^2 \frac{b_1}{k} = -k b_1 + q_1$$

$$\omega^2 b_1 = -k^2 b_1 + k q_1$$

$$(\omega^2 + k^2) b_1 = k q_1$$

$$b_1 = \frac{k q_1}{\omega^2 + k^2}$$

$$\omega \left( \frac{b_1}{k} - \frac{\omega}{\pi g r} \right) = 0$$

$$b_1 = \frac{k \omega}{\pi g r}$$

pg 312 Strogatz

$$(x, y) \rightarrow (-x, -y)$$

$$-\dot{x} = b(-y+x) \Rightarrow \dot{x} = b(y-x)$$

$$-\dot{y} = -rx + y + xz \Rightarrow \dot{y} = rx - y - xz$$

$$\dot{z} = xy - bz$$

$$\begin{aligned} \nabla f &= \frac{\partial}{\partial x} (b(y-x)) + \frac{\partial}{\partial y} (rx - y - xz) + \frac{\partial}{\partial z} (xy - bz) \\ &= -b + -1 - b \end{aligned}$$

$$\vec{v} = (-b - 1 - b)\vec{v}$$

pg 314 Strogatz

$$\dot{x} = 0 \Rightarrow y = x$$

put into 2 eqs below

$$\dot{y} = 0 \Rightarrow rx - y - xz = 0$$

$$\dot{z} = 0 \Rightarrow xy = bz$$

$$rx - x - xz = 0 \Rightarrow x(r-1-z) = 0 \Rightarrow x = 0$$

$$x^2 = bz$$

$$\text{or } z = r-1$$

$$\text{If } x > 0 \quad z = 0 \Rightarrow (0, 0, 0) \text{ vs. } (\pm\sqrt{b(r-1)}, \pm\sqrt{b(r-1)}, r-1)$$

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} -b & b \\ r & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\Delta = b - rb = b(1-r)$$

$$\begin{aligned} \tau^2 - 4\Delta &= (b+1)^2 - 4b(1-r) = b^2 + 2b + 1 - 4b + 4br \\ &= b - 2b + 1 + 4br = (b-1)^2 + 4br > 0 \end{aligned}$$


---

$$\frac{1}{2} \dot{v}^0 = - \frac{2 - (r+1)xy + yz}{x - (r+1)xy + yz}$$

$$= -(x^2 - (r+1)xy) - y^2 - bz^2$$

$$= -\left(x^2 - (r+1)xy + \left(\frac{r+1}{2}\right)^2 y^2\right) + \left(\frac{r+1}{2}\right)^2 y^2 - y^2 - bz^2$$

$$= \cancel{\text{xxxx}} - \left(x - \left(\frac{r+1}{2}\right)y\right)^2 + \left[1 - \left(\frac{r+1}{2}\right)^2\right] y^2 - bz^2$$

$$\text{If } 0 < r < 1$$

$$1 < r+1 < 2$$

$$\frac{1}{2} < \frac{r+1}{2} < 1$$

$$\text{Then } \frac{1}{4} < \left(\frac{r+1}{2}\right)^2 < 1$$

$$-1 < -\left(\frac{r+1}{2}\right)^2 < -\frac{1}{4}$$

$$0 < 1 - \left(\frac{r+1}{2}\right)^2 < \frac{3}{4}$$

$$\dot{v} = B(r-u)$$

$$\dot{v} = ru - v - 2\omega uv$$

$$\dot{w} =$$

$$\vec{e} = \mathcal{I} - \vec{r} = (u - v_r, v - v_r, w - w_r)$$

$$\dot{e}_1 = ~~r\dot{e}_1~~ - B(r-u) -$$

$$= B(e_2 - e_1)$$

$$\dot{e}_2 = r\dot{e}_1 - e_2 - 2\omega uv + 2\omega v \frac{d}{dt} w_r$$

$$= r\dot{e}_1 - e_2 - 2\omega v(e_3)$$

$$\dot{e}_3 = \delta uv - \delta uv_r - be_3 = \delta v(e_2) - be_3$$

$$\text{If } r_n = r^n$$

$$\frac{r_n - r_{n-1}}{r_{n+1} - r_n} = \frac{r^n(r-1)}{r^{n+1}(r-1)} = \frac{r^{n-1}}{r^n} = \frac{1}{r}$$

$$\therefore \lim_{n \rightarrow \infty} \frac{r_n - r_{n-1}}{r_{n+1} - r_n} = \delta$$

or dropping the limit

$$r_n - r_{n-1} = \delta(r_{n+1} - r_n)$$

$$0 = \delta r_{n+1} - (1+\delta)r_n + r_{n-1} \quad \text{constant coeff diff. eq.}$$

$$0 = \delta \lambda^2 - (1+\delta)\lambda + 1$$

$$\lambda = \frac{(1+\delta) \pm \sqrt{(1+\delta)^2 - 4\delta}}{2\delta} = \frac{1+\delta \pm \sqrt{1+2\delta+\delta^2-4\delta}}{2\delta}$$

$$= \frac{1+\delta \pm \sqrt{1-2\delta+\delta^2}}{2\delta} = \frac{1+\delta \pm (1-\delta)}{2\delta}$$

$$= 0, \quad \frac{2-2\delta}{2\delta} = \frac{1}{\delta} - 1$$



pg 358 Satz 2

$$x^* = 1 - \frac{1}{r} \text{ is stable if } f'(x^*) = \frac{\cancel{r} \cdot \cancel{(1-x^*)}}{r(1-2x^*)}$$

$$= r \left( \frac{\cancel{1-x^*}}{\cancel{r}} \right) = \frac{\cancel{1-x^*}}{\cancel{r}} \Rightarrow = r(1-2+\frac{2}{r})$$

$$= r(-1+\frac{2}{r})$$

$$= -r+2$$

$$|f'(x^*)| < 1$$

$$\Rightarrow |1 - \frac{1}{r}| < 1$$

$$-1 < 1 - \frac{1}{r} < 1$$

$$-2 < -\frac{1}{r} < 0$$

$$0 < \frac{1}{r} < 2$$

$$\frac{1}{2} < r < \infty$$

$x^*$  is stable if

$$|f'(x^*)| < 1$$

$$\Rightarrow -1 < 2-r < 1$$

$$-3 < -r < -1$$

$$1 < r < 3$$

$$\textcircled{B} \quad r=3$$

$$p \cdot q = \frac{r+1}{2r} = \frac{1}{2} + \frac{1}{2r} = \frac{1}{2} + \frac{1}{2 \cdot 3} = \frac{3+1}{6} = \frac{4}{6} = \frac{2}{3}$$

$$= \frac{4}{2 \cdot 3} = \frac{2}{3}$$

$$f(x) = rx(1-x)$$

$$\textcircled{B} \quad f'(x) = r(1-x) + rx(-1) = r - rx - rx = r(1-2x)$$

Then

$$\begin{aligned} \Delta &= f(p)f(q) = r^2(1-2p)(1-2q) \\ &= r^2(1-2(p+q)+4pq) \end{aligned}$$

But from pg 359 
$$p, q = \frac{r+1 \pm \sqrt{(r-3)(r+1)}}{2r}$$

Thus 
$$p+q = \frac{r+1}{2r} + \frac{r+1}{2r} = \frac{r+1}{r}$$

$$\begin{aligned} p \cdot q &= \frac{1}{4r^2} \left( (r+1)^2 - (r-3)(r+1) \right) \\ &= \frac{1}{4r^2} \left( \cancel{r^2} + 2r + 1 - \cancel{r^2} - r + 3r + 3 \right) \end{aligned}$$

$$p \cdot q = \frac{1}{4r^2} (4r+4) = \frac{r+1}{r^2}$$

$$\begin{aligned} \text{Then } \Delta &= r^2 \left[ 1 - 2\left(\frac{r+1}{r}\right) + 4\left(\frac{r+1}{r^2}\right) \right] \\ &= r^2 - 2r(r+1) + 4(r+1) \\ &= r^2 - 2r^2 - 2r + 4r + 4 \\ &= 4 + 2r - r^2 \end{aligned}$$

This 2 cycle stable iff  $|\Delta| < 1$

$$\Rightarrow \underbrace{|4 + 2r - r^2|} < 1$$

$$-1 < 4 + 2r - r^2 < 1$$

$$0 < 5 + 2r - r^2$$

$$\begin{aligned} \Rightarrow r &= \frac{-2 \pm \sqrt{4 - 4(-1)(5)}}{2(-1)} \\ &= \frac{-2 \pm \sqrt{4 + 20}}{-2} \\ &= \frac{2 \pm \sqrt{24}}{2} = 1 \pm \sqrt{6} \end{aligned}$$

$$0 < (r - (1 - \sqrt{6})) (r + (1 - \sqrt{6}))$$

$$\underbrace{3 + 2r - r^2} < 0$$

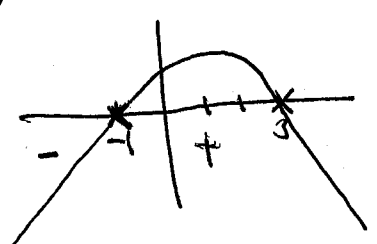
$$(3 - r)(1 + r) < 0$$

$$r = 3 \quad r = -1$$

$$\Rightarrow -1 < r < 3$$

Thus this is true for

$$r \in (-\infty, -1) \cup (3, \infty)$$



$$|4 + 2r - r^2| < 1$$

$$-1 < 4 + 2r - r^2 < 1$$

Solve 1st  $-1 < 4 + 2r - r^2$

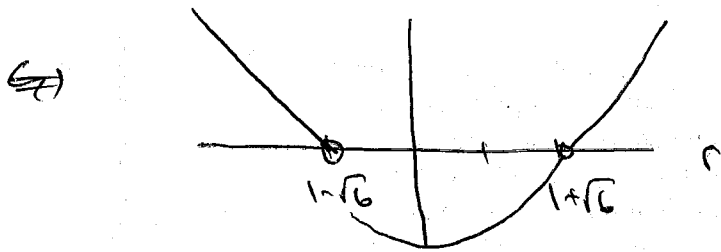
$$\Leftrightarrow r^2 - 2r - 5 < 0$$

Zeros:

$$r = \frac{2 \pm \sqrt{4 - 4(-5)}}{2} = \frac{2 \pm 2\sqrt{1+5}}{2} = 1 \pm \sqrt{6}$$

$$\Leftrightarrow (r - (1 + \sqrt{6}))(r - (1 - \sqrt{6})) < 0$$

$r^2 - 2r - 5$



Thus  $\Rightarrow$

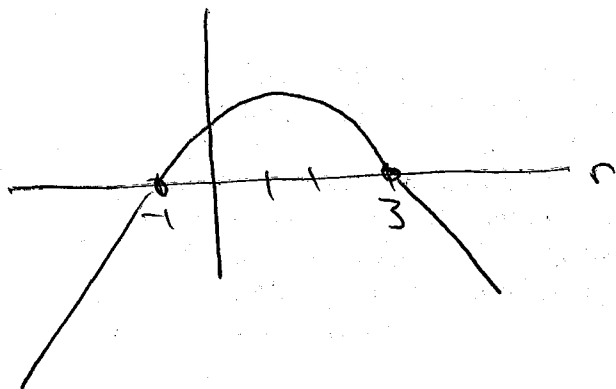
$$1 - \sqrt{6} < r < 1 + \sqrt{6} \approx 3.449$$

Solve next:

$$4 + 2r - r^2 < 1$$

$$\Leftrightarrow 3 + 2r - r^2 < 0$$

$$\Leftrightarrow (3 - r)(1 + r) < 0$$



Thus  $\Rightarrow r < -1$  or  $r > 3$

combining these ranges w/  $r > 0 \Rightarrow$

$$3 < r < 3.449 = 1 + \sqrt{6}$$

pg 370 Strogatz

$$f(x) = r \sin \pi x$$

$$f'(x) = \pi r \cos \pi x = 0$$

$$\pi x = \frac{\pi}{2} \Rightarrow x = \frac{1}{2}$$

$$\text{Then } f(\frac{1}{2}) = r$$

$$f(x) = rx(1-x)$$

$$f'(x) = r(1-2x) = 0$$

$$\Rightarrow x = \frac{1}{2}$$

$$f(\frac{1}{2}) = r \frac{1}{2} (\frac{1}{2}) = \frac{r}{4}$$

Thus  $r \sin \pi x$ 's maximum is 4x's as large as the maximum of  $rx(1-x)$ 's the ~~logistic's~~ logistic's.

Why does the x-axis ~~of~~ of  $r \sin \pi x$  scale by  $\frac{1}{4}$  of that of the logistic's map?

pg 380 Strogatz

$$\Delta = (4) pq = 0 \quad p=0 \text{ or } q=0$$

$$f^2(x, R_1) = \left( \frac{R_1 - x^2}{R_1 - x^2} \right) (R_1 - x^2)(R_1 - x^2) = p \text{ or } q$$

$$= R_1 - (R_1 - x^2)^2$$

$x=p \text{ or } q$

i.e.  $p$  &  $q$  are both fixed pts for the ~~end~~ map  $f^2(x)$

pt the one that is 0.

$$0 = R_1 - R_1^2 \rightarrow R_1 = 0; R_1 = 1 \text{ if } R_1 = 0$$

Then  $q = f(p, R_1) = 0$  &  $q$  is also 0 (if  $p$  is)

Thus we must pick  $R_1 = 1$ .

Note that for  $f = 5 - x^2$   
 $f' = -2x = 0 \Rightarrow x = 0 \downarrow f_{max} = 5$ .

$f^3(x, R_1) =$

~~$f(x, R_0) \approx \alpha^2 f$~~

$f^2(x, R_1) \approx \alpha f^4\left(\frac{x}{\alpha^2}, R_2\right)$

$\downarrow f(x, R_0) \approx \alpha f^2\left(\frac{x}{\alpha}, R_1\right)$

$\Rightarrow f(x, R_0) \approx \alpha^2 f^4\left(\frac{x}{\alpha^2}, R_2\right)$

From  $g_n(x) = \lim_{n \rightarrow \infty} \alpha^n f^{(2^n)}\left(\frac{x}{\alpha^n}, R_{n+1}\right)$

$g_\infty(x) = \lim_{n \rightarrow \infty}$

$$x=0$$

$$g(0) = \alpha g^2(0)$$

||

$$1 = \alpha g(1) \Rightarrow \alpha =$$

$$x \Rightarrow x/\alpha \quad \text{let } v = x/\alpha \Rightarrow x = \alpha v \quad v = \alpha x$$

$$\alpha v_{n+1} = -(1+\mu)\alpha v_n + a\alpha^2 v_n^2 + O(v_n^3)$$

$$v_{n+1} = -(1+\mu)v_n + a v_n^2 + O(v_n^3) \quad \text{pick } \alpha = 1/a$$

$$p = -(1+\mu)p + q^2$$

$$q = -(1+\mu)q + p^2$$

$$\text{sb } (p-q) = -(1+\mu)(q-p) + q^2 - p^2$$

$$1 = +(1+\mu) + -(q+p)$$

$$q+p = \mu$$

\* Note we are just using the result that the sum of two roots equals the value of  $c$  in a quadratic & the product equals the value of  $b$  in a quadratic.



Multiply,

$$pq = + (1+\mu)^2 pq - q^2 (1+\mu) - p^2 (1+\mu) + (pq)^2$$

$$0 = 2\mu pq + \mu^2 pq - pq(1+\mu)(\underbrace{p+q}_\mu) + p^2 q^2$$

$$0 = \underbrace{\mu(\mu+2) pq - pq(1+\mu)(\mu)} + p^2 q^2$$

$$0 = \mu pq + (pq)^2$$

$$\Rightarrow pq = -\mu$$

$$p = -\frac{\mu}{q}$$

$$p + \frac{\mu}{p} = \mu$$

$$p^2 - \mu p - \mu = 0 \quad p = \frac{\mu \pm \sqrt{\mu^2 - 4(-\mu)}}{2}$$
$$= \frac{\mu \pm \sqrt{\mu^2 + 4\mu}}{2} =$$

$$\text{Thus } p = \frac{\mu + \sqrt{\mu^2 + 4\mu}}{2} \quad q = \frac{\mu - \sqrt{\mu^2 + 4\mu}}{2}$$

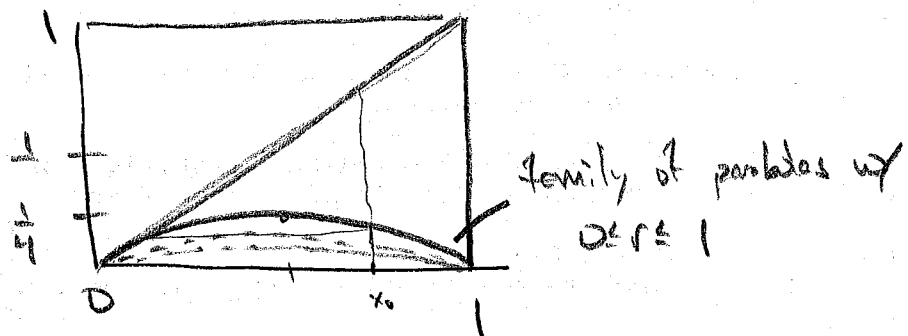
Ex 10.2.2

Logistic map:

$$x_{n+1} = rx_n(1-x_n) \quad \text{then if } 0 \leq r \leq 1$$

 $x^* = 0$  is globally stable

 Max of  $rx_n(1-x_n)$  for  $x_0 \in [0, 1]$  is at  $x = 1/2$ 

 Max value of  $1/4$ 

 Claim:  $x + rx(1-x)$  intersect at only  $x=0$ 

$$x=0 \text{ is one solution } \text{ \& so is } 1 = r(1-x_2)$$

$$-\left(\frac{1}{r} - 1\right) = x_2$$

$$\Rightarrow x_2 = 1 - \frac{1}{r}$$

 But  $1 - \frac{1}{r}$  is  $-\infty < 1 - \frac{1}{r} < 0$ .

Check.

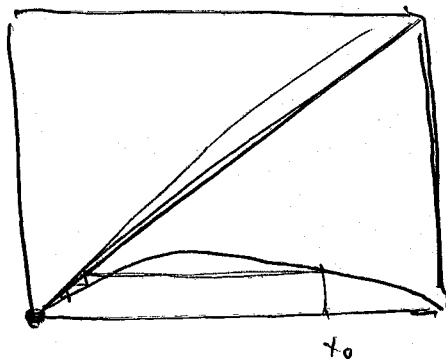
$$0 \leq r \leq 1$$

$$1 < \frac{1}{r} < \infty$$

$$-\infty < -\frac{1}{r} < -1$$

$$-\infty < 1 - \frac{1}{r} < 0. \quad \checkmark$$

Thus the plot shown up looks like



→ All trajectories lead to the fixed pt  $x^* = 0$ .

(10.7.3)

$g(x) +$

$\int$   ~~$g(x)$~~   $u g^2\left(\frac{x}{u}\right) = g(x)$

$u g(x/u)$  is also a solution

~~$u g\left(\frac{x}{u}\right)$~~  Now  $u g\left(\frac{x}{u}\right) \overset{\text{change}}{=} u g\left(\frac{x}{u}\right)$

$$= u g\left(\frac{1}{u} u g\left(\frac{x}{u}\right)\right) = u g^2\left(\frac{x}{u}\right) = g(x)$$

From \*  $\therefore u g(x/u)$  is also a solution

QED

(x, y)

Pg 430 Stages 2

$$T^1: x^1 = x, y^1 = 1 + y - ax^2$$

$$T^2: x^2 = bx^1, y^2 = y^1$$

$$\Rightarrow x^2 = bx, y^2 = 1 + y - ax^2$$

$$T^3: x^3 = y^2, y^3 = x^2$$

$$\Rightarrow x^3 = 1 + y - ax^2, y^3 = bx$$

Pg 431 Stages 2

$$x_{n+1} = y_n + 1 - ax_n^2$$

$$y_{n+1} = bx_n$$

$$x_{n+1} - 1 + ax_n^2 = y_n$$

$$x_n = \frac{y_{n+1}}{b}$$

$$y_n = x_{n+1} - 1 + \frac{a}{b^2} y_{n+1}^2$$

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Pg 432 Stages 2

$$x_{n+1} = 1 - ax_n^2 + y_n$$

$$y_{n+1} = bx_n$$

$$\frac{\partial(x_{n+1}, y_{n+1})}{\partial(x_n, y_n)} = \begin{pmatrix} -2x_n a & 1 \\ b & 0 \end{pmatrix}$$

$$\therefore \left| \frac{\partial(x_{n+1}, y_{n+1})}{\partial(x_n, y_n)} \right| = -b$$

$$\det d \frac{\partial(x_{n+1}, y_{n+1})}{\partial(x_n, y_n)} = -b$$