

Ex 3.1

eq 2.16 is

$$\int_{x_1}^{x_2} u(x, t_2) dx = \int_{x_1}^{x_2} u(x, t_1) dx + \int_{t_1}^{t_2} f(u(x_1, t)) dt - \int_{t_1}^{t_2} f(u(x_2, t)) dt + x_1, x_2, t_1, t_2$$

W/ $f(u) = au$ we get

$$\int_{x_1}^{x_2} u_0(x-at_2) dx = \int_{x_1}^{x_2} u_0(x-at_1) dx + \int_{t_1}^{t_2} a u_0(x_1-at) dt - \int_{t_1}^{t_2} a u_0(x_2-at) dt$$

$$\begin{array}{lll} \text{Working on R.H.S} & \text{let } v = x - at & \text{let } v = x_1 - at \\ \text{we get} & dv = dx & dv = -adt \\ & & dv = -adt \end{array}$$

$$= \int_{x_1 - at_1}^{x_2 - at_1} U_0(r) dr - \int_{x_1 - at_1}^{x_1 - at_2} U_0(r) dr + \int_{x_2 - at_2}^{x_2 - at_1} U_0(r) dr$$

Then

$$= \int_{V_0}^{V_2-aL_1} U_0(r) dr + \int_{V_1-aL_1}^{V_2-aL_2} U_0(r) dr + \int_{V_2-aL_2}^{V_3-aL_3} U_0(r) dr$$

$$= \int_{x_1 - at_1}^{x_1 + at_1} + \int_{x_2 - at_2}^{x_2 + at_2} + \int_{x_3 - at_3}^{x_3 + at_3}$$

$$= \int_{V_0}^{x_2 - at_2} U(dv) \Delta v$$

let $v = x - at_2$
 $\Delta v = \Delta x$

$$= \int_{x_1}^{x_2} u_0(x - ct_0) dx \quad \text{correct } \checkmark$$

Ex 3.2

$$v_t + \alpha v_x = \epsilon v_{xx}$$

$$\text{let } v(x,t) = u(x+\alpha t, t) \Rightarrow u(x,t) = v(x-\alpha t, t) \text{ see pg 2}$$

$$v_x = u_x \quad v_t = u_x \alpha + u_t \Rightarrow u_t = v_t - \alpha u_x \\ v_{xx} = u_{xx} \quad = v_t - \alpha v_x$$

$$\Rightarrow v_t - \alpha v_x + \alpha v_x = \epsilon v_{xx}$$

$$v_t = \epsilon v_{xx} \quad \text{eq 3.12}$$

Solve w/ Fourier transforms: let $\hat{v}(x,t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \hat{v}(\omega, t) e^{i\omega x} d\omega$

$$\hat{v}(\omega, t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} v(x,t) e^{-i\omega x} dx$$

Thus eq above becomes

$$\frac{d\hat{v}}{dt} = \epsilon (-i\omega)^2 \hat{v} = -\epsilon \omega^2 \hat{v}$$

$$\hat{v}(\omega, t) = C_0 e^{-\epsilon \omega^2 t} \quad \hat{v}(\omega, 0) = C_0 = \hat{v}_0(\omega) \text{ F.T. of } v_0(x)$$

Then $v(x,t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \hat{v}_0(\omega) e^{-\epsilon \omega^2 t} e^{i\omega x} d\omega$

so that see pg 2.

$$\text{If } \hat{U}(x,t) = v(x-at, t)$$

$$v_x = v_x \quad v_t = v_x(-a) + v_t$$

$$v_t + a v_x = \epsilon v_{xx} \Rightarrow -av_x + v_t + av_x = \epsilon v_{xx} \quad \text{Yes}$$

$$\hat{U}(x,t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \hat{U}_0(\omega) e^{-\epsilon \omega^2 t} e^{i\omega(x-at)} d\omega$$

$$\lim_{\epsilon \rightarrow 0} U^\epsilon(x,t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \hat{U}_0(\omega) e^{i\omega(x-at)} d\omega = \hat{U}_0(x-at)$$

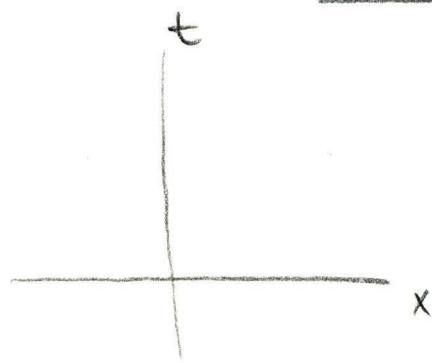
$$\text{Since } \hat{U}_0(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} u_0(x) e^{-ix\omega} dx$$

$$u_0(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \hat{U}_0(\omega) e^{i\omega x} d\omega$$

Ex 3.3

q 3.14 is

$$u_t + uu_x = 0$$

By method of characteristics $\frac{d\bar{x}(t), u}{dt} = 0$ Along $\frac{d\bar{x}(t)}{dt} = u(\bar{x}(t), t)$ $u(x, 0) = u_0(x)$ given

$$\therefore \text{extending at } 0 \quad \frac{d\bar{x}(0)}{dt} = u(\bar{x}(0), 0) = u(x_0, 0) = u_0(x_0)$$

$$\text{Thus } \frac{du(\bar{x}(t), t)}{dt} = 0 \quad \text{along } \frac{d\bar{x}(t)}{dt} = u_0(\bar{x}(0))$$

Breaking occurs iff characteristics cross. This happen if the characteristic from $x_0 + x_0 + \Delta x$ intersect \Rightarrow each characteristic is a d. line

$$\Rightarrow x - x_0 = u_0(x_0)t \Rightarrow x - x_0 = u_0(x_0)t$$

$$x - x_0 - \Delta x = u_0(x_0 + \Delta x)t$$

$$\approx u_0(x_0)t + u'_0(x_0)\Delta x t + O(\Delta x^2)$$

Subtracting to find $x + t$ when the 'intersection' occurs we obtain

$$\cancel{\Delta x} = u'_0(x_0) \cancel{\Delta x} t \Rightarrow t = \frac{-1}{u'_0(x_0)} \quad \forall x_0.$$

Thus the 1st characteristic crossing (t being minimum occurs when)

$$t = T_b = \frac{+1}{(-u'_0(x_0))} = \frac{+1}{\max(-u'_0(x_0))} = \frac{-1}{\min_{x \in (-\infty, +\infty)}(u'_0(x_0))}$$

For arbitrary convex scalar eqs

$$u_t + (f(u))_x = 0 \quad f(u) \text{ convex} \Rightarrow f''(u) > 0$$

Smart flows

$$\Leftrightarrow u_t + f(u)u_x = 0$$

everything follows as before w/

$$\begin{aligned} x - x_0 &= f(u_0(x_0))t \\ + x - x_0 - dx &= f'(u_0(x_0+dx))t \\ &= f'(u_0(x_0) + u_0'(x_0)dx + O(dx^2))t \\ &= (f'(u_0(x_0)) + f''(u_0(x_0))u_0'(x_0)dx + O(dx^2))t \end{aligned}$$

Subtracting $\cancel{x} = -f''(u_0(x_0))u_0'(x_0)\cancel{t}$

$$\Rightarrow t = -\frac{1}{f''(u_0(x_0))u_0'(x_0)}$$

$$T_b = \frac{\frac{+1}{\max(-f''(u_0(x_0))u_0'(x_0))}}{-\infty < x_0 < +\infty} = \frac{-1}{\min(f''(u_0(x_0))u_0'(x_0))} \quad -\infty < x_0 < +\infty$$

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$$\int_0^\infty \int_{-\infty}^\infty (\phi u_t + \phi f(u)_x) dx dt = 0$$

$$\Rightarrow \left(\int_{-\infty}^\infty \left(\int_0^\infty \phi u_t dt \right) dx \right) + \left(\int_0^\infty \left(\int_{-\infty}^\infty \phi f(u)_x dx \right) dt \right) = 0$$

$$\cancel{\left(\int_{-\infty}^\infty \left(\int_0^\infty \phi u_t |^{\infty}_0 dx \right) - \int_{-\infty}^\infty \int_0^\infty \phi_t u dx dt \right)} + \left(\int_0^\infty \left(\int_{-\infty}^\infty \phi f(u) |^{\infty}_{-\infty} dt \right) - \int_{-\infty}^\infty \int_0^\infty \phi_x f(u) dx dt \right) = 0$$

$$- \int_{-\infty}^\infty \phi(x,0) u(x,0) dx \therefore \int_{-\infty}^\infty \int_0^\infty (\phi_t u + \phi_x f(u)) dt dx = \cancel{- \int_{-\infty}^\infty f(x,0) u(x,0) dx}$$

Ex 3.4

$$3.25 \Rightarrow v(x,t) = \begin{cases} v_e & x < st \\ v_r & x > st \end{cases} \quad s = \frac{1}{2}(v_e + vr)$$

3.22

$$\rightarrow \int_0^\infty \int_{-\infty}^\infty (\phi_t v + \phi_x f(v)) dx dt = - \int_{-\infty}^\infty \phi(x,0) v(x,0) dx$$

R.H.S eq w/ $v(x,0) = \begin{cases} v_e & x < 0 \\ v_r & x > 0 \end{cases}$ + $f(v) = \frac{v^2}{2}$

$$= -v_e \int_{-\infty}^0 \phi(x,0) dx - v_r \int_0^{+\infty} \phi(x,0) dx \quad \checkmark$$

L.H.S.

$$= \int_0^{+\infty} \int_{-\infty}^{st} \phi_t v dx dt + \int_0^{+\infty} \int_{st}^{+\infty} \phi_t v dx dt + \int_0^{\infty} \int_{-\infty}^{st} \phi_x f(v) dx dt$$

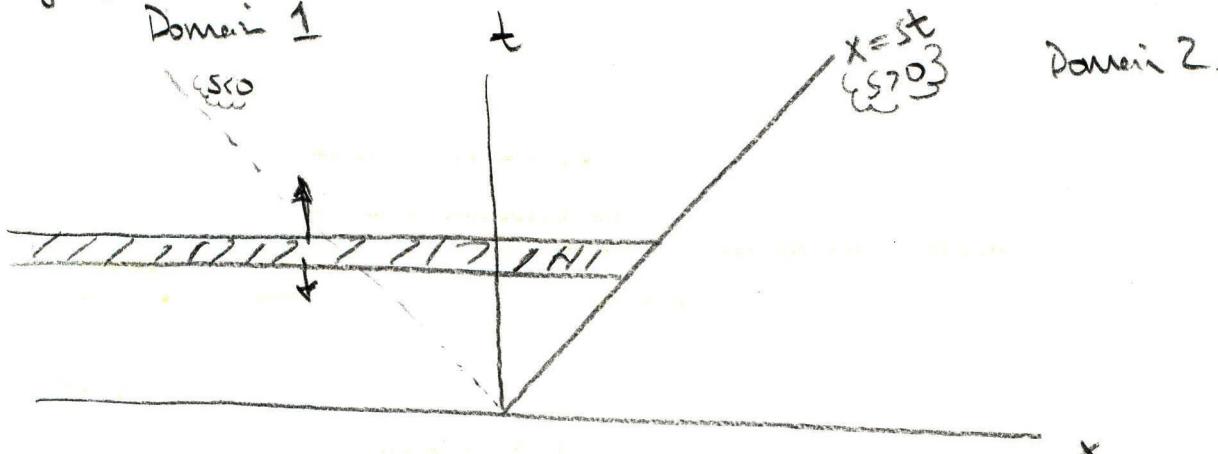
$$+ \int_0^{+\infty} \int_{st}^{+\infty} \phi_x f(v) dx dt \quad \checkmark$$

$$= v_e \int_0^{+\infty} \int_{-\infty}^{st} \phi_t dx dt + v_r \int_0^{+\infty} \int_{st}^{+\infty} \phi_t dx dt + \frac{v_e^2}{2} \int_0^{\infty} \int_{-\infty}^{st} \phi_x dx dt$$

$$+ \frac{v_r^2}{2} \int_0^{+\infty} \int_{st}^{+\infty} \phi_x dx dt \quad \checkmark$$

Choosing the order of integration of the 1st term

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Assume $s > 0$ If $s < 0$ procedure is the same

Then limits of integrand of 1st integral become:

$$\begin{array}{ll} -\infty \leq x \leq 0 & 0 \leq x \leq +\infty \\ 0 \leq t \leq +\infty & x/s \leq t \leq +\infty \end{array}$$

The limits of the 2nd integral then becomes:

$$0 \leq x \leq +\infty$$

$$0 \leq t \leq x/s$$

L.H.S

$$\Rightarrow V_L \int_{-\infty}^0 \int_0^{+\infty} \phi_t dt dx + V_L \int_0^{+\infty} \int_{x/s}^{+\infty} \phi_t dt dx$$

$$+ V_R \int_0^{+\infty} \int_0^{x/s} \phi_t dt dx$$

$$+ \frac{V_L^2}{2} \int_0^{\infty} \int_{-\infty}^{st} \phi_x dx dt + \frac{V_R^2}{2} \int_0^{\infty} \int_{st}^{+\infty} \phi_x dx dt$$

$$\Rightarrow V_L \int_{-\infty}^0 (-\phi(x,0)) dx + V_R \int_0^{+\infty} (-\phi(x,s)) dx$$

$$+ V_R \int_0^{+\infty} (\phi(x,s) - \phi(x,0)) dx$$

$$+ \frac{V_L^2}{2} \int_0^{\infty} \phi(st,t) dt + \frac{V_R^2}{2} \int_0^{\infty} (-\phi(st,t)) dt$$

$$= -V_L \int_{-\infty}^0 \phi(x,0) dx - V_R \int_0^{+\infty} \phi(x,0) dx$$

$$- V_L \int_0^{+\infty} \phi(x,s) dx + V_R \int_0^{+\infty} \phi(x,s) dx + \left(\frac{V_L^2}{2} - \frac{V_R^2}{2} \right) \int_0^{\infty} \phi(st,t) dt$$

$$v = st \\ dv = dt s$$

$$= -V_L \int_{-\infty}^0 \phi(x,0) dx - V_R \int_0^{+\infty} \phi(x,0) dx$$

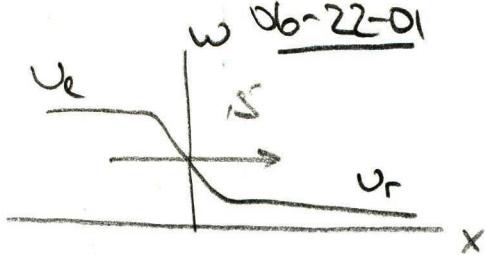
$$-(V_L - V_R) \int_0^{+\infty} \phi(x,s) dx + \frac{(V_L + V_R)(V_L - V_R)}{2s} \int_0^{+\infty} \phi(v,s) dv$$

$$\underbrace{= 0}_{= 0}$$

$$\therefore = -V_L \int_{-\infty}^0 \phi(x,0) dx - V_R \int_0^{+\infty} \phi(x,0) dx = RHS \quad \checkmark$$

Ex 3.5

$$\text{Eq 3.15 is } u_t + uu_x = \epsilon u_{xx}$$



Let $U^{\epsilon}(x,t) = \omega(x-st)$ is constant, let $\Theta = x-st$

$$-\omega'(s) + \omega\omega'(\Theta) = \epsilon\omega''(\Theta) \quad \checkmark$$

property of solution we seek
is that for fixed s & t

$$\epsilon\omega''(\Theta) + (s-\omega)\omega'(\Theta) = 0 \quad \checkmark$$

$$\Rightarrow \epsilon\omega'(\Theta) + s\omega'(\Theta) - \frac{1}{2} \int_0^\Theta \omega^2(\theta) = 0 \quad \checkmark$$

integrate once

$$\epsilon\omega'(\Theta) + s\omega(\Theta) - \frac{1}{2} \int_0^\Theta \omega^2(\theta) = C_1 \quad \checkmark$$

$$\lim_{x \rightarrow -\infty} U^{\epsilon}(x,t) = u_e$$

$$\lim_{x \rightarrow +\infty} U^{\epsilon}(x,t) = u_r$$

+ derivatives go to zero

$$\lim_{x \rightarrow -\infty} \frac{du^{\epsilon}}{dx}(x,t) = 0$$

$$\lim_{x \rightarrow +\infty} \frac{du^{\epsilon}}{dx}(x,t) = 0$$

$$\text{take } x \rightarrow \pm\infty \Rightarrow \Theta \rightarrow \pm\infty$$

$$x \rightarrow -\infty$$

$$0 + s\omega_e - \frac{1}{2} \omega_e^2 = C_1 \quad \checkmark$$

$$x \rightarrow +\infty$$

$$0 + s\omega_r - \frac{1}{2} \omega_r^2 = C_1 \quad \checkmark$$

Then subtracting the two gives

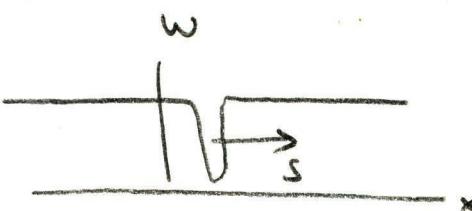
$$s(\omega_e - \omega_r) - \frac{1}{2} (\omega_e^2 - \omega_r^2) = 0 \quad \checkmark$$

$$(\omega_e - \omega_r) \left[s - \frac{1}{2} (\omega_e + \omega_r) \right] = 0 \quad \checkmark$$

$$\Rightarrow \omega_e = \omega_r \quad \text{or} \quad s = \frac{1}{2} (\omega_e + \omega_r)$$

$$\text{If } \omega_e = \omega_r \equiv \bar{\omega}$$

Then the $\psi(t)$ would look like



But this would not correspond to a "wave" shape & so we exclude this possibility.

How show that this is not a possibility otherwise?

$$\therefore S = \frac{1}{2}(\omega_e + \omega_r)$$

$$+ C_1 = \frac{1}{2}(\omega_e + \omega_r)\omega_e - \frac{1}{2}\omega_e^2 = \frac{1}{2}\omega_e\omega_r \quad \checkmark$$

Then our eq becomes

$$E\omega'(\theta) + \frac{1}{2}(\omega_e + \omega_r)\omega(\theta) - \frac{1}{2}\omega^2(\theta) - \frac{1}{2}\omega_e\omega_r = 0 \quad \checkmark$$

$$E\omega(\theta) - \frac{1}{2}(\omega^2(\theta) - (\omega_e + \omega_r)\omega(\theta) + \omega_e\omega_r) = 0 \quad \checkmark$$

$$E\omega'(\theta) - \frac{1}{2}(\omega(\theta) - \omega_e)(\omega(\theta) - \omega_r) = 0 \quad \checkmark$$

$$\frac{dw}{d\theta} = \frac{1}{2E}(\omega - \omega_e)(\omega - \omega_r) \quad \checkmark$$

$$\frac{dw}{(\omega - \omega_e)(\omega - \omega_r)} = \frac{1}{2E} d\theta \quad \checkmark$$

integrate both sides

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$$\frac{1}{2e} \Theta + C_2 = \int \frac{dw}{(w-w_e)(w-w_r)}$$

$$\frac{1}{(w-w_e)(w-w_r)} = \frac{A}{(w-w_e)} + \frac{B}{(w-w_r)}$$

$$A = \frac{1}{w_r - w_e} \quad B = \frac{1}{w_r - w_e} = -\frac{1}{w_r - w_e}$$

$$\Rightarrow \frac{1}{(w-w_e)(w-w_r)} = \frac{1}{(w_r - w_e)(w-w_e)} - \frac{1}{(w_r - w_e)(w-w_r)}$$

$$= \frac{1}{(w_r - w_e)} \left[\frac{1}{(w-w_e)} - \frac{1}{(w-w_r)} \right]$$

$$\text{Then } \int \frac{dw}{x} = \frac{1}{(w_r - w_e)} (\ln(w-w_e) - \ln(w-w_r))$$

$$= \frac{1}{(w_r - w_e)} \ln \left(\frac{|w-w_e|}{|w-w_r|} \right)$$

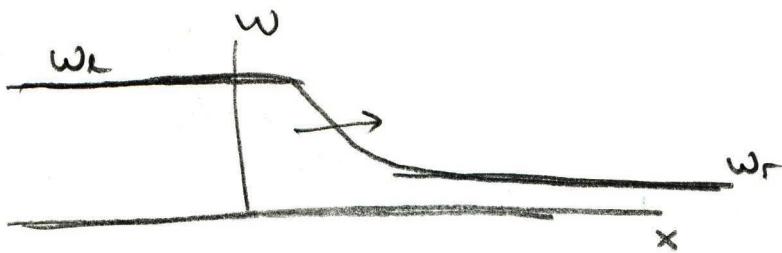
Generally, from the assumed profile solution $w < w_e$
+ $w > w_r$

$$\therefore \ln \left(\frac{|w-w_e|}{|w-w_r|} \right) = (w_r - w_e) \left[\frac{\Theta}{2e} + C_2 \right]$$

let $x \rightarrow -\infty$ $w \rightarrow w_e$ eq $-\infty = -\infty$ ✓ if $w_r - w_e > 0$

$x \rightarrow +\infty$ $w \rightarrow w_r$ eq $+\infty = +\infty$ ✓ if $w_r - w_e > 0$

Assume



$$\text{so } w_L > w_r$$

$$\text{and } w_r \leq w \leq w_L$$

$$\ln\left(\frac{w_L - w}{w - w_r}\right) = (w_L - w_r) \left[\frac{\theta}{2\epsilon} + c_2 \right]$$

$$\frac{w_L - w}{w - w_r} = C_3 \exp\left[\frac{(w_L - w_r)}{2\epsilon} \theta\right]$$

$$w_L - w = (w - w_r) C_3 \exp\left[\frac{(w_L - w_r)}{2\epsilon} \theta\right]$$

$$\left[C_3 \exp[t] + 1 \right] w = w_L + w_r C_3 \exp[t]$$

$$t \equiv \frac{w - w_r}{2\epsilon} \theta$$

$$w = \frac{w_L + w_r C_3 \exp(t)}{1 + C_3 \exp(t)} = w_r + \frac{-w_r(1 + C_3 \exp(t)) + w_L + w_r C_3 \exp(t)}{1 + C_3 \exp(t)}$$

$$w = w_r + \frac{w_L - w_r}{1 + C_3 \exp(t)}$$

$$= w_r + \frac{(w_L - w_r)}{2} \frac{2}{1 + C_3 \exp(t)}$$

$$\omega(\theta \rightarrow -\infty) = \omega_e = \omega_r + \frac{(\omega_e - \omega_r)}{2} \cdot \frac{2}{(1+0)} = \omega_e \checkmark.$$

$$\omega(\theta \rightarrow +\infty) = \omega_r = \omega_r + \frac{(\omega_e - \omega_r)}{2} \left(\frac{1}{\infty} \right) = \omega_r \times$$

Thus c_3 is undetermined pick $c_3 \rightarrow$ how choose otherwise?

$$\begin{aligned}\omega(\theta=0) &= \frac{1}{2}(\omega_e + \omega_r) = \omega_r + \frac{(\omega_e - \omega_r)}{1+c_3} \\ &= \frac{\frac{1}{2}\omega_e + \frac{1}{2}\omega_r - \omega_r}{\omega_e - \omega_r} = \frac{1}{1+c_3} \\ &= \frac{1}{2} = \frac{1}{1+c_3} \Rightarrow c_3 = 1\end{aligned}$$

$$\omega(\theta) = \omega_r + \frac{\omega_e - \omega_r}{2} \cdot \frac{2}{1+\exp(\pm)}$$

$$= \omega_r + \frac{\omega_e - \omega_r}{2} \cdot \frac{2}{1+\exp(\pm)} \cdot \frac{\exp(-\frac{\theta}{2})}{\exp(-\frac{\theta}{2})}$$

$$= \omega_r + \frac{(\omega_e - \omega_r)}{2} \left[\frac{2\exp(-\frac{\theta}{2})}{\exp(-\frac{\theta}{2}) + \exp(\frac{\theta}{2})} \right]$$

$$\tanh(x) = \frac{\sinh(x)}{\cosh(x)} = \frac{e^x - e^{-x}}{e^x + e^{-x}}$$

$$\frac{2e^{-\theta}}{e^{\theta} + e^{-\theta}} = \frac{e^{-\theta} - e^{\theta} + e^{-\theta} + e^{\theta}}{e^{\theta} + e^{-\theta}} = -\frac{(e^{\theta} + e^{-\theta})}{e^{\theta} + e^{-\theta}} + 1$$

$$= -(-\tanh(\theta))$$

$$\text{Thus } \omega(\theta) = \omega_r + \frac{(\omega_e - \omega_r)}{2} \left[1 - \tanh\left(\frac{y}{2}\right) \right]$$

$$= \omega_r + \frac{(\omega_e - \omega_r)}{2} \left[1 - \tanh\left(\frac{\omega_e - \omega_r}{4e} \theta\right) \right]$$

$$\text{if } \theta = x - st = x - \frac{1}{2}(\omega_e + \omega_r)t$$

$$\text{To plot we take } \omega_e = 2 \quad \omega_r = 0 \quad \Rightarrow \quad s = 1$$

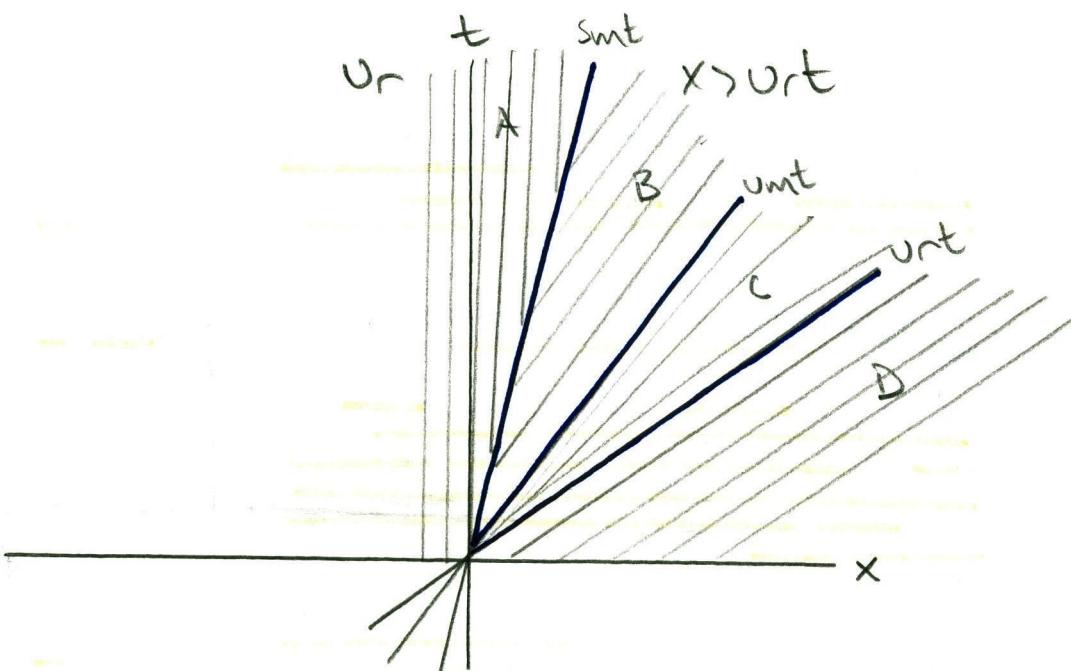
horizontal scale is given by?

Ex 3, b To be a weak solution $u(x,t)$ must satisfy

$$\int_0^{+\infty} \int_{-\infty}^{+\infty} (\phi_t u + \phi_x f(u)) dx dt = - \int_{-\infty}^{\infty} \phi(x,0) u(x,0) dx \quad \checkmark$$

$$\forall \phi(x,t) \in C_0^1(\mathbb{R} \times \mathbb{R}) \quad f(u) = u^2/2$$

let $u(x,t) = \begin{cases} u_L & x < Smt \\ u_M & Smt \leq x \leq Umt \\ x/t & Umt \leq x \leq Urt \end{cases}$

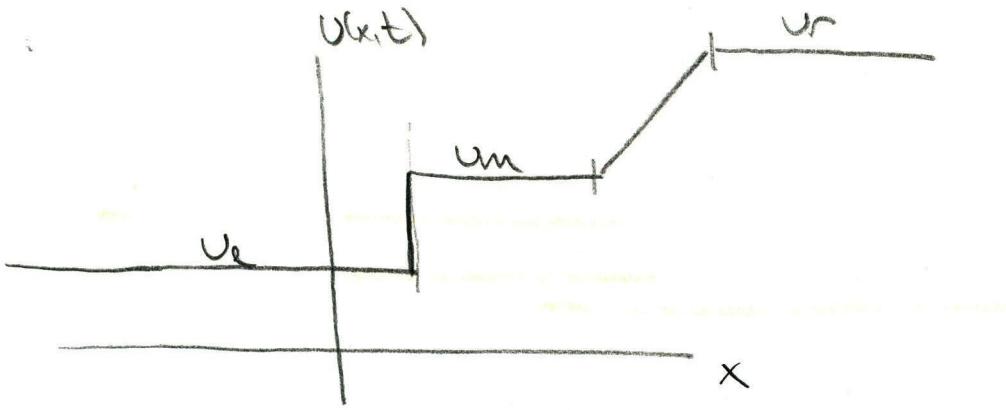


In Region A characteristics are slower than S_m but still positive

B " " " faster than $S_m + 1/2$ to U_m

C Characteristics can be any speed between U_m & U_r respectively

D " " " or $1/2$ to U_r



Then RHS of 3.22 is

$$-u_e \int_{-\infty}^0 \phi(x,0) dx - u_r \int_0^{+\infty} \phi(x,0) dx \quad \text{True + Riemann problem solutions.}$$

Then L.H.S of 3.22 becomes

$$\begin{aligned}
 & \int_0^{+\infty} \left\{ \int_{-\infty}^{Snt} (\phi_t u + \phi_x f(u)) dx + \int_{Snt}^{Umt} (\phi_t u + \phi_x f(u)) dx + \int_{Umt}^{Urt} (\phi_t u + \phi_x f(u)) dx \right. \\
 & \quad \left. + \int_{Urt}^{+\infty} (\phi_t u + \phi_x f(u)) dx \right\} dt \quad \checkmark \\
 = & \int_0^{+\infty} \left\{ \int_{-\infty}^{Snt} (\phi_t u_e + \phi_x f(u_e)) dx + \int_{Snt}^{Umt} (\phi_t u_m + \phi_x f(u_m)) dx + \int_{Umt}^{Urt} (\phi_t(\frac{x}{t}) + \phi_x f(\frac{x}{t})) dx \right. \\
 & \quad \left. + \int_{Urt}^{+\infty} (\phi_t u_r + \phi_x f(u_r)) dx \right\} dt \quad \checkmark
 \end{aligned}$$

$$= \int_0^{+\infty} \left\{ \int_{-\infty}^{Smt} \phi_t u_e dx + \int_{Smt}^{\text{unit}} \phi_E u_m dx + \int_{\text{unit}}^{Urt} \phi_t(x) dx + \int_{Urt}^{+\infty} \phi_U u_r dx \right\} dt$$

$$+ \int_0^{+\infty} \left\{ \int_{-\infty}^{Smt} \phi_x f(u_e) dx + \int_{Smt}^{\text{unit}} \phi_x f(u_m) dx + \int_{\text{unit}}^{Urt} \phi_x f(x/t) dx + \int_{Urt}^{+\infty} \phi_x f(u_r) dx \right\} dt$$

Change limits of integration:

Assuming $S_m, U_m, U_r > 0$

region A_1 , region A_2 , region B , region C

$$\begin{array}{l} -\infty \leq x \leq 0 \\ 0 \leq t \leq +\infty \end{array} \quad \begin{array}{l} 0 \leq x \leq +\infty \\ \frac{x}{S_m} \leq t \leq +\infty \end{array} \quad \begin{array}{l} 0 \leq x \leq +\infty \\ \frac{x}{U_m} \leq t \leq \frac{x}{S_m} \end{array} \quad \begin{array}{l} 0 \leq x \leq +\infty \\ \frac{x}{U_r} \leq t \leq \frac{x}{U_m} \end{array}$$

region D

$$0 < x < +\infty$$

$$0 \leq t \leq \frac{x}{U_r}$$

$$= \int_{-\infty}^0 \int_0^{+\infty} \phi_t u_e dt dx + \int_0^{+\infty} \int_{\frac{x}{S_m}}^{+\infty} \phi_t u_e dt dx$$

$$+ \int_0^{+\infty} \int_{\frac{x}{U_m}}^{\frac{x}{S_m}} \phi_t u_m dt dx$$

$$+ \int_0^{+\infty} \int_{x_{lm}}^{x_{sm}} \phi_t(x/t) dt dx$$

$$+ \int_0^{+\infty} \int_0^{x_{lr}} \phi_t v_r dt dx$$

$$+ \int_0^{+\infty} \left\{ f(v_l) \phi(s_m t, t) + f(u_m) (\phi(u_m t, t) - \phi(s_m t, t)) + \int_{u_m t}^{v_r t} \phi_x f(x/t) dx \right.$$

$$\left. + f(v_r) (-\phi(v_r t, t)) \right\} dt$$

✓

$$= v_l \int_{-\infty}^0 (-\phi(x, 0)) dx + \int_0^{\infty} v_l (-\phi(x, x_{sm})) dx$$

$$+ \int_0^{+\infty} u_m (\phi(x, x_{sm}) - \phi(x, x_{lm})) dx + \int_0^{+\infty} \int_{x_{lm}}^{x_{sm}} \phi_t(x/t) dt dx$$

$$+ \int_0^{+\infty} v_r (\phi(x, x_{lr}) - \phi(x, 0)) dx$$

$$+ f(v_l) \int_0^{+\infty} \phi(s_m t, t) dt + f(u_m) \int_0^{+\infty} \phi(u_m t, t) dt - f(u_m) \int_0^{+\infty} \phi(s_m t, t) dt$$

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$$+ \int_0^{+\infty} \int_{u_{nt}}^{u_{rt}} \phi_x f(x/t) dx dt - f(u_r) \int_0^{+\infty} \phi(u_{rt}, t) dt$$

✓

$$= -v_L \int_{-\infty}^0 \phi(x, 0) dx - v_r \int_0^{+\infty} \phi(x, 0) dx = \text{RHS} \}$$

$$- v_L \int_0^{+\infty} \phi(x, x/s_m) dx + f(v_L) \int_0^{+\infty} \phi(s_m t, t) dt$$

$$+ v_m \int_0^{+\infty} \phi(x, x/s_m) dx - f(v_m) \int_0^{+\infty} \phi(s_m t, t) dt$$

$$- v_m \int_0^{+\infty} \phi(x, x/v_m) dx + f(v_m) \int_0^{+\infty} \phi(v_m t, t) dt$$

$$+ \int_0^{+\infty} \int_{x/v_r}^{x/u_m} \phi_t(x/t) dt dx + \int_0^{+\infty} \int_{u_{nt}}^{u_{rt}} \phi_x f(x/t) dx dt$$

$$+ v_r \int_0^{+\infty} \phi(x, x/v_r) dx - f(v_r) \int_0^{+\infty} \phi(v_r t, t) dt$$

✓

$$= -U_e \int_{-\infty}^0 \phi(x, 0) dx - U_r \int_0^{+\infty} \phi(x, 0) dx$$

$$+ \left(-U_e + \frac{f(U_e)}{S_m} \right) \int_0^{+\infty} \phi(x, x/S_m) dx$$

$$+ \left(U_m - \frac{f(U_m)}{S_m} \right) \int_0^{+\infty} \phi(x, x/S_m) dx$$

$$+ \left(-U_m + \frac{f(U_m)}{U_m} \right) \int_0^{+\infty} \phi(x, x/U_m) dx$$

$$+ \int_0^{+\infty} \int_{x/U_r}^{x/U_m} \phi_t(x/t) dt dx + \int_0^{+\infty} \int_{U_m t}^{U_r t} \phi_{xt}(x/t) dx dt$$

$$+ \left(U_r - \frac{f(U_r)}{U_r} \right) \int_0^{+\infty} \phi(x, x/U_r) dx \quad w \quad f(u) = u^2/2 \quad \checkmark$$

$$= -U_e \int_{-\infty}^0 \phi(x, 0) dx - U_r \int_0^{+\infty} \phi(x, 0) dx$$

$$+ \left(-U_e + \frac{f(U_e)}{S_m} + U_m - \frac{f(U_m)}{S_m} \right) \int_0^{+\infty} \phi(x, x/S_m) dx$$

$$+ \left(-U_m + \frac{U_m}{2} \right) \int_0^{+\infty} \phi(x, x/U_m) dx$$

$$= \int_0^{+\infty} \int_{x_{Ur}}^{x_{Um}} \phi(x_t) dx dt + \int_0^{+\infty} \int_{v_{Ur}}^{v_{Um}} \phi_x f(x_t) dx dt \\ + \frac{v_r}{2} \int_0^{+\infty} \phi(x_r v_r) dx \quad \checkmark$$

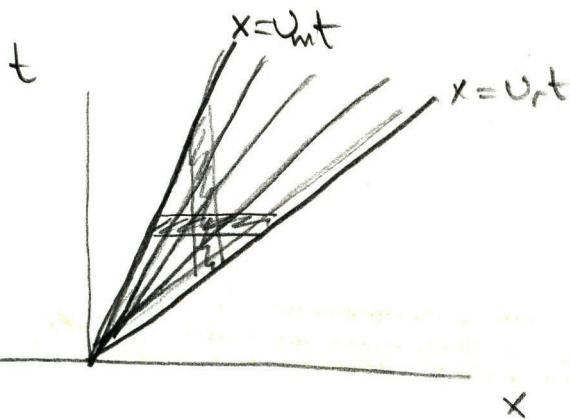
$$= -v_e \int_{-\infty}^0 \phi(x, 0) dx - v_r \int_0^{+\infty} \phi(x, 0) dx \\ \left(v_m - v_e + \frac{1}{2m} (f(v_e) - f(v_m)) \right) \int_0^{+\infty} \phi(x, \frac{v_e - v_m}{2}) dx \\ \underbrace{\frac{2}{(v_e + v_m)} \frac{(v_e^2 - v_m^2)}{2}}$$

$$(v_e + v_m) = 0.$$

$$+ -\frac{v_m}{2} \int_0^{+\infty} \phi(x, \frac{x_{Um}}{v_{Um}}) dx + \int_0^{+\infty} \int_{x_{Ur}}^{x_{Um}} \phi_t f'(x_t) dt dx + \int_0^{+\infty} \int_{v_{Ur}}^{v_{Um}} \phi_x f(x_t) dx dt \\ + \frac{v_r}{2} \int_0^{+\infty} \phi(x, \frac{x_{Ur}}{v_{Ur}}) dx$$

But now lets consider the two integrals





Now

$$\int_0^{+\infty} \int_{x_0r}^{x_0m} \phi_t\left(\frac{x}{t}\right) dt dx + \int_0^{+\infty} \int_{0nt}^{0rt} \phi_x f\left(\frac{x}{t}\right) dx dt$$

Let's change the order of integration
+ see what we get.

* Correctly x integration is done 1st w/ t integration done next

$$0 \leq x \leq +\infty$$

$$x_0r \leq t \leq x_0m$$

$$\Rightarrow \int_0^{+\infty} \int_{x_0r}^{x_0m} \left(\left(\frac{x}{t} \right) \phi_t + \frac{1}{2} \left(\frac{x}{t} \right)^2 \phi_x \right) dt dx \quad \text{How integrate?}$$

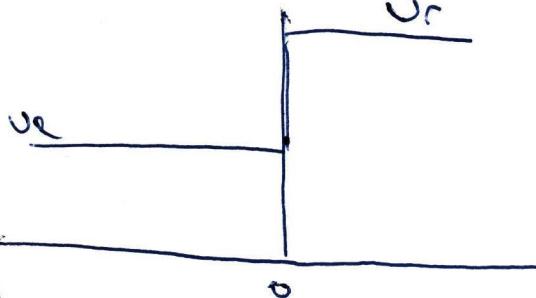
!!

$$\int_{r=0}^{+\infty} \int_{\theta=}$$

Ex 3.7

$$v_t + (f(v))_x \stackrel{\text{LeVeque}}{=} 0 \Rightarrow v_t + f'(v)v_x = 0$$

$$v(x_0) = \begin{cases} v_e & x < 0 \\ v_r & x > 0 \end{cases}$$



(here)

$$\frac{dt}{ds} = 1 \quad \frac{dx}{ds} = f'(v) \quad \frac{dv}{ds} = 0$$

$$t = s + f_0(\xi) \quad x = f(v_0(\xi))s + x_0(\xi) \quad v = v_0(\xi)$$

IC

$$t(\xi) = 0$$

$$x(\xi) = \xi$$

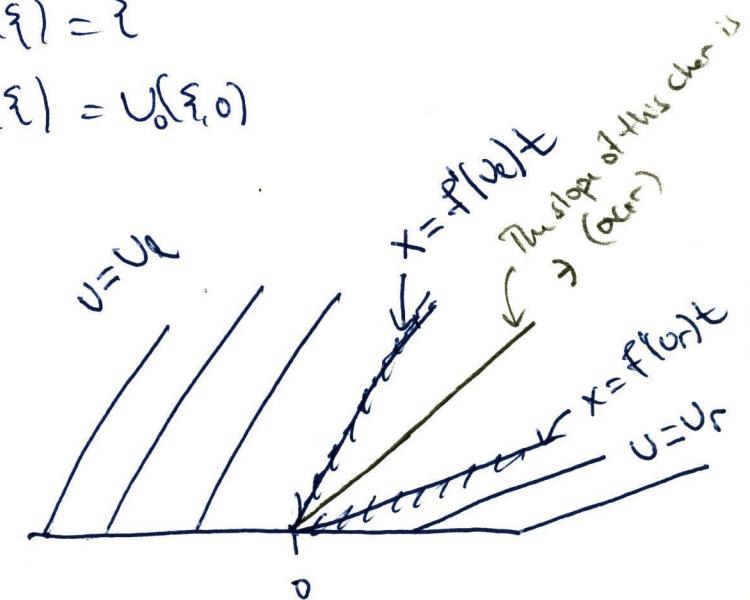
$$v(\xi) = v_0(\xi, 0)$$

$$t = s ; \quad x = f(v_0(\xi))s + \xi ; \quad v = v_0(\xi)$$

$$x = f(v_0(\xi))t + \xi \quad v = v_0(\xi)$$

$$f'' > 0 \Rightarrow f'(v_e) < f'(v_r)$$

$$\frac{1}{f'(v_e)} > \frac{1}{f'(v_r)}$$



In fan region must have characteristic of all slopes

~~f'~~
Pg 291 derivation goes by smoothing initial discontinuity. to get all slopes
from $f'(u_e)$ to $f'(u_r)$.

The slope of characteristic in the fan must be between $f'(u_e) < \frac{d}{dt} < f'(u_r)$

Thus given $v \rightarrow f'(u_e) < f(v) < f'(u_r)$ The value on the characteristic w/ speed $\frac{d}{dt} = f(v)$
will be v .

Pg 31 LeVeque

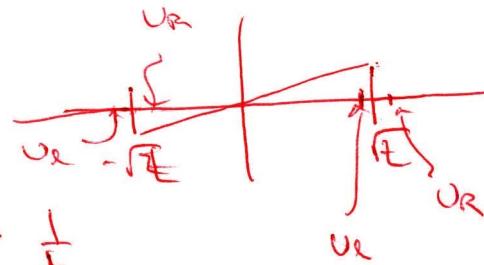
$$\int_{-M}^M v dx = v_e(x) \Big|_{-M}^{st} + v_r(x) \Big|_{st}^M$$

$$= v_e(st + M) + v_r(M - st)$$

Pg 32 Wveque

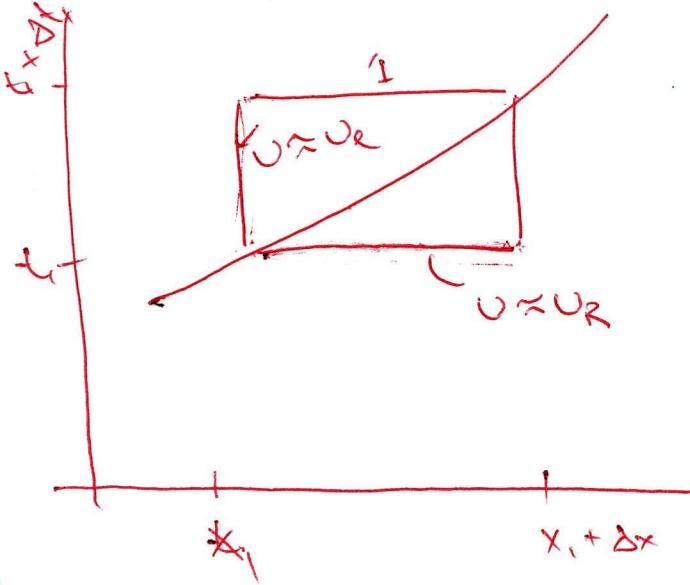
Shock shock speed $s = \frac{[f]}{[v]} = \frac{\frac{1}{2} (f_0^2 - f_e^2)}{v_0 - v_e}$

$$v = \begin{cases} x/t & -\sqrt{t} < x < \sqrt{t} \\ 0 & \text{else} \end{cases}$$



$$\therefore f_0^2 - f_e^2 = \begin{cases} 0 - \left(\frac{x_0}{t}\right)^2 = -\frac{1}{t} \\ \left(\frac{x_0}{t}\right)^2 - 0 = \frac{1}{t} \end{cases}$$

$$\therefore s = \frac{1}{2} \frac{\pm(1/t)}{\frac{1}{t}} = \pm \frac{1}{2}$$



Pj 34 le Vague

3.38 1

$$\Rightarrow \int_{x_i}^{x_i + \Delta x} f(u_e(t)) dt \leq \int_{x_i}^{x_i + \Delta x} f(u_R(t)) dt$$

$$\Rightarrow \int_{x_i}^{x_i + \Delta x} (u_e(t) + O(\Delta t)) dt = \int_{x_i}^{x_i + \Delta x} u_e(t) dt + O(\Delta t)$$

$$+ \int_{t_i}^{t_i + \Delta t} f(u_e(x_i, t)) dt - \int_{t_i}^{t_i + \Delta t} \cancel{f(u_e(x_i, t))} f(u(x_i + \Delta x), t) dt$$

$$\approx f(u_e(t_i) + O(\Delta t), t)$$

$$\approx f(u_R(t_i)) + f(u_R(t_i)) \Delta t_0 + f(u_R, t_i) \Delta t^2 + \dots$$

$$= \int$$

$$v_L \Delta x + O(\Delta t \Delta x) = v_R \Delta x + O(\cancel{\Delta t} \Delta x) + f(v_L) \Delta t$$

2

$$- f(v_R) \Delta t = f(v_R, t_1) \Delta t^2 + \dots$$
$$\approx O(\Delta t^2)$$

\therefore

$$\cancel{\frac{\Delta t}{\Delta x}} \approx s =$$

$$\Delta x \approx s(h) \Delta t + O(\Delta t^2)$$

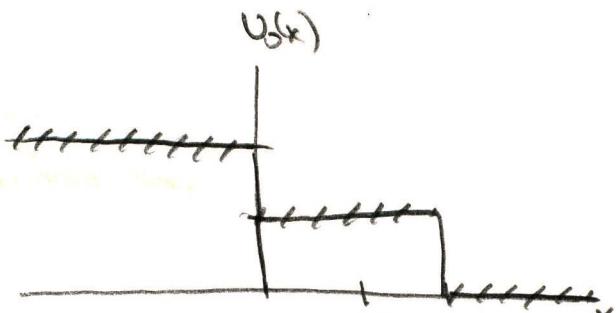
08-4-01

Exrc 3,8

Solice $u_t + uu_x = 0$ w/

$$u(x) = \begin{cases} 2 & x < 0 \\ 1 & 0 < x < 2 \\ 0 & x > 2 \end{cases}$$

Note



$$\frac{du(x(t), t)}{dt} = 0 \quad \text{if} \quad \frac{dx}{dt} = u(x(t), t)$$

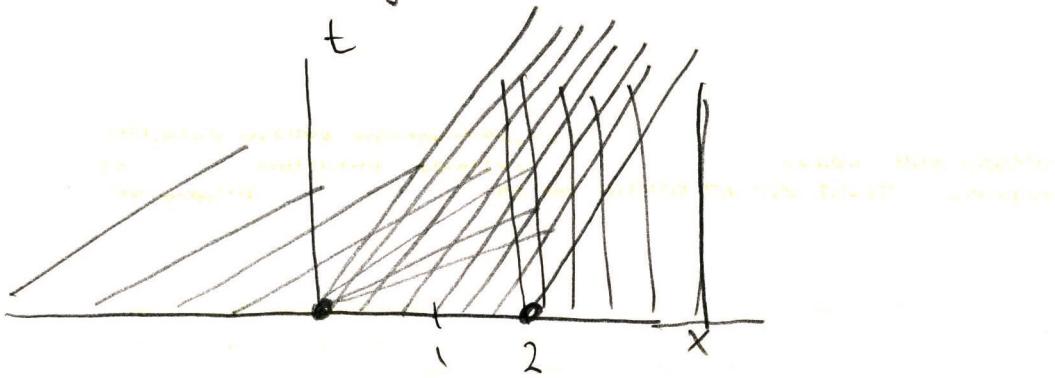
{2 shocks form :}

Both Right going

$$* \Rightarrow \frac{d\bar{x}(0)}{dt} = u_0(\bar{x}(0)) = \begin{cases} 2 & \bar{x}(0) < 0 \\ 1 & 0 < \bar{x}(0) < 2 \\ 0 & \bar{x}(0) > 2 \end{cases}$$

Then $\bar{x}(t) = \begin{cases} 2t + x_0 & x_0 < 2 \\ t + x_0 & 0 < x_0 < 2 \\ x_0 & x_0 > 2 \end{cases}$

Drawn in the x-t diagram then characteristics look like



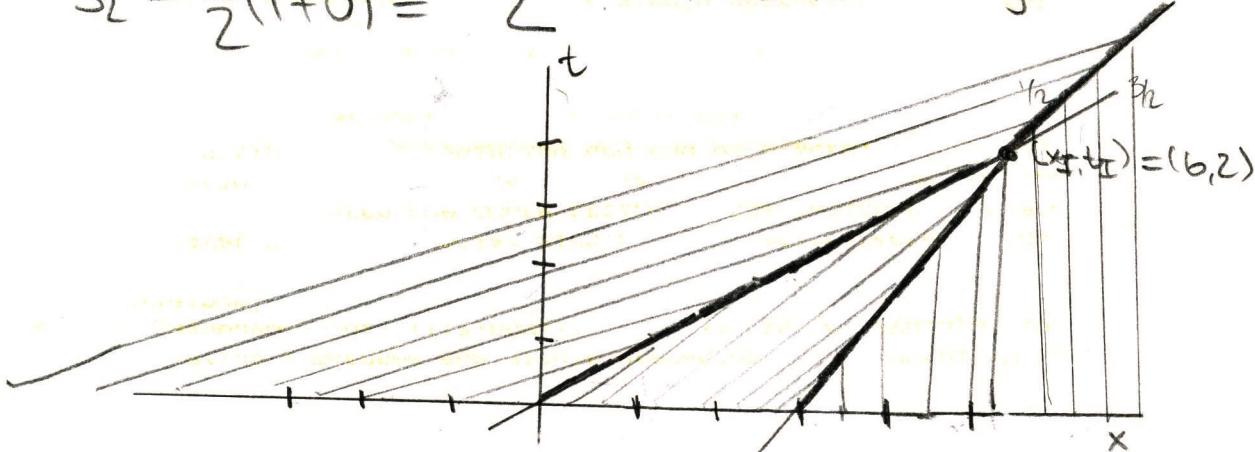
Now this preliminary drawing shows that two shocks form immediately one at $x=0$ + one at $x=2$

Now the 1st shock that starts at $x=0$ has $u=2$ on its back w/ 1 in front of it. Thus the shock speed is

$$S_1 = \frac{1}{2}(1+2) = \frac{3}{2}$$

The 2nd shock starting at $x=2$ begins w/ speed

$$S_2 = \frac{1}{2}(1+0) = \frac{1}{2} \quad \text{Thus the drawing now looks like}$$



Shock intersects at $x = \frac{3}{2}t_1, \quad x_2 = \frac{1}{2}t_2 + 2$

$$\frac{3}{2}t_1 = \frac{1}{2}t_2 + 2 \Rightarrow t_1 = 4$$

$$\therefore x_1 = 6$$

From this point on the shock is fed w/ $v = 2$ from the left & $v = 0$
from the right

$$S_3 = \frac{1}{2}(2+0) = 1$$

Ex 4.1

If $(p_e + p_r) < p_{max}$ & w/ initial condition of $\Rightarrow s > 0$

$$p(x, 0) = \begin{cases} p_e & x < 0 \\ p_r & x > 0 \end{cases}$$

pick $p_r = 0$ & $p_e = \frac{p_{max}}{2}$ Then $s = v_{max}(1 - \frac{1}{2}) = \frac{v_{max}}{2}$ speed of shock

Characteristic speeds are $f'(p_e = \frac{p_{max}}{2}) = v_{max}(1 - \frac{2p_{max}}{2p_{max}}) = 0$

$$f'(p_r = 0) = v_{max}$$

Particle speeds are

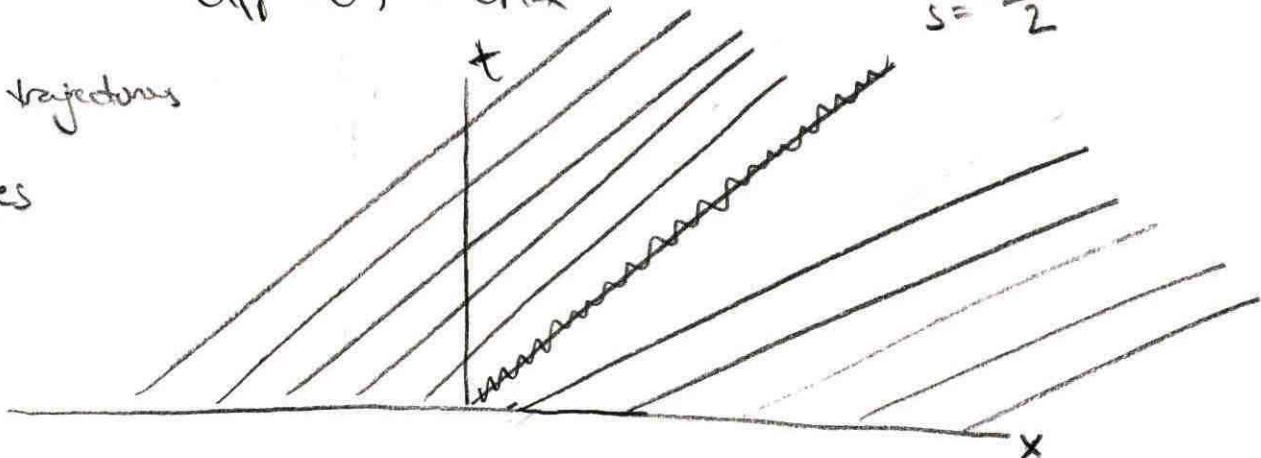
$$v(p_e = \frac{p_{max}}{2}) = v_{max}(1 - \frac{1}{2}) = \frac{v_{max}}{2}$$

$$v(p_r = 0) = v_{max}$$

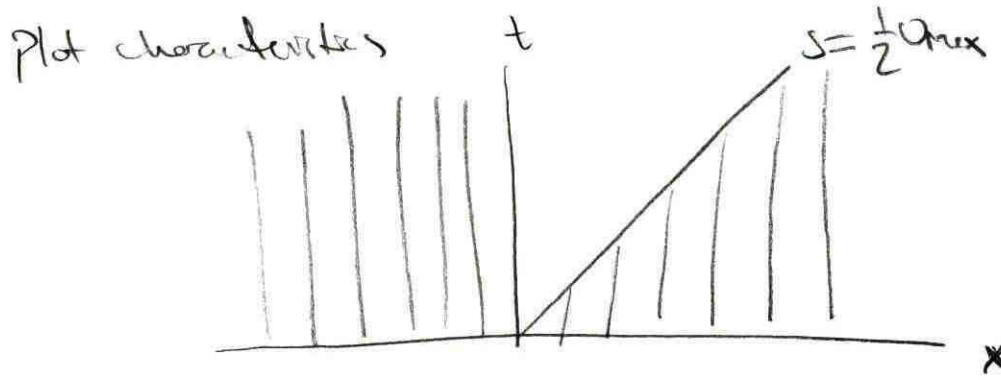
$$s = \frac{v_{max}}{2}$$

Then vehicle trajectories

look like:
plotting velocities



This seems strange. Are you sure this is correct?



The reason for this strange result is that you don't have initial conditions that correspond to a shock. The requirement for a shock is that $P_L < P_r$

Thus we need an initial condition where $P_L + P_r < P_{\max}$

$$\text{pick } P_r = 2P_L \quad \text{Then} \quad 3P_L < P_{\max} \Rightarrow P_L < \frac{P_{\max}}{3}$$

$$\text{pick } P_L = \frac{P_{\max}}{6}, \quad P_r = \frac{P_{\max}}{3}$$

Then particle speeds $v(p) = v_{\max}(1 - p/p_{\max})$

$$v(p_L = \frac{P_{\max}}{6}) = v_{\max}(1 - \frac{1}{6}) = \frac{5}{6} v_{\max}$$

$$v(p_r = \frac{P_{\max}}{3}) = v_{\max}(1 - \frac{1}{3}) = \frac{2}{3} v_{\max} = \frac{4}{6} v_{\max}$$

Then characteristic speeds

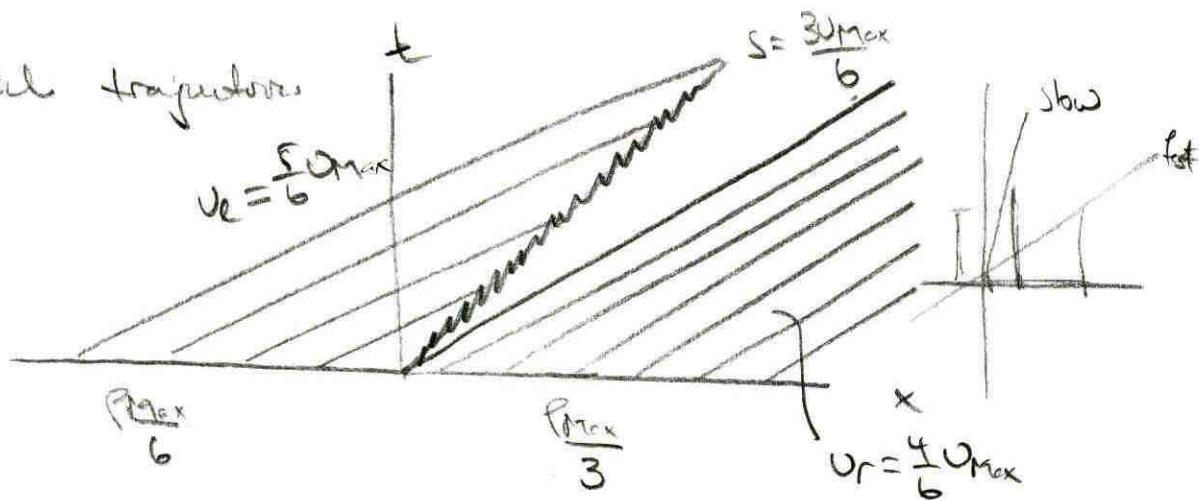
$$c_L = v_{\max}(1 - \frac{2P_{\max}}{6P_{\max}}) = \frac{2}{3} v_{\max} = \frac{4}{6} v_{\max}$$

$$c_r = v_{\max}(1 - \frac{2}{3}) = \frac{1}{3} v_{\max} = \frac{2}{6} v_{\max}$$

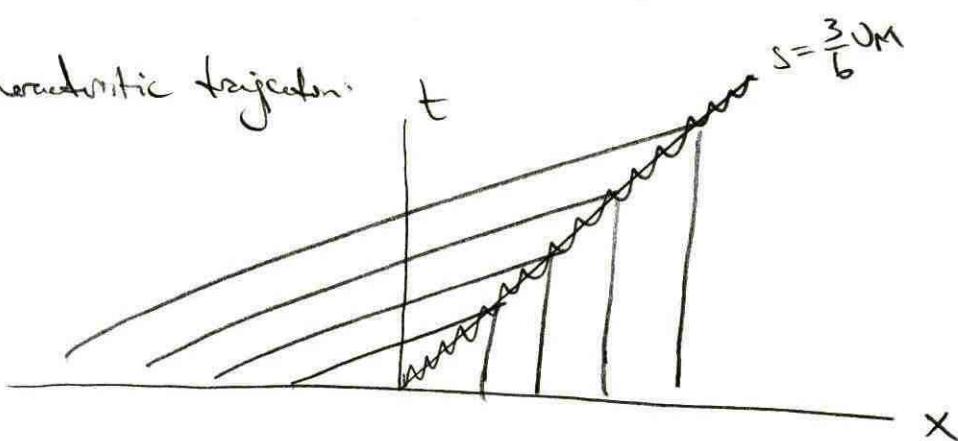
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$$S = V_{\max} \left(1 - \left(\frac{P_{\max} + \frac{2V_{\max}}{6}}{P_{\max}} \right) \right) = V_{\max} \left(1 - \frac{1}{2} \right) = \frac{V_{\max}}{2} = \frac{3V_{\max}}{6}$$

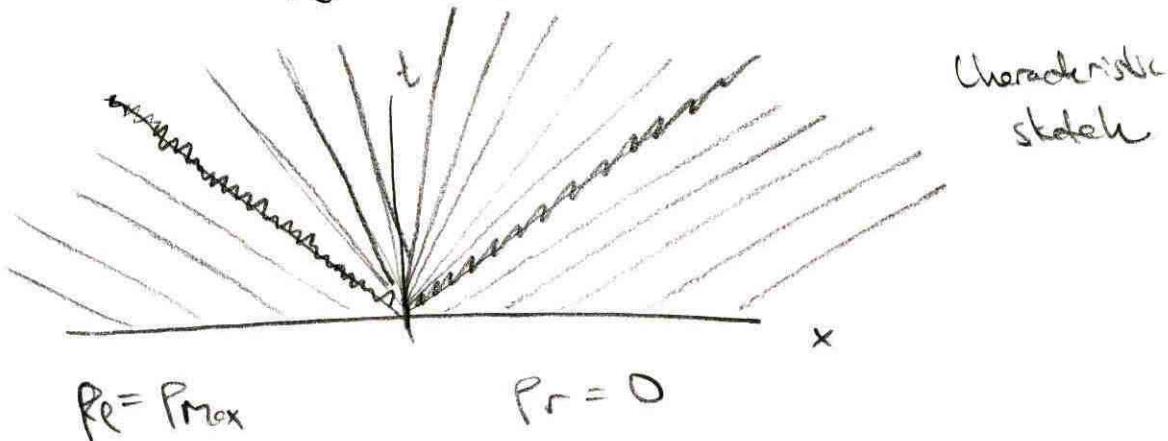
Then pertil trajectories



Then the characteristic trajectory



Ex 4.2



Then since we are dealing w/ scalar equations } one wave (a shock or a rarefaction wave that can propagate from this Riemann problem + separating constant states.

For a shock the requirement of $f(P_e) > s > f'(P_r) \Rightarrow f(P_e) > f'(P_r)$
 $\Leftrightarrow P_e < P_r$ Since this is not satisfied we cannot have a propagating shock. Since we now know that we have a rarefaction fan, the edges will move w/ a spread of the characteristics

$$c_l = U_{\max}(-1) = -U_{\max}$$

$$c_r = U_{\max}$$

Now to find the particle paths know that when $P_e = P_{\max}$

$$U_x = 0 \quad \text{when } P = P_r = 0 \quad U_r = U_{\max}$$

Inside the fan

$$\frac{dx}{dt} = \text{"slope" of chord to characteristic}$$

$$\frac{dx_{\text{path}}}{dt} = v_{\text{perihelion}} = v_{\text{max}} \left(1 - \frac{f}{P_{\text{max}}} \right)$$

Told that $\frac{x}{t} = \text{slope in } x-t \text{ plane} = \text{characteristic speed at}$
 $t \text{ that point.}$

$$= f'(p) = v_{\text{max}} \left(1 - \frac{2f}{P_{\text{max}}} \right)$$

$$\Rightarrow 1 - \left(\frac{x}{t v_{\text{max}}} \right) = \frac{2f}{P_{\text{max}}}$$

$$\frac{f}{P_{\text{max}}} = \frac{1}{2} \left[1 - \left(\frac{x}{t v_{\text{max}}} \right) \right] \text{ pt in place}$$

$$\begin{aligned} \frac{dx}{dt} &= v_{\text{max}} \left[1 - \frac{1}{2} \left[1 - \frac{x}{t v_{\text{max}}} \right] \right] = v_{\text{max}} \left[\frac{1}{2} + \frac{x}{2 t v_{\text{max}}} \right] \\ &= \frac{v_{\text{max}}}{2} \left[1 + \frac{x}{t v_{\text{max}}} \right] \end{aligned}$$

Now given $x_0 < 0$ car does not move until hits edge of

Rectification for at $t = \frac{-x_0}{v_{\text{max}}}$

$$\text{Thus solve } \frac{dx}{dt} = \frac{v_{\text{max}}}{2} + \frac{x}{2t}$$

$$t \frac{dx}{dt} = \frac{v_{\text{max}}}{2} t + \frac{x}{2}$$

$$t \frac{dx}{dt} - \frac{x}{2} = \frac{v_{\text{max}}}{2} t$$

Linear eq for x 1st solve homogeneous then
particular. Homogeneous eq is

$$t \frac{dx}{dt} - \frac{x}{2} = 0$$

$$\text{let } x = Ct^P$$

$$C P t^P + t^{P-1} - \frac{Ct^P}{2} = 0 \Rightarrow P = \frac{1}{2} \Rightarrow x = Ct^{\frac{1}{2}}$$

Alternatively this is a separable eq. Thus now find a particular eq

$$\text{Try } x = C_2 t$$

Sub

$$t C_2 - \frac{C_2 t}{2} = \frac{v_m t}{2}$$

$$\frac{C_2 t}{2} = \frac{v_m t}{2} \Rightarrow C_2 = v_m$$

The solution to this DE is

$$x(t) = Ct^{\frac{1}{2}} + v_{max}$$

$$\text{Initial condition is } x_0 = g\left(\frac{-x_0}{v_{max}}\right)^{\frac{1}{2}} + v_{max}\left(\frac{-x_0}{v_{max}}\right)$$

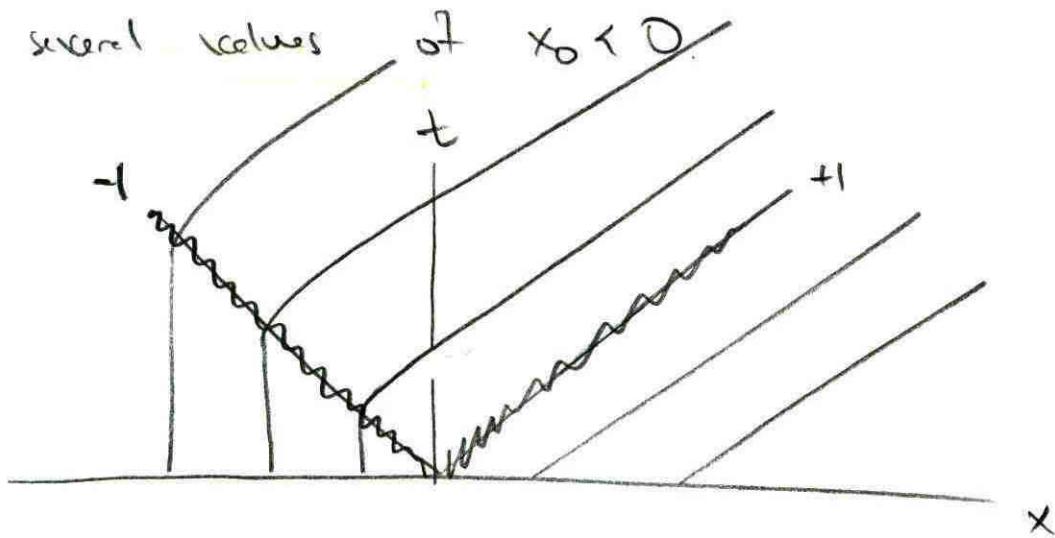
$$2x_0\left(\frac{v_{max}}{-x_0}\right)^{\frac{1}{2}} = g$$

$$\text{Then } x(t) = 2x_0\left(\frac{+v_{max}}{-x_0}\right)^{\frac{1}{2}} t^{\frac{1}{2}} + v_{max} t$$

$$x(t) = v_{max}t + 2x_0 \left(\frac{tv_{max}}{-x_0} \right)^{1/2}$$

As a test I'll look at this path w/ $v_{max} = +1$

for several values of $x_0 < 0$



Check this & plot.

Ex 4.3

$$p(x,t) = p_L = P_{\max} \quad \text{if} \quad x < c_0 t = x < -v_{\max} t$$

$$p(x,t) = p_r = 0 \quad \text{if} \quad x > c_0 t \Rightarrow x > v_{\max} t$$

$$+ p(x,t) = \frac{P_{\max}}{2} \left[1 - \left(\frac{x}{t v_{\max}} \right) \right] \quad -v_{\max} t < x < v_{\max} t$$

Since

$$V(p) = V_{\max} \left(1 - \frac{p}{P_{\max}} \right)$$

$$\begin{aligned} V(x,t) &= V_{\max} \left(1 - \frac{p(x,t)}{P_{\max}} \right) = V_{\max} \left(1 - \frac{1}{2} \left(1 - \left(\frac{x}{t v_{\max}} \right) \right) \right) \\ &= \frac{V_{\max}}{2} \left[1 + \frac{x}{t v_{\max}} \right] \end{aligned}$$

(Ex 4,4)

$$v(t) = \frac{dx_{\text{particle}}(t)}{dt} \quad \text{w/ } x_{\text{particle}}(t) \text{ from Exercise}$$

$$v(t) = v_{\max} + 2x_0 \left(\frac{1}{2}\right) \left(\frac{t v_{\max}}{-x_0}\right)^{-1/2} \left(\frac{v_{\max}}{-x_0}\right)$$

$$= v_{\max} - v_{\max} \left(\frac{t v_{\max}}{-x_0}\right)^{-1/2} = v_{\max} \left(1 - \left(\frac{t v_{\max}}{-x_0}\right)^{1/2}\right)$$

Note: $\lim_{t \rightarrow +\infty} v(t) = v_{\max}$

4.2 + 4.5 cm

$$v(p) = v_{max}(1 - p/p_{max})$$

$$f'(p) = v_{max}(1 - 2p/p_{max})$$

$$\text{Then } C = f'(p_0) - v(p_0)$$

$$= v_{max} - \frac{2v_{max}p_0}{p_{max}} - v_{max} - \frac{v_{max}p_0}{p_{max}}$$

$$= -\frac{v_{max}p_0}{p_{max}} \quad \text{eq 4.14}$$

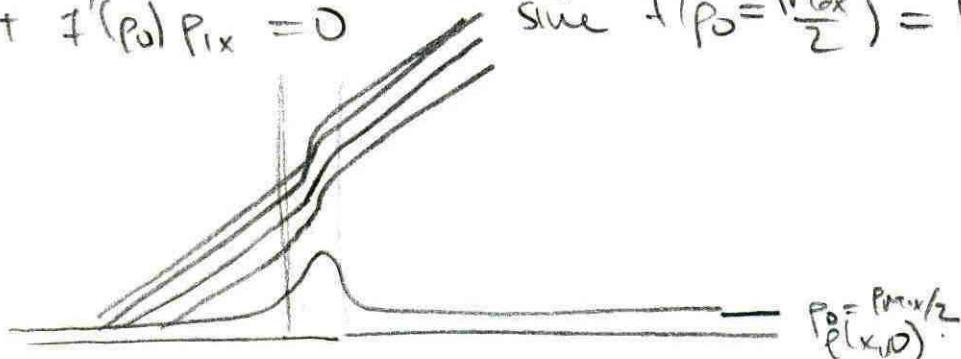
(Ex 4.5)

Information about what is happening propagates backwards

(Ex 4.6)

Small disturbances are governed by

$$p_{it} + f'(p_0)p_{ix} = 0 \quad \text{since } f'(p_0 = \frac{p_{max}}{2}) = 0$$



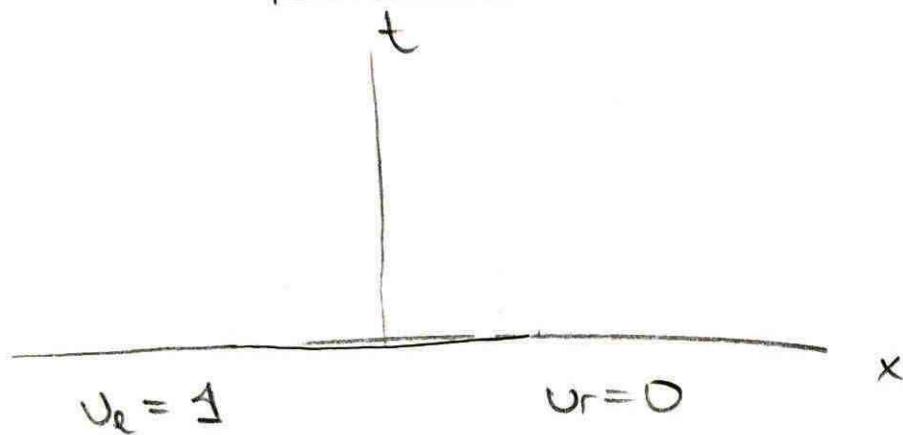
Since $\mathcal{J}'(p_0 = \frac{p_{\text{rank}}}{2}) = 0$ the location of the disturbance
does not move.

Ex 4.7

This is simply Taylor expansion about the average of
the two states $p^* = \frac{1}{2}(p_L + p_R)$

See also Hebermans book. There is an example there also.

(Ex 4.8)



$$f'(v_e)$$

$$f(v) = \frac{v^2}{v^2 + \frac{1}{2}(1-v)^2} = \frac{1}{1 + \frac{1}{2}\left(\frac{1}{v}-1\right)^2}$$

$$f'(v) = \left(1 + \frac{1}{2}\left(\frac{1}{v}-1\right)^2\right)^2 \left(\frac{1}{v}-1\right)^3 \left(-\frac{1}{v^2}\right)$$

$$= -\frac{f(v)}{v^2} \frac{(1-v)^3}{v^3} = -\frac{(1-v)^3}{v^5} f(v)^2$$

$$f'(1) = 0$$

$$f'(0) = 0$$

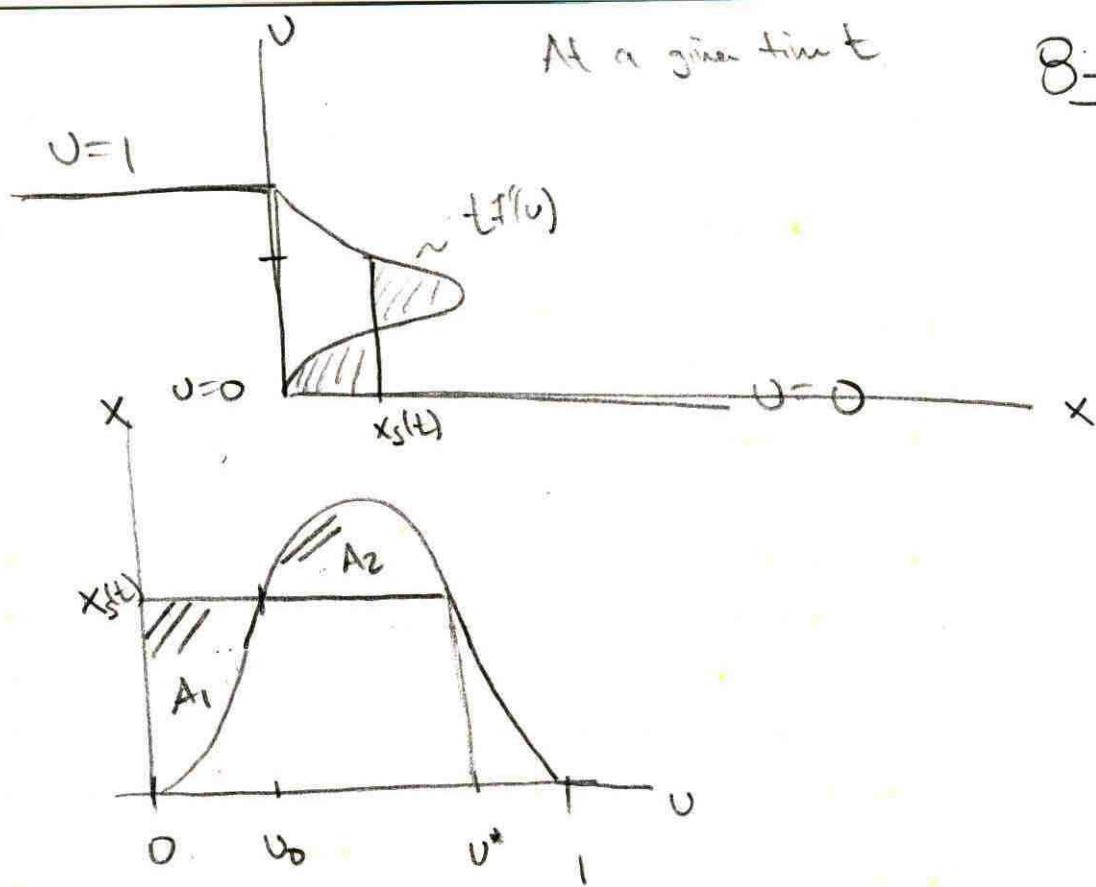
Then for an arbitrary $0 < v < 1$ $f'(v) < 0$

Assuming result from L'Veque that profile of the budget is

$t f'(v)$ turned side ways

At a given time

8-10-01 2



Now if $A_1 = A_2$ then

$$\int_0^{v^*} (x_s(t) - t f'(u)) du = 0$$

$$\Rightarrow x_s(t) v^* - t \int_0^{v^*} f'(u) du = 0$$

$$x_s(t) v^* - t(f(v^*) - 0) = 0$$

$$x_s(t) = \frac{t f(v^*)}{v^*}$$

So that the shock speed $S = \frac{f(v^*) - f(0)}{v^* - 0} = \text{Riemann-Hugoniot}$

We still must derive an equation to determine v^* , how do?

Ex 4.9

When f is convex or concave $f''(v) > 0$

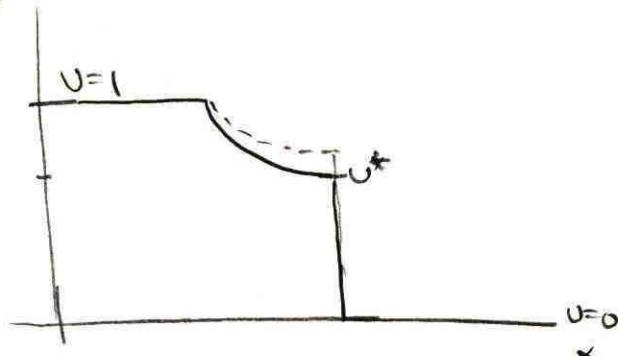
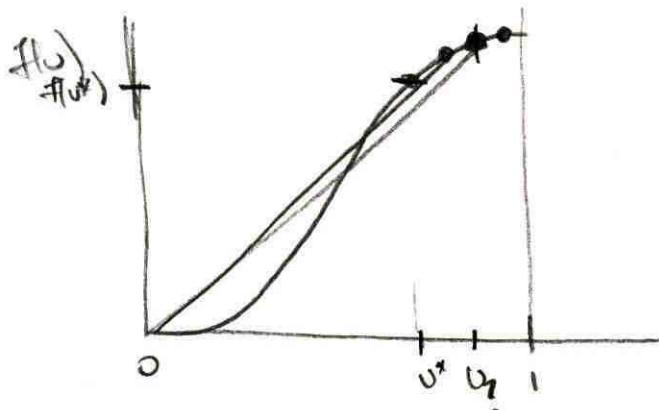
Then send speed is monotone & thus ~~can't~~ it can be inverted uniquely.

Then also the convex hull construction gives either a single line or the function itself. See last statement on pg 50 Lilleque

Ex 4.10

eg 3.46 is

$$\frac{f(v) - f(v_l)}{v - v_l} \geq s \geq \frac{f(v) - f(v_r)}{v - v_r} \quad \text{if } v \text{ between } v_l + v_r$$



If shot goes above v^* Then $v_l = 1$ $v_r = 0$

$$\text{so } \frac{f(v) - f(1)}{v - 1} \stackrel{?}{\geq} s \stackrel{?}{\geq} \frac{f(v) - 0}{v}$$

$$\frac{f(v)}{v-1} \stackrel{?}{\geq} s \stackrel{?}{>} \frac{f(v)}{v}$$

"

this is not satisfied since s is the slope

to point U_2 from 0

+ a point below U_2 w/ f smaller has a greater slope

+ thus $\frac{f(v)}{v} > s \leftrightarrow$

PJ 52 Leveque
from Whitham:

$$\text{If we 1D: } \rho(e_t + u e_x) + p u_x = 0$$

$$\text{Eng: } \rho \frac{de}{dt} + p \frac{\partial u_x}{\partial x} = 0.$$

let $E = \text{total energy} = \text{kinetic} + \text{potential}$

$$"E_t + (\sqrt{E+p})_x = 0" \quad = \frac{1}{2} \rho u^2 + \rho e$$

$$\frac{dp}{dt} + p \nabla \cdot u = 0.$$

$$\text{Then } E_t = \rho_t u^2 + 2 \rho u u_t + \rho e + \rho e_t$$

$$\rho \frac{du_i}{dt} + \frac{\partial p}{\partial x_i} = \rho f_i$$

$$(\sqrt{E+p})_x = \left(\frac{1}{2} \rho u^3 + \rho u e + \rho p \right)_x \quad \text{ID:}$$

\Leftarrow

$$(\rho e)_t - \rho_t e + \rho u e_x + p u_x = 0$$

$$\begin{cases} \rho_t + u p_x + p u_x = 0 \\ \rho u_t + \rho u u_x + p_x = 0. \end{cases}$$

Take $\frac{d}{dt}$ of E_t \Rightarrow

$$\frac{d}{dt}$$

$$\Rightarrow \left(E - \frac{1}{2} \rho u^2 \right)_t - \rho_t e + \rho u e_x + p u_x \parallel$$

\parallel

$$(p u)_x - p_x u = 0.$$

$$E_t - \frac{1}{2} \rho_t u^2 - \frac{1}{2} \rho u u_t - \rho_t e + \rho u e_x + (p u)_x - p_x u = 0.$$

$$-\left(\frac{1}{2} u^2 + e \right) \rho_t - u(p u_t) + \rho u e_x - p_x u + (p u)_x = 0.$$

$\parallel \text{MASS}$

$$(u p_x - p u_x)$$

~~THEOREM~~

Start w/ eq: $p_{et} + p_{ue} + p_{ux} = 0$

$$\Rightarrow (pe)_t - p_t e + v((fe)_x - p_x e) + (pu)_x - p_x u = 0$$

After ~~pe~~ & ~~fe~~

$$(pe)_t + (upe)_x - v_x fe \xrightarrow{+ (pu)_x = 0} -p_t e - v p_x e - p_x u$$

let $pe = E - \frac{1}{2}pv^2$

$$\Rightarrow E_t - \left(\frac{1}{2}pv^2\right)_t + (vE)_x + (pu)_x - \left(\frac{1}{2}pv^3\right)_x - v_x pe - p_t e - v p_x e - p_x u = 0.$$

$$\Rightarrow E_t + (v(E+p))_x = \left(\frac{1}{2}pv^2\right)_t + p_t e + \left(\frac{1}{2}pv^3\right)_x + v_x pe + v_x e + p_x u$$

3 - terms vanish by cons of mass

$$\Rightarrow E_t + (v(E+p))_x = \frac{1}{2}v^2 p_t + \frac{1}{2}v^2 (pu)_x + vu_p + \frac{1}{2}pv^2 vu_x$$

$$+ p_x u$$

$$= 0$$

1st 2 terms. By cons. of mass.

$$E_t + (v(E+P))_x = v(pv_t + puu_x + P_x) = 0$$

By cons of MCL.

Derive jump conditions for gas dynamics
Pg 54 Leveque

From Leveque + show consistent w/ 10.3c Corrie

i.e.

$$\frac{1}{2} u_1^2 + \frac{\gamma}{\gamma-1} \frac{P_1}{P_1} = \frac{1}{2} u_2^2 + \frac{\gamma}{\gamma-1} \frac{P_2}{P_2}$$

Consider leveque conservation eqs

$$p_t + (pu)_x = 0$$

$$(pu)_x + (pu^2 + p)_x = 0$$

$$E_t + (u(E+p))_x = 0$$

Now: jump conditions relative to stationary shock

as

$$p_1 u_1 = p_2 u_2$$

y same as corrie

$$p_1 u_1^2 + p_1 = p_2 u_2^2 + p_2$$

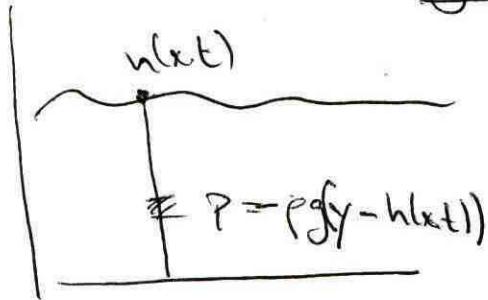
$$u_1(E_1 + p_1) = u_2(E_2 + p_2)$$



$$u_1 \sqrt{\gamma} \left(\frac{E_1}{p_1} + \frac{p_1}{p_1} \right) = u_2 \sqrt{\gamma} \left(\frac{E_2}{p_2} + \frac{p_2}{p_2} \right) \quad \text{By Ross}$$

$$\therefore \left(e_1 + \frac{1}{2} u_1^2 + \frac{p_1}{p_1} \right) = e_2 + \frac{1}{2} u_2^2 + \frac{p_2}{p_2}$$

$$e_1 + \frac{p_1}{p_1} = \frac{1}{r-1} \frac{p_1}{p_1} + \frac{p_1}{p_1} = \frac{r}{r-1} \frac{p_1}{p_1} \quad \checkmark$$



$$-\rho g \int_0^{u(x,t)} (y - h) dy = -\rho g \left(\frac{y^2}{2} - hy \right) \Big|_0^h = -\rho g \left(-\frac{h^2}{2} \right) = \frac{h^2 \rho g}{2}$$

$$\Rightarrow \therefore b \quad p$$

$$(hv)_t + \left(hv^2 + \frac{h^2 g}{2}\right)_x = 0$$

$$hv_t + v_h + \cancel{h_x v^2} + \cancel{2vv_x h} + \cancel{hh_x g} = 0$$

|| By mass

$$(-v_x h - \cancel{h_x v})_v + \dots$$

$$\Rightarrow v_h + vv_x h + \cancel{hh_x} = 0.$$

$$v_t + \left(\frac{v^2}{2} + gh\right)_x = 0. \quad + \text{mass} \quad h_t + (vh)_x = 0.$$

$$\phi = gh$$

$$\Rightarrow (gh)_t + (vh)_x = 0$$

$$\Rightarrow \left(v\right)_t + \left(\frac{v^2}{2} + \phi\right)_x = 0.$$

Pg 60 Lebesgue

$$V = R^{-1}v$$

$$V(x, 0) = R^{-1}v_0(x)$$

get $v_p(x, 0)$ $p = 1, 2, \dots, m.$

$$v(x, t) = \sum_{p=1}^m v_p(x - \lambda_p t, 0) r_p = \sum_{p \neq i} c_p r_p + v_i(x - \lambda_i t, 0) r_i$$

$$= R \left(\begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right) = R \bar{v}(x - \lambda_i t)$$

$$\bar{v} \rightarrow \bar{v} = c_p \quad p \neq i \\ v_i \quad p = i$$

$$= v_0(x - \lambda_i t)$$

Ex 6.1

Pg 61 LeVeque

$$\text{eval } A = \pm c$$

$$\begin{pmatrix} 0 & -1 \\ -c^2 & 0 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \pm c \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$$

$$-v_2 = cv_1$$

vector $\vec{v} = \begin{pmatrix} 1 \\ -c \end{pmatrix}$

$$-c^2 v_1 = cv_2$$

$$\begin{pmatrix} 0 & -1 \\ -c^2 & 0 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = -c \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \quad \text{vector } \vec{v} = \begin{pmatrix} 1 \\ +c \end{pmatrix}$$

$$\text{let } R = \frac{1}{\sqrt{1+c^2}} \begin{pmatrix} 1 & 1 \\ c & -c \end{pmatrix}; \quad R^{-1} = \frac{\sqrt{1+c^2}}{2} \begin{pmatrix} 1 & c \\ 1 & -c \end{pmatrix}$$

$$\text{check } A = \begin{pmatrix} -c & 0 \\ 0 & c \end{pmatrix} = R^{-1} A R = \frac{1}{2} \begin{pmatrix} 1 & c \\ 1 & -c \end{pmatrix} \begin{pmatrix} 0 & -1 \\ -c^2 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ c & -c \end{pmatrix} \quad \checkmark$$

$$\text{Thus let } \mathbf{v} = R^{-1}\mathbf{u} \quad \mathbf{v}_t + A\mathbf{v}_x = \mathbf{0}$$

$$A\mathbf{R}\mathbf{R}^{-1}\mathbf{u}_x = \mathbf{0}$$

Then system becomes =

$$\mathbf{v}_t + \lambda \mathbf{v}_x = \mathbf{0}$$

or $\mathbf{v}_{1t} - c \mathbf{v}_{1x} = \mathbf{0} \Rightarrow \mathbf{v}_1(x,t) = \mathbf{v}_1^0(x+ct)$

+ $\mathbf{v}_{2t} + c \mathbf{v}_{2x} = \mathbf{0} \Rightarrow \mathbf{v}_2(x,t) = \mathbf{v}_2^0(x-ct)$

get the $\mathbf{v}_1^0 + \mathbf{v}_2^0 \quad \bar{\mathbf{v}}^0 = R^{-1}\bar{\mathbf{v}}^0 = R^{-1} \begin{pmatrix} v_0'(x) \\ v_1(x) \end{pmatrix}$

$$\begin{pmatrix} \mathbf{v}_1^0 \\ \mathbf{v}_2^0 \end{pmatrix} = \frac{\sqrt{1+c^2}}{2} \begin{pmatrix} v_0'(x) + \frac{v_1(x)}{c} \\ v_0'(x) - \frac{v_1(x)}{c} \end{pmatrix}$$

Thus $\mathbf{v}_1(x,t) = \frac{\sqrt{1+c^2}}{2} (v_0'(x+ct) + \frac{1}{c} v_1(x+ct))$
 $\mathbf{v}_2(x,t) = \frac{\sqrt{1+c^2}}{2} (v_0'(x-ct) - \frac{1}{c} v_1(x-ct))$

$$\text{Now: } v(x,t) = Rv(x,t)$$

$$\begin{aligned} &= \begin{pmatrix} v(x,t) \\ w(x,t) \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ c & -c \end{pmatrix} \begin{pmatrix} v_0'(x+ct) + \frac{1}{c} v_1(x+ct) \\ v_0'(x-ct) - \frac{1}{c} v_1(x-ct) \end{pmatrix} \\ &= \frac{1}{2} \begin{pmatrix} v_0'(x_1) + v_0'(x_2) + \frac{1}{c} (v_1(x_1) - v_1(x_2)) \\ cv_0'(x_1) - cv_0'(x_2) + v_1(x_1) + v_1(x_2) \end{pmatrix} \end{aligned}$$

$$\text{Then } v_x = v = \frac{1}{2} \left(\dots \right)$$

$$w_x = w = \frac{1}{2} \left(\dots \right)$$

$$v = \frac{1}{2} \left[\int (v_0'(x+ct) + v_0'(x-ct)) dx + \frac{1}{c} \int (v_1(x+ct) - v_1(x-ct)) dx \right]$$

$$v = x+ct$$

$$dv = dx$$

$$+ C(t)$$

$$= \frac{1}{2} \left[v_0(x+ct) + v_0(x-ct) + \frac{1}{2} \left(\int (v_1(x+ct) - v_1(x-ct)) dx \right) \right] \Big|_{x=c(t)}$$

Then

↓ see back of the page for better explanation.

$$u_t = \frac{1}{2} [c u_0'(x+ct) - c u_0'(x-ct) + \frac{1}{2} (x u_0(x+ct) + x u_0(x-ct))] \\ + C(t)$$

$$\equiv w(x,t) \quad \text{if } C(t) = 0$$

$$\Rightarrow C(t) = \text{const and } \int$$

Ex 6.2

Pg 61 L-Vequs

$$v_t = v_{xt} = \phi_x$$

$$w_t = \phi_y$$

$$\phi_t = c^2(v_x + w_y)$$

$$\therefore \begin{pmatrix} v \\ w \\ \phi \end{pmatrix}_t + \begin{pmatrix} -\phi \\ 0 \\ -c^2 v \end{pmatrix}_x + \begin{pmatrix} 0 \\ -\phi \\ -c^2 w \end{pmatrix}_y = 0$$

$$\begin{pmatrix} v \\ w \\ \phi \end{pmatrix}_t + \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ -c^2 & 0 & 0 \end{pmatrix} \begin{pmatrix} v \\ w \\ \phi \end{pmatrix}_x + \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -c^2 & 0 \end{pmatrix} \begin{pmatrix} v \\ w \\ \phi \end{pmatrix}_y = 0$$

Ex 6.3

Assume

$$\begin{pmatrix} U \\ \phi \end{pmatrix}^0 = \begin{pmatrix} U_0(x) \\ \phi_0(x) \end{pmatrix}$$

Pg 61 b) Vague

Introduce char var $\begin{pmatrix} 0 & 1 \\ \phi & 0 \end{pmatrix} \rightarrow$ e.values. $\left\{ \bar{U} - \sqrt{\Phi}, \bar{U} + \sqrt{\Phi} \right\}$

$$\Lambda = \begin{pmatrix} \bar{U} - \sqrt{\Phi} & 0 \\ 0 & \bar{U} + \sqrt{\Phi} \end{pmatrix}$$

$$R = \frac{1}{\sqrt{1 + \frac{1}{\Phi}}} \begin{pmatrix} \frac{-1}{\sqrt{\Phi}} & \frac{1}{\sqrt{\Phi}} \\ -1 & 1 \end{pmatrix} \quad \text{vec}$$

$$R^{-1} = \frac{\sqrt{1 + \frac{1}{\Phi}}}{2} \begin{pmatrix} -\sqrt{\Phi} & 1 \\ \sqrt{\Phi} & 1 \end{pmatrix}$$

Define. $v = R^{-1} u$. Then eq for $v_1 + v_2$ decouple

$$\text{To become: } \partial_t v_1 + (\bar{v} - \sqrt{\Phi}) \partial_x v_1 = 0$$

$$\partial_t v_2 + (\bar{v} + \sqrt{\Phi}) \partial_x v_2 = 0$$

w/ initial fns of: $\begin{pmatrix} v_1^0 \\ v_2^0 \end{pmatrix} = \frac{\sqrt{1+\sqrt{\Phi}}}{2} \begin{pmatrix} -\sqrt{\Phi} v_0(x) + \phi_0(x) \\ \sqrt{\Phi} v_0(x) + \phi_0(x) \end{pmatrix}$

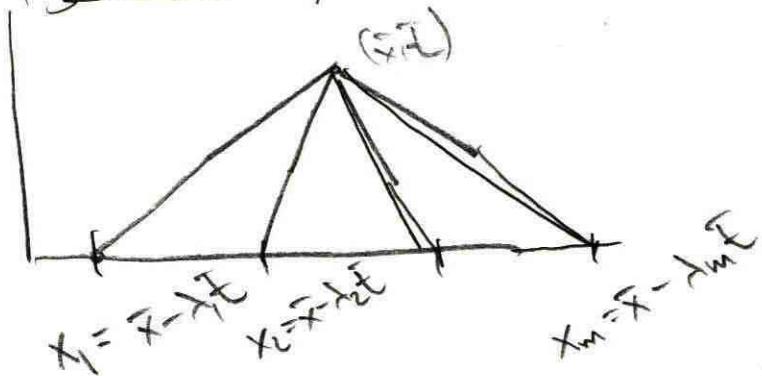
$$\therefore v_1(x,t) = \frac{\sqrt{1+\sqrt{\Phi}}}{2} \left(-\sqrt{\Phi} v_0(x - (\bar{v} - \sqrt{\Phi})t) + \phi_0(x - (\bar{v} - \sqrt{\Phi})t) \right)$$

$$v_2(x,t) = \frac{\sqrt{1+\sqrt{\Phi}}}{2} \left(\sqrt{\Phi} v_0(x - (\bar{v} + \sqrt{\Phi})t) + \phi_0(x - (\bar{v} + \sqrt{\Phi})t) \right)$$

Then $\mathcal{D} = \begin{pmatrix} U(x,t) \\ \phi(x,t) \end{pmatrix} = R \begin{pmatrix} v_1(x,t) \\ v_2(x,t) \end{pmatrix} =$

$$= \frac{1}{2} \left(\begin{pmatrix} v_0(x_1) + v_0(x_2) - \frac{1}{\sqrt{\Phi}} \phi_0(x_1) + \frac{1}{\sqrt{\Phi}} \phi_0(x_2) \\ -\sqrt{\Phi} v_0(x_1) + \sqrt{\Phi} v_0(x_2) + \phi_0(x_1) + \phi_0(x_2) \end{pmatrix} \right)$$

Pg 61 LeVeque



If f is smooth at $\{x_1, \dots, x_m\}$ so will be

smooth at $(\bar{x}, f(\bar{x}))$

$$\rho, P, V, E = E(\rho, P)$$

Pg 63. LeVeque

$$E = \frac{P}{r-1} + \frac{1}{2} PV^2$$

$$\bar{\eta} = \begin{pmatrix} \rho \\ VP \\ E \end{pmatrix} \text{ state for polytropic gas.}$$

$$\begin{aligned} f(v) &= \begin{pmatrix} Pv \\ Pv^2 + P \\ V(E + P) \end{pmatrix} \\ &= \begin{pmatrix} v_2 \\ v_2/v_1 + P(v) \\ \frac{v_2}{v_1}(v_3 + P(v)) \end{pmatrix} \end{aligned}$$

$$f' = \begin{pmatrix} 0 & 1 & 0 \\ -\frac{v_2^2}{v_1^2} + \frac{\partial P}{\partial v_1} & \frac{2v_2}{v_1} + \frac{\partial P}{\partial v_2} & \frac{\partial P}{\partial v_3} \\ -\frac{v_2}{v_1^2}(v_3 + Pv) & \frac{v_3 + Pv}{v_1} & \frac{v_2}{v_1}(1 + \frac{\partial P}{\partial v_3}) \\ + \frac{v_2}{v_1} \left(\frac{\partial P}{\partial v_1} \right) & + \frac{v_2}{v_1} \left(\frac{\partial P}{\partial v_2} \right) & \end{pmatrix}$$

$\frac{\partial P}{\partial v_1} = ?$ get using eq of state:

$$E = \frac{P}{r-1} + \frac{1}{2} \rho v^2$$

$$\Rightarrow P = (r-1) \left(v_3 - \frac{1}{2} \frac{v_2^2}{v_1} \right)$$

$$\frac{\partial P}{\partial v_1} = (r-1) \left(\frac{1}{2} \frac{v_2^2}{v_1^2} \right)$$

$$\frac{\partial P}{\partial v_2} = (r-1) \left(-\frac{v_2}{v_1} \right); \quad \frac{\partial P}{\partial v_3} = (r-1)$$

$$\therefore f'(v) = \begin{pmatrix} 0 & 1 & 0 \\ -v^2 + \frac{1}{2}(r-1)v^2 & 2v - (r-1)v & (r-1) \\ (r-1)\frac{v^2}{2} & (3-r)v & \end{pmatrix}$$

$$(F'(v))_{31} = -\frac{v}{p}(E+p) + v\left(-\frac{1}{2}(r-1)v^2\right)$$

$$= \frac{(r-1)}{2}v^3 - \frac{(E+p)v}{p} \quad \checkmark$$

$$(F'(v))_{32} = \underbrace{\frac{(E+p)}{p}}_{r} - v^2(r-1) \quad \checkmark$$

$$(F'(v))_{33} = v(1+r-1) = rv \quad \checkmark$$

entering 6.30 into Ma + Asking for eigenvalues gives

$$\sqrt{v}, \sqrt{v} \pm \sqrt{(r-1)p(2e+2p-v^2p)}$$

putting e in gives

$$\sqrt{v}, \sqrt{v} \pm \sqrt{rp} \quad \text{As claimed!!}$$

$$\begin{aligned} E &= \omega p \approx pe \\ E/p &\approx \omega_e \approx e \end{aligned}$$

$$\text{Eq 6.4} \quad \rho(x,t) = \hat{\rho}(x - vt)$$

$$v = v'$$

$$\rho = \hat{\rho}$$

Pg 63 LeVeque

Euler eq 5.6.

$$\left(\begin{array}{c} \rho \\ \rho v \\ E \end{array} \right)_t + \left(\begin{array}{c} \rho v \\ \rho v^2 + p \\ v(E + p) \end{array} \right)_x = 0$$

$$\Rightarrow -\bar{v} \partial_{\xi} \hat{\rho}(\xi) + \partial_{\xi} \hat{\rho}(-\bar{v}) = 0 \quad \checkmark$$

~~$$\bullet \bullet \star -\bar{v} \partial_{\xi} \hat{\rho}(-\bar{v}) + \bar{v}^2 \partial_{\xi} \hat{\rho} + 0 = 0 \quad \checkmark.$$~~

$$+ \partial_t E + \bar{v} \partial_x E = 0 \quad ??$$

E_t 6.4

Pg 63 L'Veque

$$\hat{P} = \hat{K} \hat{\rho}^r (x - vt)$$

1D Euler energy eq : $E_t + (v(E + p))_x = 0$

But for polytropic gas $E = \frac{P}{r-1} + \frac{1}{2} \rho v^2$

$$= \frac{\bar{P}}{r-1} + \frac{1}{2} \hat{\rho}(x-vt) v^2$$

$$\therefore \partial_t E = -\frac{1}{2} \partial_t \hat{\rho} v^3$$

$$v(E + p) = v \left(\left(\frac{\bar{P}}{r-1} + \frac{1}{2} \hat{\rho}(x-vt) v^2 \right) + \bar{P} \right)$$

$$\therefore \partial_x \downarrow = \frac{1}{2} \partial_x \hat{\rho} v^3 \quad \checkmark$$

2

(3)

isentropic? No if so then $P = \rho r$
at same t but ρ is a constant & r is not
depends on $x - vt$.

Ex 6.5

Pg 64 LaVague

$$\begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} r \\ s \\ t \end{pmatrix}$$

$$v_{1t} + v_{2x} = 0$$

$$v_{2t} + \left(\frac{v_2^2}{v_1} + p(v_1, v_3) \right)_x = 0$$

$$v_{3t} + \frac{v_2}{v_1} v_{3x} = 0$$

Assume $v_1 = \bar{v}_1 + u(x,t)$

$$v_2 = \bar{v}_2 + v(x,t)$$

$$v_3 = \bar{v}_3 + w(x,t)$$

$$\frac{v_2^2}{v_1} = \frac{\bar{v}_2^2 + 2\bar{v}_2 v + v^2}{\bar{v}_1 + v}$$

$$\approx \frac{1}{\bar{v}_1} \left(1 - \frac{v}{\bar{v}_1} \right) (\bar{v}_2^2 + 2\bar{v}_2 v + v^2)$$

$$\frac{v_2}{v_1} \approx \frac{1}{\bar{v}_1} \left(1 - \frac{v}{\bar{v}_1} \right) (\bar{v}_2 + v)$$

$$\rightarrow \frac{\bar{v}_2}{\bar{v}_1} \quad \text{only order term needed.}$$

$$\left(\frac{v^2}{v_1}\right)_x = \left(\frac{1}{v_1}(2\bar{v}_2 v - \frac{\bar{v}_2^2}{v_1} v)\right)_x = \frac{1}{v_1}(2\bar{v}_2 v_x - \frac{\bar{v}_2^2}{v_1} v_x)$$

$$P(v_1, v_3) \approx P(\bar{v}_1, \bar{v}_3) + \frac{\partial P}{\partial \bar{v}}|_{\bar{v}} (\bar{v}_1, \bar{v}_3) v + \frac{\partial P}{\partial \bar{v}}|_{\bar{v}} (\bar{v}_1, \bar{v}_3) w + \alpha(v \cdot w)$$

$$\partial_x P \approx \frac{\partial P}{\partial \bar{v}}|_{\bar{v}} v_x + \frac{\partial P}{\partial \bar{v}}|_{\bar{v}} w_x$$

Putting everything together get

$$v_t + v_x = 0$$

$$v_t + 2\frac{\bar{v}_2}{v_1} v_x - \frac{\bar{v}_2^2}{v_1^2} v_x + \frac{\partial P}{\partial \bar{v}}|_{\bar{v}} v_x + \frac{\partial P}{\partial \bar{v}}|_{\bar{v}} w_x = 0$$

$$w_t + \frac{\bar{v}_2}{v_1} w_x = 0$$

or:

$$\begin{pmatrix} v \\ \dot{v} \\ w \end{pmatrix}_t + \begin{pmatrix} 0 & 1 & 0 \\ -\frac{\bar{v}_2^2}{\bar{v}_1^2} + \frac{\partial P}{\partial \rho l_s} & 2\frac{\bar{v}_2}{\bar{v}_1} & \frac{\partial P}{\partial \rho l_s} \\ 0 & 0 & \frac{\bar{v}_2}{\bar{v}_1} \end{pmatrix} \begin{pmatrix} v \\ \dot{v} \\ w \end{pmatrix}_x = 0$$

3

want to determine eigenvalues of this matrix: ↑

get $\frac{\bar{v}_2}{\bar{v}_1}, \frac{\bar{v}_2}{\bar{v}_1} \pm \sqrt{\frac{\partial P}{\partial \rho l_s}}$

⇒ $\bar{v}, \bar{v} \pm \sqrt{\frac{\partial P}{\partial \rho l_s}}$ ↑ velocity we are in around

Ex 6.6

Bg 6.4 LeVeque

$$\left(\frac{P}{\rho v}\right)_t + \left(\frac{\rho v}{\rho v^2 + \hat{k} \rho^r}\right)_x = 0$$

$$\hat{k} = k e^{\frac{f}{\rho v}}$$

$$v_1 = \rho$$

$$v_2 = \rho v$$

$$\rightarrow v_t + \left(\frac{v_2}{v_1^2 + \hat{k} v_1^r} \right)_x = 0$$

$$f'(v) = \begin{pmatrix} 0 & 1 \\ -\frac{v_2^2}{v_1^2} + r \hat{k} v_1^{r-1} & \frac{2v_2}{v_1} \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -v^2 + r \hat{k} v^{r-1} & 2v \end{pmatrix}$$

evalves $\lambda^2 - (2v)\lambda + (v^2 - r \hat{k} v^{r-1}) = 0$

$$\lambda = \frac{2v \pm \sqrt{4v^2 - 4(v^2 - r \hat{k} v^{r-1})}}{2}$$

$$\gamma = \sqrt{r^2 p^{n-1}} = \sqrt{\frac{r}{p^n}} = \sqrt{\frac{r}{p^2}}$$

Ex 6.7

Q 6.4 LeVeque

$$\begin{pmatrix} \zeta \\ \phi \end{pmatrix}_t + \begin{pmatrix} \zeta^2/2 + \phi \\ \zeta\phi \end{pmatrix}_x = 0$$

$$\zeta = \zeta_1 + \zeta_-$$

$$\zeta^2/2 = (\zeta_1^2 + 2\zeta_1\zeta_- + \zeta_-^2)$$

$$\phi = \phi_1 + \phi_-$$

$$\zeta\phi = \zeta_1\phi_1 + \zeta_1\phi_- + \phi_1\zeta_- + \phi_-\zeta_-$$

$$\begin{pmatrix} \zeta \\ \phi \end{pmatrix}_t + \begin{pmatrix} \zeta \zeta_x + \phi_x \\ \zeta \phi_{xx} + \phi \zeta_x \end{pmatrix} = 0$$

$$\begin{pmatrix} \zeta \\ \phi \end{pmatrix} = \begin{pmatrix} \zeta_1 & 1 \\ \phi_1 & \zeta_- \end{pmatrix} \begin{pmatrix} \zeta \\ \phi \end{pmatrix}_x \quad \checkmark$$

$$\begin{pmatrix} \zeta \\ \phi \end{pmatrix}$$

$$\begin{pmatrix} \zeta \\ \phi \end{pmatrix} = \begin{pmatrix} \zeta_1 & 1 \\ \phi_1 & \zeta_- \end{pmatrix} \begin{pmatrix} \zeta \\ \phi \end{pmatrix}_x \quad \checkmark$$

sound speed first evaluate $\pm F(u)$

$$= \bar{v} - \sqrt{\bar{\phi}} + \bar{v} + \sqrt{\bar{\phi}} = \text{sound speed} \downarrow = \sqrt{\bar{\phi}}.$$

2

Pg 65 Lec 8

$$v(x,t) = \sum_{p=1}^{P(x,t)} \beta_p r_p + \sum_{p=P(x,t)+1}^m \beta_p r_p + \sum_{p=P(x,t)+1}^m (\alpha_p - \beta_p) r_p$$

$$= v_r - \sum (\beta_p - \alpha_p) r_p \quad P(x,t) \text{ Max } p \exists$$
$$\gamma_p > \gamma_t \iff \gamma_p < \frac{x}{t}$$

Sim.

$$v(x,t) = \sum_{p=1}^{P(x,t)} (\beta_p - \alpha_p) r_p + v_e$$

$$= v_e + \sum (\beta_p - \alpha_p) r_p$$
$$\gamma_p < \gamma_t$$

$$v_m - v_e = B_1 r_1 + \alpha_2 r_2 - (\alpha_1 r_1 + \alpha_2 r_2)$$
$$= (B_1 - \alpha_1) r_1$$

$$v_r - v_m = B_1 r_1 + B_2 r_2 - (B_1 r_1 + \alpha_2 r_2)$$
$$= (B_2 - \alpha_2) r_2$$

Pg 71 Leveque

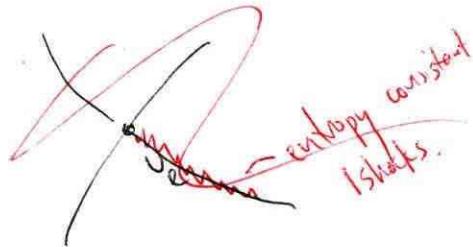
$$f(\tilde{v}_p(\xi)) - f(\hat{v}) = s_p(\xi)(\tilde{v}_p(\xi) - \hat{v})$$

$$\frac{d}{d\xi} \left(f(\tilde{v}_p(\xi)) - f(\hat{v}) \right) \Big|_{\xi=0}$$

$$\begin{aligned} f'(\hat{v}) \tilde{v}'_p(0) &= s'_p(\xi)(\cdot 0) + s_p(\xi)(\tilde{v}'_p(0)) \\ &= s_p(0)\tilde{v}'_p(0) \end{aligned}$$

$$\left(\frac{p}{m}\right)_t + \left(\frac{m}{\frac{p^2}{m} + a^2 p}\right)_x = 0$$

$$+ \begin{pmatrix} 0 & 1 \\ -\frac{m^2}{p^2} + a^2 & 2\frac{m}{p} \end{pmatrix} \begin{pmatrix} p \\ m \end{pmatrix}_x = 0$$



Pg 71 LeVeque

$$\begin{pmatrix} p \\ m \end{pmatrix}_t + \begin{pmatrix} \quad \end{pmatrix} \begin{pmatrix} p \\ m \end{pmatrix}_x = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \times \text{can't linearize}$$

$$f(v) = \begin{pmatrix} m \\ \frac{m^2}{p} + a^2 p \end{pmatrix}$$

$$f'(v) = \begin{pmatrix} 0 & 1 \\ -\frac{m^2}{p^2} + a^2 & \frac{2m}{p} \end{pmatrix}$$

$$\tilde{v}_1(\xi, \zeta) = \begin{pmatrix} \hat{p} \\ \hat{m} \end{pmatrix} = \begin{pmatrix} \hat{p}(1+\xi) \\ \hat{m}(1+\xi) - a\xi\sqrt{1+\xi} \end{pmatrix} \quad s_1(\xi; v) = \frac{\hat{m}}{\hat{p}} - a\sqrt{1+\xi}$$

$$= \begin{pmatrix} \hat{p} \\ \hat{m} \end{pmatrix} + \xi \begin{pmatrix} \hat{p} \\ \hat{m} - a\sqrt{1+\xi} \end{pmatrix}$$

$$\frac{\partial \tilde{U}_1(\xi; \zeta)}{\partial \xi} = \begin{pmatrix} \hat{r} \\ \hat{m} - a\hat{r}\sqrt{1+\xi} \end{pmatrix} + \xi \begin{pmatrix} 0 \\ -\frac{a\hat{r}}{2\sqrt{1+\xi}} \end{pmatrix}$$

$$\frac{\partial \tilde{U}_1(0; \zeta)}{\partial \xi} = \begin{pmatrix} \hat{r} \\ \hat{m} - a\hat{r} \end{pmatrix} = \hat{r} \begin{pmatrix} 1 \\ \frac{\hat{m}}{\hat{r}} - a \end{pmatrix} \propto r_1(\zeta)$$

$$\frac{\partial \tilde{U}_2(0)}{\partial \xi} = \begin{pmatrix} \hat{r} \\ \hat{m} + a\hat{r}\sqrt{1+\xi} \end{pmatrix} = \hat{r} \begin{pmatrix} 1 \\ \frac{\hat{m}}{\hat{r}} + a \end{pmatrix}$$

$$p_x + m_x = 0$$

$$m_x^2 + (m_p^2 + a^2 p)_x = 0$$

$$\vec{U} = \begin{pmatrix} P \\ m \end{pmatrix}$$

$$f'(u) = \begin{pmatrix} 0 & 1 \\ -\frac{m^2}{p^2} + a^2 & \frac{2m}{p} \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ a^2 - \frac{m^2}{p^2} & \frac{2m}{p} \end{pmatrix}$$

eigenvalues \Rightarrow solve

$$(\Delta I - f'(u)) = 0$$

$$\begin{vmatrix} \lambda & -1 \\ -a^2 + \frac{m^2}{p^2} & -\frac{2m}{p} + \lambda \end{vmatrix} = 0$$

$$= -\frac{2m\lambda}{p} + \lambda^2 + -a^2 + \frac{m^2}{p^2} = 0$$

$$\lambda^2 - \frac{2m}{p}\lambda + \frac{m^2}{p^2} - a^2 = 0$$

$$\lambda^2 - \frac{2m}{p}\lambda + \frac{m^2}{p^2}$$

$$(\lambda - \frac{m}{p})^2 - a^2 = 0$$

~~6.07a~~

$$\therefore \left(\lambda - \frac{m}{p}\right)^2 = a^2$$

$$\lambda - \frac{m}{p} = \pm a$$

$$\lambda = \frac{m}{p} \pm a$$

Then eigenvectors

$$\tilde{m} - \hat{m} = S(\tilde{\rho} - \hat{\rho})$$

state above is $\hat{\rho} \tilde{m}$

$$\frac{\tilde{m}^2}{\tilde{\rho}} + a^2 \tilde{\rho} - \frac{\hat{m}^2}{\hat{\rho}} - a^2 \hat{\rho} = S(\tilde{m} - \hat{m})$$

2 eqs + 3 unknowns ($\tilde{\rho}, \tilde{m}, S$)
Solve for $\tilde{m} + S$ in terms of $\tilde{\rho}$
(why? $\tilde{\rho}$ appears linearly in eqs?)

1st eq solve for $\tilde{m} = \hat{m} + S(\tilde{\rho} - \hat{\rho})$ put into 2nd eq

$$\frac{(\hat{m} + S(\tilde{\rho} - \hat{\rho}))^2}{\tilde{\rho}} + a^2 \tilde{\rho} - \frac{\hat{m}^2}{\hat{\rho}} - a^2 \hat{\rho} = S(S(\tilde{\rho} - \hat{\rho}))$$

$$\Rightarrow \frac{\hat{m}^2 + 2\hat{m}(\tilde{\rho} - \hat{\rho})S + (\tilde{\rho} - \hat{\rho})^2 S^2}{\tilde{\rho}} + a^2 \tilde{\rho} - \frac{\hat{m}^2}{\hat{\rho}} - a^2 \hat{\rho} = S^2(\tilde{\rho} - \hat{\rho})$$

$$\Rightarrow (\tilde{\rho} - \hat{\rho})^2 S^2 + 2\hat{m}(\tilde{\rho} - \hat{\rho})S + \hat{m}^2 + a^2 \tilde{\rho} - \frac{\hat{m}^2}{\hat{\rho}} - a^2 \hat{\rho} = S^2(\tilde{\rho} - \hat{\rho})$$

$$\Rightarrow [(\tilde{\rho} - \hat{\rho})^2 - \hat{\rho}(\tilde{\rho} - \hat{\rho})] S^2 + 2\hat{m}(\tilde{\rho} - \hat{\rho})S + \hat{m}^2 + a^2 \tilde{\rho} - \frac{\hat{m}^2}{\hat{\rho}} - a^2 \hat{\rho} = 0$$

$$(\tilde{\rho} - \hat{\rho})[\tilde{\rho} - \hat{\rho} - \hat{\rho}] S^2 + \dots$$

$$= -\hat{\rho}(\tilde{\rho} - \hat{\rho}) S^2 + \dots$$

$$s = -2\hat{m}(\tilde{p} - \hat{p}) \pm \sqrt{4\hat{m}^2(\tilde{p} - \hat{p})^2 + 4\hat{p}(\tilde{p} - \hat{p})}$$

Can't use quadratic eq here

I'm going to complete the square

$$\Rightarrow s^2 - 2\frac{\hat{m}}{\hat{p}}s - \frac{1}{\hat{p}(\tilde{p} - \hat{p})} \left[\hat{m}^2 + \hat{a}^2 \tilde{p}^2 - \left(\frac{\hat{m}^2}{\hat{p}} + \hat{a}^2 \tilde{p} \right) \right] = 0$$

↑

Let's how nice

this term is

$$\text{Take middle term } \div 2 + \text{sqr} = \frac{\hat{m}^2}{\hat{p}^2}$$

$$\Rightarrow s^2 - 2\frac{\hat{m}}{\hat{p}}s + \frac{\hat{m}^2}{\hat{p}^2} - \frac{\hat{m}^2}{\hat{p}^2} - \frac{1}{\hat{p}(\tilde{p} - \hat{p})} \underbrace{\left[\hat{m}^2 + \hat{a}^2 \tilde{p}^2 - \left(\frac{\hat{m}^2}{\hat{p}} + \hat{a}^2 \tilde{p} \right) \right]}_{} = 0$$

$$\Rightarrow \left(s - \frac{\hat{m}}{\hat{p}} \right)^2 - \frac{\hat{m}^2}{\hat{p}^2} - \frac{1}{\hat{p}(\tilde{p} - \hat{p})} \left[\underbrace{\hat{m}^2 \left(1 - \frac{\tilde{p}}{\hat{p}} \right)}_{}, \hat{a}^2 \tilde{p}(\tilde{p} - \hat{p}) \right] = 0$$

$$\frac{\hat{m}^2}{\hat{p}^2} (\hat{p} - \tilde{p})$$

$$\Rightarrow \left(s - \frac{\hat{m}}{\hat{p}} \right)^2 - \cancel{\frac{\hat{m}^2}{\hat{p}^2}} + \cancel{\frac{\hat{m}^2}{\hat{p}^2}} - \frac{\hat{a}^2 \tilde{p}}{\hat{p}} = 0$$

$$S = \frac{\hat{m}}{\hat{p}} \pm a \sqrt{\frac{\hat{f}}{\hat{p}}} \quad \text{eq 7.10.}$$

Then $\tilde{m} = \hat{m} + (\tilde{p} - \hat{p}) \left(\frac{\hat{m}}{\hat{p}} \pm a \sqrt{\frac{\hat{f}}{\hat{p}}} \right)$

$$= \hat{m} \left(\frac{\hat{p}}{\hat{p}} + \frac{\tilde{p} - \hat{p}}{\hat{p}} \right) \pm a(\tilde{p} - \hat{p}) \sqrt{\frac{\hat{f}}{\hat{p}}}$$

$$= \frac{\hat{p}}{\hat{p}} \hat{m} \pm a(\tilde{p} - \hat{p}) \sqrt{\frac{\hat{f}}{\hat{p}}} \quad \text{eq 7.9}$$