

$$\lim_{h \rightarrow 0} \frac{1}{h} \left\{ \int_{W(t+h)} \phi(\tilde{\gamma}, t+h) d(y_1, y_2, y_3) - \int_{W(t)} \phi(x, y, z, t) d(x, y, z) \right\}$$

$$= \lim_{h \rightarrow 0} \frac{1}{h} \left\{ \int_{W(t)} \phi(x+h u(x, t) + o(h), t+h) (1+h \nabla \phi \cdot u + o(h)) d(x, y, z) \right.$$

$$\left. - \int_{W(t)} \phi(x, y, z, t) d(x, y, z) \right\}$$

taylor expand $\phi(\dots)$
about h

$$= \lim_{h \rightarrow 0} \frac{1}{h} \left\{ \int_{W(t)} [\phi(\vec{x}, t) + \phi_t h + \nabla \phi \cdot \vec{u} h + o(h)] (1+h \nabla \phi \cdot \vec{u} + o(h)) d\vec{x} \right.$$

$$\left. - \int_{W(t)} \phi(x, y, z, t) d(x, y, z) \right\}$$

$$= \lim_{h \rightarrow 0} \frac{1}{h} \left\{ \int_{W(t)} (\cancel{\phi} + \phi_t h + \nabla \phi \cdot \vec{u} h + \cancel{\phi} \nabla \phi \cdot \vec{u} h - \cancel{\phi}) d(x, y, z) \right\}$$

$$= \lim_{h \rightarrow 0} = \int_{W(t)} (\phi_t + \nabla \phi \cdot \vec{u} + \phi \nabla \phi \cdot \vec{u}) d(x, y, z)$$

eq 1.2 ✓

let eq 1.8

~~1.8~~

$$\frac{\partial \vec{q}}{\partial t} + \frac{1}{\rho} (\vec{q} \cdot \nabla) \vec{q} + \nabla \left(\frac{1}{\rho} \vec{q} \right) \cdot \vec{q} + \nabla p = \vec{F}$$

x component:

$$\frac{\partial q_1}{\partial t} + \frac{1}{\rho} \left(q_1 \frac{\partial q_1}{\partial x} + q_2 \frac{\partial q_1}{\partial y} + q_3 \frac{\partial q_1}{\partial z} \right) + \left(\frac{\partial}{\partial x} \left(\frac{1}{\rho} q_1 \right) + \frac{\partial}{\partial y} \left(\frac{1}{\rho} q_2 \right) + \frac{\partial}{\partial z} \left(\frac{1}{\rho} q_3 \right) \right) q_1 + \frac{\partial p}{\partial x} = 0$$

$$= \frac{\partial q_1}{\partial t} + \frac{1}{\rho} q_1 \frac{\partial q_1}{\partial x} + \frac{\partial}{\partial x} \left(\frac{1}{\rho} q_1 \right) q_1 + \frac{1}{\rho} q_2 \frac{\partial q_1}{\partial y} + q_1 \frac{\partial}{\partial y} \left(\frac{1}{\rho} q_2 \right) + \frac{1}{\rho} q_3 \frac{\partial q_1}{\partial z} + q_1 \frac{\partial}{\partial z} \left(\frac{1}{\rho} q_3 \right) + \frac{\partial p}{\partial x} = 0$$

$$\Rightarrow \frac{\partial q_1}{\partial t} + \frac{\partial}{\partial x} \left(\frac{1}{\rho} q_1 \cdot q_1 \right) + \frac{\partial}{\partial y} \left(\frac{1}{\rho} q_1 q_2 \right) + \frac{\partial}{\partial z} \left(\frac{1}{\rho} q_1 q_3 \right) + \frac{\partial p}{\partial x} = 0$$

$$\Rightarrow \frac{\partial q_1}{\partial t} + \frac{\partial}{\partial x} \left(\frac{1}{\rho} q_1 q_1 + p \right) + \frac{\partial}{\partial y} \left(\frac{1}{\rho} q_1 q_2 \right) + \frac{\partial}{\partial z} \left(\frac{1}{\rho} q_1 q_3 \right) = 0 \quad \checkmark$$

$$\left(1 - \left(\frac{u}{c}\right)^2\right) \frac{\partial u}{\partial x} + \left(1 - \left(\frac{v}{c}\right)^2\right) \frac{\partial v}{\partial y} - \frac{uv}{c^2} \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}\right) = 0 \quad \text{eq 1.55}$$

Assum

$$u = u(x, y)$$

$$v = v(x, y)$$

can be inverted them

$$0 = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix} \neq 0$$

$$du = \frac{\partial u}{\partial x} dx + \frac{\partial u}{\partial y} dy$$

$$dv = \frac{\partial v}{\partial x} dx + \frac{\partial v}{\partial y} dy$$

$$\Rightarrow \begin{pmatrix} du \\ dv \end{pmatrix} = \begin{pmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} \begin{pmatrix} dx \\ dy \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} dx \\ dy \end{pmatrix} = \frac{1}{D} \begin{pmatrix} \frac{\partial v}{\partial y} & -\frac{\partial u}{\partial y} \\ -\frac{\partial v}{\partial x} & \frac{\partial u}{\partial x} \end{pmatrix} \begin{pmatrix} du \\ dv \end{pmatrix}$$

$$\text{so } dx = \frac{1}{D} \left(\frac{\partial v}{\partial y} du - \frac{\partial u}{\partial y} dv \right)$$

$$dy = \frac{1}{D} \left(-\frac{\partial v}{\partial x} du + \frac{\partial u}{\partial x} dv \right)$$

$$\Rightarrow \frac{\partial x}{\partial u} = \frac{1}{D} \frac{\partial v}{\partial y} ; \frac{\partial x}{\partial v} = -\frac{1}{D} \frac{\partial u}{\partial y} ; \frac{\partial y}{\partial u} = -\frac{1}{D} \frac{\partial v}{\partial x} ; \frac{\partial y}{\partial v} = \frac{1}{D} \frac{\partial u}{\partial x}$$

or $\frac{\partial u}{\partial x} = D \frac{\partial y}{\partial v} ; \frac{\partial u}{\partial y} = -D \frac{\partial x}{\partial v} ; \frac{\partial v}{\partial x} = -D \frac{\partial y}{\partial u} ; \frac{\partial v}{\partial y} = D \frac{\partial x}{\partial u}$

Thus: Eq 1.55 becomes:

$$(1 - (\frac{u}{c})^2) \left[D \frac{\partial y}{\partial v} \right] + (1 - (\frac{x}{c})^2) \left[D \frac{\partial x}{\partial u} \right] - \frac{uv}{c^2} \left[-D \frac{\partial x}{\partial v} + -D \frac{\partial y}{\partial u} \right] = 0$$

$\div D \neq 0$

$$(1 - (\frac{u}{c})^2) \frac{\partial y}{\partial v} + (1 - (\frac{x}{c})^2) \frac{\partial x}{\partial u} + \frac{uv}{c^2} (\frac{\partial x}{\partial v} + \frac{\partial y}{\partial u}) = 0 \quad \checkmark$$

+ eq of $\nabla \times \vec{u} = 0$ is $\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} = 0$ or transformed

$$-D \frac{\partial x}{\partial v} - (-D \frac{\partial y}{\partial u}) = 0 \quad \div D$$

$$-\frac{\partial x}{\partial v} + \frac{\partial y}{\partial u} = 0 \quad \checkmark$$

$$\nabla \times \vec{u}(u, v, w) = \begin{vmatrix} \hat{k} & \hat{j} & \hat{i} \\ \frac{\partial}{\partial u} & \frac{\partial}{\partial v} & \frac{\partial}{\partial w} \\ x & y & z \end{vmatrix} = \hat{k} \left(\frac{\partial y}{\partial u} - \frac{\partial x}{\partial v} \right) \quad \checkmark = 0$$

1.56 w/ $x = \Theta_u$ $y = \Theta_v$ we get

$$(1 - (\frac{x}{c})^2) \Theta_{vv} + (1 - (\frac{u}{c})^2) \Theta_{ww} + \frac{uv}{c^2} (\Theta_{vu} + \Theta_{uv}) = 0$$

$$(1 - (\frac{x}{c})^2) \Theta_{ww} + (1 - (\frac{u}{c})^2) \Theta_{vv} + \frac{2uv}{c^2} \Theta_{uv} = 0 \quad \checkmark$$

(ω, α) used in the hodograph plane

$$U = \omega \cos \alpha \quad V = \omega \sin \alpha$$

eq 1.57 is

$$\left(1 - \left(\frac{v}{c}\right)^2\right) \partial_w \theta + \left(1 - \left(\frac{v}{c}\right)^2\right) \partial_v \theta + \frac{2uv}{c^2} \partial_w \theta = 0 \quad \text{eq 1.57}$$

$$\text{let } U = w \cos \alpha \quad V = w \sin \alpha \quad \begin{cases} W = \sqrt{U^2 + V^2} \\ \alpha = \tan^{-1}\left(\frac{V}{U}\right) \end{cases}$$

$$\partial_U = \partial_w \partial_w + \partial_\alpha \partial_\alpha$$

$$\partial_V = \partial_w \partial_w + \partial_\alpha \partial_\alpha$$

$$\frac{\partial w}{\partial U} = ? \quad \frac{\partial \alpha}{\partial U} = ? \quad \frac{\partial w}{\partial V} = ? \quad \frac{\partial \alpha}{\partial V} = ?$$

$$\frac{\partial w}{\partial U} = \frac{U}{\sqrt{U^2 + V^2}} \quad ; \quad \frac{\partial \alpha}{\partial U} = \frac{\left(-\frac{V}{U^2}\right)}{1 + \left(\frac{V}{U}\right)^2}$$

$$\frac{\partial w}{\partial V} = \frac{V}{\sqrt{U^2 + V^2}} \quad ; \quad \frac{\partial \alpha}{\partial V} = \frac{\left(\frac{1}{U}\right)}{1 + \left(\frac{V}{U}\right)^2}$$

$$\Rightarrow \frac{\partial w}{\partial U} = \cos \alpha \quad ; \quad \frac{\partial \alpha}{\partial U} = \frac{-\frac{V}{U^2 + V^2}}{1 + \left(\frac{V}{U}\right)^2} = -\frac{\sin \alpha}{W}$$

$$\frac{\partial w}{\partial V} = \sin \alpha \quad ; \quad \frac{\partial \alpha}{\partial V} = \frac{\frac{U}{U^2 + V^2}}{1 + \left(\frac{V}{U}\right)^2} = +\frac{\cos \alpha}{W}$$

$$\partial_w = \cos \alpha \frac{\partial}{\partial w} + - \frac{\sin \alpha}{w} \frac{\partial}{\partial \alpha} \quad \checkmark$$

$$\frac{\partial}{\partial v} = \sin \alpha \frac{\partial}{\partial v} + \frac{\cos \alpha}{w} \frac{\partial}{\partial \alpha} \quad \checkmark$$

Then eq 1.51 becomes:

~~(1.51)~~

$$\begin{aligned} & (1 - (\frac{v}{c})^2) \left(\cos \alpha \partial_w - \frac{1}{w} \sin \alpha \partial_\alpha \right)^2 \Theta \\ & + (1 - (\frac{v}{c})^2) \left(\sin \alpha \partial_w + \frac{1}{w} \cos \alpha \partial_\alpha \right)^2 \Theta \\ & + \frac{2wv}{c^2} \left(\cos \alpha \partial_w - \frac{1}{w} \sin \alpha \partial_\alpha \right) \left(\sin \alpha \partial_w + \frac{1}{w} \cos \alpha \partial_\alpha \right) \Theta = 0 \end{aligned}$$

$$\Rightarrow (1 - (\frac{v}{c})^2) \left(\cos \alpha \partial_w - \frac{1}{w} \sin \alpha \partial_\alpha \right) \left(\cos \alpha \partial_w - \frac{1}{w} \sin \alpha \partial_\alpha \right) \Theta$$

$$+ (1 - (\frac{v}{c})^2) \left(\sin \alpha \partial_w + \frac{1}{w} \cos \alpha \partial_\alpha \right) \left(\sin \alpha \partial_w + \frac{1}{w} \cos \alpha \partial_\alpha \right) \Theta$$

$$+ \frac{2wv}{c^2} \left(\sin \alpha \cos \alpha \partial_w^2 + \frac{1}{w} \cos^2 \alpha \partial_w \partial_\alpha - \frac{1}{w^2} \cos^2 \alpha \partial_\alpha \right.$$

$$- \frac{1}{w} \sin \alpha (\cos \alpha) \partial_w - \frac{1}{w} \sin^2 \alpha \partial_\alpha \partial_w - \frac{1}{w^2} \sin \alpha (-\sin \alpha) \partial_\alpha$$

$$\left. - \frac{1}{w^2} \sin \alpha \cos \alpha \partial_\alpha^2 \right) \Theta = 0 \quad \checkmark$$

$$\Rightarrow \left(1 - \left(\frac{v}{c}\right)^2\right) \left[\cos^2 \alpha \partial_\omega^2 + \frac{1}{\omega^2} \cos \alpha \sin \alpha \partial_\alpha - \frac{1}{\omega} \cos \alpha \sin \alpha \partial_{\alpha\omega} \right.$$

$$- \frac{1}{\omega} \sin \alpha \cos \alpha \partial_{\alpha\omega} + \frac{1}{\omega} \sin^2 \alpha \partial_\omega + \frac{1}{\omega^2} \sin^2 \alpha \partial_\alpha^2$$

$$+ \frac{1}{\omega^2} \sin \alpha \cos \alpha \partial_\alpha \left. \right] \Theta$$

$$+ \left(1 - \left(\frac{v}{c}\right)^2\right) \left[\sin^2 \alpha \partial_\omega^2 - \frac{1}{\omega^2} \sin \alpha \cos \alpha \partial_\alpha + \frac{1}{\omega} \cos \alpha \sin \alpha \partial_{\omega\alpha}^2 \right.$$

$$+ \frac{1}{\omega} \cos^2 \alpha \partial_\omega + \frac{1}{\omega} \cos \alpha \sin \alpha \partial_{\alpha\omega} + \frac{1}{\omega^2} (-1) \sin \alpha \cos \alpha \partial_\alpha$$

$$+ \frac{1}{\omega^2} \cos^2 \alpha \partial_\alpha^2 \left. \right] \Theta$$

$$+ \frac{2v}{c^2} \left[\sin \alpha \cos \alpha \partial_\omega^2 + (\cos^2 \alpha - \sin^2 \alpha) \left(\frac{1}{\omega}\right) \partial_{\omega\alpha}^2 \right.$$

$$+ 4 (\sin^2 \alpha - \cos^2 \alpha) \left(\frac{1}{\omega^2}\right) \partial_\alpha - \frac{1}{\omega} \sin \alpha \cos \alpha \partial_\omega$$

$$\left. - \frac{1}{\omega^2} \sin \alpha \cos \alpha \partial_{\alpha\alpha}^2 \right] \Theta = 0$$

$$\Rightarrow \left(1 - \left(\frac{v}{c}\right)^2\right) \left[\cos^2 \alpha \partial_\omega^2 - \frac{2}{\omega} \right.$$

07-14-03 4

Assume eq 1.5B Results

$$\partial_{\omega} \Theta + \frac{1}{\omega^2} \left(1 - \frac{\omega^2}{c^2}\right) \partial_{\alpha} \Theta + \frac{1}{\omega} \left(1 - \frac{\omega^2}{c^2}\right) \partial_{\omega} \Theta = 0$$

let $\Theta(\omega, \alpha) = g(\omega) \sin(m\alpha)$ or $\Theta(\omega, \alpha) = g(\omega) \cos(m\alpha)$

$$g''(\omega) \begin{Bmatrix} \sin(m\alpha) \\ \cos(m\alpha) \end{Bmatrix} + \frac{1}{\omega^2} \left(1 - \frac{\omega^2}{c^2}\right) m^2 \begin{Bmatrix} \sin(m\alpha) \\ \cos(m\alpha) \end{Bmatrix} g + \cancel{\frac{1}{\omega} \left(1 - \frac{\omega^2}{c^2}\right) m g \begin{Bmatrix} \cos(m\alpha) \\ -\sin(m\alpha) \end{Bmatrix}} = 0$$

 $\Leftrightarrow$

$$+ \frac{1}{\omega} \left(1 - \frac{\omega^2}{c^2}\right) g'(\omega) \begin{Bmatrix} \sin(m\alpha) \\ \cos(m\alpha) \end{Bmatrix} = 0$$

$$\Rightarrow g''(\omega) - \frac{m^2}{\omega^2} \left(1 - \frac{\omega^2}{c^2}\right) g + \frac{1}{\omega} \left(1 - \frac{\omega^2}{c^2}\right) g' = 0$$

$$\Rightarrow g'(\omega) + \frac{1}{\omega} \left(1 - \frac{\omega^2}{c^2}\right) g' - \frac{m^2}{\omega^2} \left(1 - \frac{\omega^2}{c^2}\right) g = 0 \quad \checkmark$$

$$m=0 \quad \frac{g''}{g'} = -\frac{1}{\omega} \left(1 - \frac{\omega^2}{c^2}\right) = -\frac{1}{\omega} + \frac{\omega}{c^2} \quad \checkmark$$

 $m=1$

$$g'' + \frac{1}{\omega} \left(1 - \frac{\omega^2}{c^2}\right) g' - \frac{1}{\omega^2} \left(1 - \frac{\omega^2}{c^2}\right) g = 0$$

$$2.9 \quad f(p) = v_f \cdot p \cdot \left(1 - \frac{p}{p^*}\right)$$

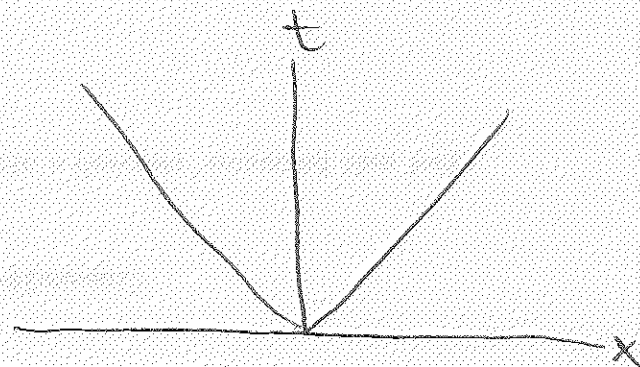
$$1.17 \quad x(t) = x_0 + t f'(w(x_0)) \quad \left[\begin{array}{l} f'(p) = v_f \left[\left(1 - \frac{p}{p^*}\right) + \frac{p}{p^*} (-1) \right] \\ = v_f \left[1 - \frac{2p}{p^*} \right] \end{array} \right]$$

$$w/p \quad p(x) = \begin{cases} p^* & x < 0 \\ 0 & x \geq 0 \end{cases}$$

$$f'(p_0(x)) = v_f \cdot \begin{cases} 1-2 & x_0 < 0 \\ 1 & x_0 \geq 0 \end{cases} = \begin{cases} -v_f & x_0 < 0 \\ v_f & x_0 \geq 0 \end{cases}$$

$$x(t) = x_0 + t \begin{cases} -v_f & x_0 < 0 \\ v_f & x_0 \geq 0 \end{cases}$$

$$\frac{x-x_0}{v_f} = \begin{cases} -t & x_0 < 0 \\ +t & x_0 \geq 0 \end{cases}$$



eq 2.3 is $\partial_t F + \partial_x F = 0$

$$f(p) = p v(p) = \cancel{p \cdot V_f \cdot \left(1 - \frac{f}{p^*}\right)} = V \cdot p^* \left(1 - \frac{V}{V_f}\right) \\ = p V_f \left(1 - \frac{p}{p^*}\right)$$

$$\frac{f}{p^*} = 1 - \frac{V}{V_f} \Rightarrow \left(1 - \frac{f}{p^*}\right) V_f = V(p)$$

eq 2.3 $\Rightarrow \partial_t F + f_v \cdot \partial_x v(p) = 0$

$$\Rightarrow \partial_t F + f_v \frac{\partial}{\partial x} \left[V_f \left(1 - \frac{p}{p^*}\right) \right] = 0 \quad \sim \checkmark$$

eq 2.2 is

$$\int_{\Omega} \left[\vec{V} \partial_t \Phi + \vec{F}(\vec{V}) \partial_x \Phi \right] d(x,t) + \int_{-\infty}^{+\infty} \vec{V}_0(x) \Phi(x,0) dx = 0 \quad \forall \Phi \in C_0^1(\Omega)$$

$$\Rightarrow \int_0^{\infty} \int_{-\infty}^{+\infty} \left[p_1 \cdot \partial_t \Phi + \partial_x \Phi \cdot p_1 V_f \left(1 - \frac{p}{p^*}\right) \right] d(x,t) + \int_{-\infty}^{\infty} \Phi(x,0) p_0(x) dx$$

$$= \int_0^{\infty} \int_{-\infty}^0 \left[p^* \partial_t \Phi + 0 \right] d(x,t) + \int_{-\infty}^0 \Phi(x,0) p^* dx =$$

$$= p^* \int_{-\infty}^0 \Phi(x,t') \Big|_0^{\infty} dx + p^* \int_{-\infty}^0 \Phi(x,0) dx =$$

$$= P^* \int_{-\infty}^0 (\cancel{\Phi(x, \infty)}^0 - \Phi(x, 0)) dx + P^* \int_{-\infty}^0 \Phi(x, 0) dx = 0 \quad \checkmark$$

07-16-03

2

$$\hat{V} > u_r > 0$$

$$\Rightarrow \hat{V} - u_r > 0$$

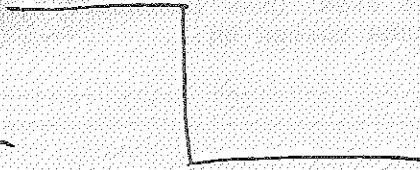
Since $\hat{V} - u_r$ is the sum

sign by

$$p_e(\hat{V} - u_r) = p_r(\hat{V} - u_r)$$

$$\hat{V} - u_r > 0$$

$$\Rightarrow \hat{V} > u_r$$



$e = \text{energy per unit mass}$

$$\frac{\partial \rho}{\partial t} + \rho \frac{\partial e}{\partial t} + \rho \frac{\partial e}{\partial x} + \frac{1}{2} \frac{\partial \rho}{\partial t} u^2$$

$$+ \rho u \frac{\partial u}{\partial t} + u \left\{ \frac{\partial \rho}{\partial x} + \frac{\partial \rho}{\partial x} e + \rho \frac{\partial e}{\partial x} + \frac{1}{2} \frac{\partial \rho}{\partial x} u^2 + \rho u \frac{\partial u}{\partial x} \right\}$$

$$+ \left(\rho e + \frac{\rho u^2}{2} + p \right) \frac{\partial u}{\partial x} = 0$$

$$\Rightarrow \frac{\partial \rho}{\partial t} e + \rho u \frac{\partial e}{\partial x} + \rho e \frac{\partial u}{\partial x}$$

$$+ \frac{1}{2} \frac{\partial \rho}{\partial x} u^3 + \frac{\rho u^2}{2} \frac{\partial u}{\partial x} + \frac{1}{2} \frac{\partial \rho}{\partial t} u^2$$

$$+ \rho \frac{\partial e}{\partial t} + \rho u \frac{\partial e}{\partial x} + \rho \frac{\partial u}{\partial x}$$

$$+ \rho u \frac{\partial u}{\partial t} + \rho u \frac{\partial u}{\partial x} + \rho u^2 \frac{\partial u}{\partial x} = 0$$

$$\Rightarrow e \left(\frac{\partial \rho}{\partial t} + \frac{\partial (\rho u)}{\partial x} \right) + \frac{u^2}{2} \left(\frac{\partial \rho}{\partial x} + \rho \frac{\partial u}{\partial x} + \frac{\partial \rho}{\partial t} \right)$$

$$+ \rho \left(\frac{\partial e}{\partial t} + u \frac{\partial e}{\partial x} + \frac{p}{\rho} \frac{\partial u}{\partial x} \right)$$

$$+ \rho u \left(\frac{\partial u}{\partial t} + \frac{1}{\rho} \frac{\partial \rho}{\partial x} + u \frac{\partial u}{\partial x} \right) = 0$$

$\Rightarrow$ ~~$\frac{\partial}{\partial t} + u \frac{\partial}{\partial x}$~~

$$\left(1 + \frac{u^2}{2}\right) \left(\frac{\partial p}{\partial t} + \frac{\partial(pu)}{\partial x}\right) + p \left(\frac{\partial \epsilon}{\partial t} + u \frac{\partial \epsilon}{\partial x} + \frac{p}{\rho} \frac{\partial u}{\partial x}\right)$$

$$+ u p \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + \frac{1}{\rho} \frac{\partial p}{\partial x}\right) = 0 \quad \text{eq 3.5} \quad \checkmark$$

$$\frac{\partial q}{\partial t} + \frac{\partial}{\partial x} \left(\frac{q^2}{\rho} + p \right) = 0$$

$$q = \rho u$$

$$u \frac{\partial \rho}{\partial t} + \rho \frac{\partial u}{\partial t} + \frac{\partial}{\partial x} (\rho u^2 + p) = 0$$

$$u \frac{\partial \rho}{\partial t} + \rho \frac{\partial u}{\partial t} + u^2 \frac{\partial \rho}{\partial x} + 2u\rho \frac{\partial u}{\partial x} + \frac{\partial p}{\partial x} = 0$$

$$\Rightarrow \rho \left(\frac{\partial u}{\partial t} + \frac{1}{\rho} \frac{\partial p}{\partial x} + u \frac{\partial u}{\partial x} \right) + u \left(\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} + \rho \frac{\partial u}{\partial x} \right) = 0$$

$$\Rightarrow \rho \left(\frac{\partial u}{\partial t} + \frac{1}{\rho} \frac{\partial p}{\partial x} + u \frac{\partial u}{\partial x} \right) + u \left(\frac{\partial \rho}{\partial t} + \frac{\partial (\rho u)}{\partial x} \right) = 0$$

$$\Rightarrow \frac{\partial u}{\partial t} + \frac{1}{\rho} \frac{\partial p}{\partial x} + u \frac{\partial u}{\partial x} = 0 \quad \text{so eq 3.5 becomes}$$

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + \frac{1}{\rho} \frac{\partial p}{\partial x} = 0 \quad \text{eq 3.6 } \checkmark$$

Since eq 3.4 is formulated in the following way

$$\frac{\partial s}{\partial t} + \frac{\partial (us)}{\partial x} = \frac{1}{T} \left[\underbrace{\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x}}_{\text{eq 3.6}} - \frac{p}{\rho^2} \frac{\partial \rho}{\partial t} - \frac{up}{\rho^2} \frac{\partial \rho}{\partial x} \right] - \frac{p}{\rho} \frac{\partial u}{\partial x}$$

$$= \frac{1}{T} \left[-\frac{p}{\rho} \frac{\partial u}{\partial x} - \frac{p}{\rho^2} \frac{\partial \rho}{\partial t} - \frac{up}{\rho^2} \frac{\partial \rho}{\partial x} \right]$$

eq 3.7 $\checkmark$

$$= \cancel{\frac{P}{T}} \frac{P}{T} \left\{ -\frac{P}{P^2} \frac{\partial u}{\partial x} - \frac{1}{P^2} \frac{\partial P}{\partial t} - \frac{u}{P^2} \frac{\partial P}{\partial x} \right\}$$

$$= -\frac{P \cdot P}{T P^2} \left\{ P \frac{\partial u}{\partial x} + \frac{\partial P}{\partial t} + u \frac{\partial P}{\partial x} \right\} = -\frac{P}{T P} \left\{ \frac{\partial P}{\partial t} + \cancel{\frac{\partial(Pu)}{\partial x}} \right\}$$

$$\Rightarrow \frac{\partial s}{\partial t} + \frac{\partial(us)}{\partial x} = 0$$

$$\text{eg 3.9} \quad \frac{\partial s}{\partial t} + \frac{\partial(us)}{\partial x} \geq 0$$

$$\int_{\Omega} \left(\Phi \frac{\partial s}{\partial t} + \Phi \frac{\partial(us)}{\partial x} \right) d(x,t) \geq 0 \quad \forall \Phi \in C_0^1(\Omega) \quad \Phi \geq 0$$

$$= \int_{\Omega} \left(\frac{\partial(\Phi s)}{\partial t} - s \frac{\partial \Phi}{\partial t} + \frac{\partial(\Phi us)}{\partial x} - us \frac{\partial \Phi}{\partial x} \right) d(x,t) \geq 0$$

$$= \int_{\Omega} \left(\frac{\partial(\Phi s)}{\partial t} + \frac{\partial(\Phi us)}{\partial x} \right) d(x,t) - \int_{\Omega} \left(s \frac{\partial \Phi}{\partial t} + us \frac{\partial \Phi}{\partial x} \right) d(x,t) \geq 0$$

$$= \int_{\Omega} \nabla_0(\Phi s, \Phi us) d(x,t) - \int_{\Omega} \left(s \frac{\partial \Phi}{\partial t} + us \frac{\partial \Phi}{\partial x} \right) d(x,t) \geq 0$$

$$\nabla = \left(\frac{\partial}{\partial t}, \frac{\partial}{\partial x} \right)$$

07-17-03 3

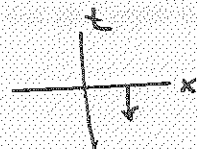
$$= \int_{\partial Q} (\Phi_s, \Phi_{us}) \cdot \hat{n} \, d\sigma - \int_Q \geq 0$$

$\hat{n} =$ let $\partial Q \rightarrow +\infty$ $\{\hat{n} = \text{actual normal}\}$

$\Rightarrow$ only integral that matters is the one over the x-axis

$$= - \int_{-\infty}^{+\infty} \Phi_s \Big|_{t=0} dx - \int_Q \geq 0 \quad d\sigma = dx$$

$$\hat{n} = \cancel{(-1, 0)} (-1, 0)$$



$$\Rightarrow \int_Q \left(s \frac{\partial \Phi}{\partial t} + us \frac{\partial \Phi}{\partial x} \right) dx dt + \int_{-\infty}^{+\infty} \Phi(x, 0) s(x, 0) dx \leq 0$$

eq 310 ✓

19.24 Aufgabe

$$S'(v) \cdot \frac{\partial v}{\partial t} + F'(v) \frac{\partial v}{\partial x} = 0 \quad \text{eq 2.1} \quad \frac{\partial v}{\partial t} + \frac{\partial F(v)}{\partial x} = 0$$

$$\Rightarrow S'(v) \left[-\frac{\partial F(v)}{\partial x} \right] + F'(v) \frac{\partial v}{\partial x} = 0$$

$$\Rightarrow -S'(v) F'(v) \frac{\partial v}{\partial x} + F'(v) \frac{\partial v}{\partial x} = 0$$

$$\Rightarrow [-S'(v) F'(v) + F'(v)] \frac{\partial v}{\partial x} = 0$$

$$\Rightarrow F'(v) = S'(v) F'(v)$$

$$\Rightarrow F(v) = \int_0^v S'(x) F'(x) dx + C \quad \text{eq 3.13} \quad \checkmark$$

If ~~w~~ $m > 1$ + $\vec{v}$ is

$$\langle \nabla_v S, \frac{\partial \vec{v}}{\partial t} \rangle + \langle \nabla_v F, \frac{\partial \vec{v}}{\partial x} \rangle = 0$$

$$\frac{\partial \vec{v}}{\partial t} = - \langle \nabla_v F, \frac{\partial \vec{v}}{\partial x} \rangle$$

$$\Rightarrow - \langle \nabla_v S, J F(v) \frac{\partial \vec{v}}{\partial x} \rangle + \langle \nabla_v F, \frac{\partial \vec{v}}{\partial x} \rangle = 0$$

$$\left(\frac{\partial \vec{v}}{\partial x} \right)^T \left(\nabla_v F - (J F(v))^T (\nabla_v S) \right) = 0$$

$$\Rightarrow \nabla_v F - (J F(v))^T \nabla_v S = 0 \quad \text{eq 3.14}$$

$$\vec{F}(\vec{v}) = \nabla_{\vec{v}} k(\vec{v}) \quad 3.14. \quad = \left(\frac{\partial k}{\partial v_i} \right)_{i=1}^n$$

$$\nabla_{\vec{v}} \hat{F} - (JH(\vec{v}))^T \nabla_{\vec{v}} \hat{S} = 0 \quad \text{w/} \quad \hat{S} = \frac{1}{2} \langle \vec{v}, \vec{v} \rangle = \frac{1}{2} \left(\sum_{i=1}^n v_i^2 \right)$$

$$\frac{\partial \hat{F}}{\partial v_i} - \left(J \begin{pmatrix} \frac{\partial k}{\partial v_1} \\ \vdots \\ \frac{\partial k}{\partial v_n} \end{pmatrix} \right)^T \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix} = 0$$

$$\Rightarrow \left(\frac{\partial \hat{F}}{\partial v_i} \right) - \begin{pmatrix} \frac{\partial^2 k}{\partial v_1^2} & \frac{\partial^2 k}{\partial v_1 \partial v_2} & \dots & \frac{\partial^2 k}{\partial v_1 \partial v_n} \\ \frac{\partial^2 k}{\partial v_2 \partial v_1} & \dots & \dots & \dots \\ \vdots & \dots & \dots & \dots \\ \frac{\partial^2 k}{\partial v_n \partial v_1} & \dots & \dots & \frac{\partial^2 k}{\partial v_n \partial v_n} \end{pmatrix}^T \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix} = 0$$

$$\Rightarrow \begin{pmatrix} \frac{\partial \hat{F}}{\partial v_1} \\ \vdots \\ \frac{\partial \hat{F}}{\partial v_n} \end{pmatrix} - \begin{pmatrix} \frac{\partial^2 k}{\partial v_1^2} v_1 + \frac{\partial^2 k}{\partial v_1 \partial v_2} v_2 + \dots + \frac{\partial^2 k}{\partial v_1 \partial v_n} v_n \\ \vdots \\ \frac{\partial^2 k}{\partial v_n \partial v_1} v_1 + \frac{\partial^2 k}{\partial v_n \partial v_2} v_2 + \dots + \frac{\partial^2 k}{\partial v_n \partial v_n} v_n \end{pmatrix} = \vec{0}$$

$$\Rightarrow \frac{\partial F}{\partial v_i} - \sum_{j=1}^n \frac{\partial^2 k}{\partial v_i \partial v_j} \cdot v_j = 0 \quad i=1, \dots, n \quad \text{Book uses } m.$$

changing to m

$$\frac{\partial F}{\partial v_i} = \sum_{j=1}^m \frac{\partial}{\partial v_i} \left(\frac{\partial k}{\partial v_j} \right) v_j$$

$$= \frac{\partial}{\partial v_i} \left(\sum_{j=1}^m \left(\frac{\partial k}{\partial v_j} \right) v_j \right) - \frac{\partial k}{\partial v_i} \quad \checkmark$$

Integrate wnt v_i

$$\tilde{F}(\vec{v}) = \langle \tilde{F}(\vec{v}), \vec{v} \rangle - k(\vec{v}) + \text{const} \quad \text{eg } 3.15 \quad \checkmark$$

$$m=1 \quad \rightarrow \quad S(v) = \frac{1}{2} v^2 \quad F(v) \neq \frac{v^2}{2} \quad \text{Specify a general } F(v)$$

$$\tilde{F}(v) = \langle \tilde{F}, \cdot \rangle$$

$$F(v) \rightarrow \frac{\partial k}{\partial v} = F(v)$$

From eq

$$\frac{\partial F}{\partial v} = \left(\frac{\partial^2 k}{\partial v^2} \right) v = \frac{\partial}{\partial v} \left(\frac{\partial k}{\partial v} \cdot v \right) - \frac{\partial k}{\partial v} \cdot 1$$

How get 3.16?

$$F(v) = -k(v) +$$

$$[\hat{S}] \hat{v} \in [\hat{F}]$$

$$\hat{v} \neq \frac{[f]}{[v]}$$

$$\frac{[\hat{S}][f]}{[v]} \in [\hat{F}]$$

$$\hat{v} = \frac{[f]}{[v]} \text{ for scalar case only}$$

$$f(v) = \begin{cases} \left(\frac{S(v) - S(v_r)}{v - v_r} \right) (f(v) - f(v_r)) - \int_{v_r}^v S'(a) f'(a) da \\ 0 \end{cases}$$

$$f'(v) = \begin{cases} \frac{S'(v)}{(v - v_r)} (f(v) - f(v_r)) + \frac{(S(v) - S(v_r))}{(v - v_r)^2} (f(v) - f(v_r)) \\ + \left(\frac{S(v) - S(v_r)}{v - v_r} \right) f'(v) - S'(v) f'(v) & v \neq v_r \\ 0 & v = v_r \end{cases}$$

$$\Rightarrow f'(v) = \begin{cases} -S'(v) \left[f'(v) - \frac{f(v) - f(v_r)}{v - v_r} \right] \\ + \frac{(S(v) - S(v_r))}{v - v_r} \left[f'(v) - \frac{f(v) - f(v_r)}{v - v_r} \right] & v \neq v_r \\ 0 & v = v_r \end{cases}$$

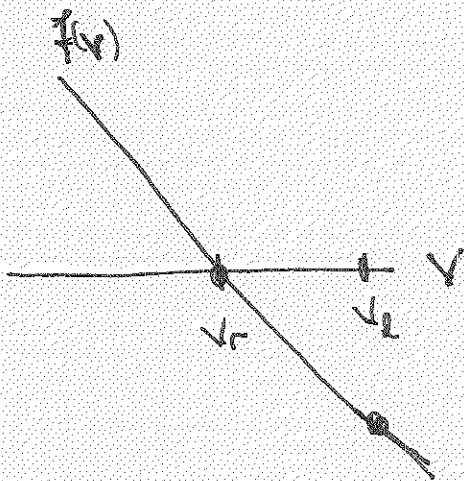
$$\Rightarrow f'(v) = \begin{cases} - \left\{ S'(v) - \frac{S(v) - S(v_r)}{v - v_r} \right\} & v \neq v_r \\ 0 & v = v_r \end{cases} \quad \begin{matrix} \text{02-21-03} \\ 2 \end{matrix}$$

Since $S''(v) > 0 \quad \forall v \in \mathbb{R}$

$$S'(v) - \frac{S(v) - S(v_r)}{v - v_r} > 0 \quad v > v_r \quad + \text{ neg for } v < v_r$$

$$\Rightarrow f'(v) - \frac{f(v) - f(v_r)}{v - v_r} > 0$$

$$f'(v) < 0 \quad \text{for } v \neq v_r$$



$$\Rightarrow v_r < v_l$$

entropy

$$\frac{d}{dt} \vec{V}(x_i(t), t) = \frac{\partial \vec{V}(x_i(t), t)}{\partial t} + \frac{\partial \vec{V}(x_i(t), t)}{\partial x} \cdot \dot{x}_i(t)$$

$$\text{Sim} \quad \frac{\partial \vec{V}}{\partial t} + \frac{\partial f(\vec{V}(x_i(t)))}{\partial x} = 0$$

$$\frac{\partial x}{\partial t} = -J_V \cdot \frac{\partial V}{\partial x}$$

$$\frac{d}{dt} \vec{V}(x_i(t), t) = -J_V \cdot \frac{\partial V(x_i(t), t)}{\partial x} + \lambda(V) \frac{\partial \vec{V}}{\partial x}$$

$$= - \left[J_V(\vec{V}(x_i(t), t)) - \lambda_i(\vec{V}(x_i(t), t)) \cdot I \right] \frac{\partial \vec{V}(x_i(t), t)}{\partial x}$$

q 3.31 ✓

$$V(x,t) = V^* \left(\frac{x-x_0}{t-t_0} \right)$$

$$\begin{aligned} \frac{\partial V}{\partial t} + \frac{\partial V}{\partial x} \xi_x &= Jf(V^*) \frac{\partial V}{\partial x} + \frac{\partial V}{\partial t} = Jf(V^*) \frac{\partial V^*}{\partial \xi} \cdot \xi_x + \frac{\partial V^*}{\partial \xi} \cdot \xi_t \\ &= \left(\xi_x Jf(V^*) + \xi_t \right) \frac{\partial V^*}{\partial \xi} = 0 \end{aligned}$$

$$\Rightarrow \left(Jf(V^*) + \frac{\xi_t}{\xi_x} I \right) \frac{\partial V^*}{\partial \xi} = 0$$

$$\frac{\xi_t}{\xi_x} = \frac{-\frac{(x-x_0)}{(t-t_0)^2}}{\frac{1}{(t-t_0)}} = -1$$

$$\Rightarrow \left(Jf(V^*) - I \right) \frac{\partial V^*}{\partial \xi} = 0 \quad \text{eq 3.33} \quad \checkmark$$

$$\begin{aligned} \Rightarrow V^*(\xi) &= \xi(V^*(\xi)) \\ \xi &= \xi(V^*(\xi)) \end{aligned} \quad \text{eq 3.34}$$

$$\xi \frac{\partial}{\partial \xi} \Rightarrow 1 = \langle \nabla_V \xi, \frac{\partial V^*}{\partial \xi} \rangle = \langle \nabla_V \xi(\vec{v}), \xi(\vec{v}) \rangle$$

$$\frac{\partial \rho}{\partial t} \bar{u} + \rho \frac{\partial \bar{u}}{\partial t} + \langle \bar{u}, \nabla \rho \rangle \bar{u} + \rho \langle \bar{u}, \nabla \rangle \bar{u} + (\rho \nabla \cdot \bar{u}) \bar{u} - \rho \hat{f} + \nabla p - (\lambda + \eta) \nabla (\nabla \cdot \bar{u}) - \eta \nabla^2 \bar{u} = 0$$

$$\rho \nabla \cdot \bar{u} + \langle \bar{u}, \nabla \rho \rangle = \nabla \cdot (\rho \bar{u})$$

$$\Rightarrow \frac{\partial \rho}{\partial t} \bar{u} + \rho \frac{\partial \bar{u}}{\partial t} + (\nabla \cdot (\rho \bar{u}) - \rho \nabla \cdot \bar{u}) \bar{u} + \rho \langle \bar{u}, \nabla \rangle \bar{u} + (\rho \nabla \cdot \bar{u}) \bar{u} - \rho \hat{f} + \nabla p - (\lambda + \eta) \nabla (\nabla \cdot \bar{u}) - \eta \nabla^2 \bar{u} = 0$$

$$\Rightarrow \left(\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \bar{u}) \right) \bar{u} + \rho \frac{\partial \bar{u}}{\partial t} - \cancel{\rho (\nabla \cdot \bar{u}) \bar{u}} + \rho \langle \bar{u}, \nabla \rangle \bar{u}$$

$$+ \cancel{\rho (\nabla \cdot \bar{u}) \bar{u}} - \rho \hat{f} + \nabla p - (\lambda + \eta) \nabla (\nabla \cdot \bar{u}) - \eta \nabla^2 \bar{u} = 0 \quad \checkmark$$

$$\Rightarrow \frac{\partial \bar{u}}{\partial t} + \langle \bar{u}, \nabla \rangle \bar{u} - \frac{(\lambda + \eta)}{\rho} \nabla (\nabla \cdot \bar{u}) - \frac{1}{\rho} \nabla^2 \bar{u} = -\frac{1}{\rho} \nabla p + \hat{f}$$

eq 8.9 ✓

$$[\lambda] = [\eta] = \frac{\text{g}}{\text{cm} \cdot \text{s}} = \text{Poise}$$