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$$\textcircled{1} (x_1, x_2) + (y_1, y_2) = (x_1 + y_1, x_2 + y_2)$$

Check each condition in turn. I.

$$(x_1, x_2) + (y_1, y_2) = (y_1, y_2) + (x_1, x_2)$$

II

$$(x_1 + y_1, x_2 + y_2) \neq (y_1 + x_1, y_2 + x_2) \quad \text{so the 1st condition is violated}$$

The 2nd condition will be violated also

3 is satisfied with $(0, 0)$

4 is satisfied with $(-x_2, -x_1)$

5 is satisfied

6 is satisfied

7 is satisfied

8 is Not satisfied. let $\bar{5} = 2 + 3$ so $C_1 = 2 + C_2 = 3$

$$\text{Then } (C_1 + C_2)(x) = \bar{5} (x_1, x_2)$$

$$\stackrel{?}{=} 2(x_1, x_2) + 3(x_1, x_2) = (2x_1, 2x_2) + (3x_1, 3x_2)$$

$$= (2x_1 + 3x_1, 2x_2 + 3x_2) \quad \text{which is Not true}$$

$\textcircled{2}$ (1) is satisfied

(2) is satisfied

(3) is satisfied

(4) is satisfied

(5) is satisfied

(6) is Not satisfied

(7) is satisfied

(8) is satisfied

2

③ (a) CX is Not in the half space so this space is Not a subspace

~~Not~~ of the axioms of ~~linear algebra~~ a vector space

(1) is ~~not~~ satisfied

(2) is satisfied

(3) is satisfied w/ 0

(4) is Not ~~satisfied~~ satisfied

(5) is satisfied

(6) ~~is~~ ~~is~~ ~~is~~ satisfied but each side is Not guaranteed to be in the required half space ($\mathbb{R}^+$) $c_1 \text{ or } c_2 < 0$

(7) The same comment as in 6 applies

(8) The same comment as in 6 applies

(b) $x+y \equiv xy$

$+ cx = x^c$

The unique zero vector is $x \equiv 1$ (in rule #3)

The unique vector $(-x)$ such that $x + (-x) = 0$ is the reciprocal element of x .

$$(c_1 c_2)x = x^{c_1 c_2}$$

$$c_1(c_2 x) = c_1(x^{c_2}) = (x^{c_2})^{c_1} = x^{c_1 c_2} \quad \text{yes rule \# 6 holds}$$

Rule #7 states that

$$c(x+y) = c(xy) = (xy)^c = x^c \cdot y^c = cx + cy \quad \text{which is true}$$

Rule #8 states that

$$(c_1 + c_2)x = x^{c_1 + c_2} = x^{c_1} x^{c_2} = c_1 x + c_2 x$$

The zero vector is the unit 1

The vector -2 is the ~~the~~ $\frac{1}{2}$

(4) ~~the~~ Much of this problem is skipped

since $A = c \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix}$

The smallest subspace containing A is all multiples of the elementary matrix $\begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix}$

(5) (a) let the subspace be all multiples of $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$

(b) Yes because the element

$$A + (-1)B = I \text{ must be in the space}$$

(c)

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(5) (a) let M consist of all matrices that are multiples of the matrix $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$.

(b) ~~Yes~~ since $1 \cdot A + (-1) \cdot B$ must be in this space

(c) let the ~~space~~ ^{subspace} consist of all matrices

$$\text{defined by } a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

(6) $h(x) = 3(x^2) - 4(5x) = 3x^2 - 20x$

(7) Rule # 7 is no longer true since

~~The expression~~

~~$(x+y)$ is interpreted as~~

~~$f(x) + g(x)$~~

~~+ the expression~~

~~$cx + cy$ is interpreted as~~

Rule # 8 is ~~interpreted as~~ No longer true since

$(c_1 + c_2)x \neq f(c_1 + c_2)x$ is interpreted as

~~$f(c_1 + c_2)x$~~ $f(c_1 + c_2)x$ +

$c_1x + c_2x$ is interpreted as $f(c_1x) + f(c_2x)$

But in general for arbitrary functions

$$f((c_1+c_2)x) \neq f(c_1x) + f(c_2x)$$

⑧ The 1st rule is $x+y = y+x$ is broken

since $f(g(x)) \neq g(f(x))$ in general

Rule # 2 ~~was~~ ~~broken~~ ~~for the~~ ~~same~~ ~~reason~~ is alright.

Rule # 3 is ~~broken~~ ~~correct~~ with the two vector defined to be x

Rule # 4 is ~~correct~~ correct if we define $-x$ to be

$\{f(g(x)) = x\}$ the inverse of the function $f(\cdot)$ then the rule states that

$f(f^{-1}(x)) = x$ Assuming an inverse of f exists

Rule # 7 is broken since

$$c(x+y) \text{ is } cf(g(x))$$

$\neq cx + cy$ is ~~not~~ $cf(g(x))$ which ~~are~~ ^{are} not the

same in ~~general~~ general

Rule # 8 is broken since the left hand side

interpreted as $(c_1+c_2)x = (c_1+c_2)f(x)$

While the right hand side is interpreted as

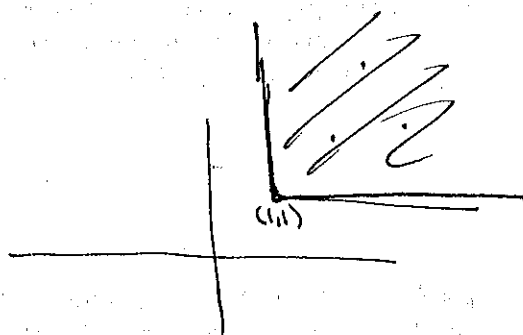
$$c_1 x + c_2 x = c_1 f(c_2 f(x)) \text{ which are not equal in general}$$

⑨ ~~(a)~~ (a) let the vectors

~~be defined by allowing any $x+y \geq 0$~~

~~(b)~~ ~~(c)~~

~~(d)~~



$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c \begin{pmatrix} 1 \\ 0 \end{pmatrix} + d \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad c \geq 0 \quad \text{and} \quad d \geq 0$$

Then this set is the upper right corner shown above

~~But~~ ~~(b)~~ = ~~the~~ ~~sum~~ of any two

vectors in the set will also be in the set.

The vector $\frac{1}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix}$ will not however

(b') let the set consist of the $x+y$ axis (all the points on them). Then for any point x on the axis $c x$ is also on the axis but the point $x+y$ will almost certainly not be

(10)

(a) Yes

(b) No since $c(b_1, b_2, b_3) = c(1, b_2, b_3)$ is not in the set if $c = 1/2$

~~(c)~~ (c) No since if two vectors ~~have~~ ~~$b_1, b_2, b_3 = 0$~~ $x + y$ are such that $x_1 x_2 x_3 = 0$ & $y_1 y_2 y_3 = 0$ there is no guarantee that $x + y$ will have that property. Consider

$$x = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \quad y = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

(d) Yes this is a subspace

(e) Yes this is a subspace

(f) No since if $b = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$ has this property then

cb should have this property but $cb_1 \leq cb_2 \leq cb_3$ ~~that~~ might

Not be true consider $b = \begin{pmatrix} -100 \\ -10 \\ -1 \end{pmatrix}$ & $c = -1$

Then $b_1 \leq b_2 \leq b_3$ but ~~$cb_1 \leq cb_2 \leq cb_3$~~ is Not true.

(11) (a) All matrices of the form

$$\begin{bmatrix} a & b \\ 0 & 0 \end{bmatrix}$$

$\forall a, b \in \mathbb{R}$

(b) All matrices of the form $\begin{bmatrix} a & a \\ 0 & 0 \end{bmatrix}$ $a \in \mathbb{R}$

(c) All matrices of the form $\begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$ or diagonal matrices

(12) let vector $v_1 = \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} + v_2 = \begin{pmatrix} 4 \\ 0 \\ 0 \end{pmatrix}$

Then $v_1 + v_2 = \begin{pmatrix} 5 \\ 1 \\ -2 \end{pmatrix}$ let $5 + 1 - 2(-2) = 10 \neq 4$

So the sum is Not on the plane

(13) ~~This~~ The plane parallel to the previous plane P is

$$x + y - 2z = 0$$

let vector $v_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + v_2 = \begin{pmatrix} 1 \\ 0 \\ \frac{1}{2} \end{pmatrix}$ which are

both on P_0 . Then $v_1 + v_2 = \begin{pmatrix} 2 \\ 1 \\ \frac{3}{2} \end{pmatrix}$

checking $2 + 1 - 2(\frac{3}{2}) = 0$ we see it is true

(14) (a) lines, $\mathbb{R}^2$ itself, or $(0,0,0)$

(b) $\mathbb{R}^4$ itself, hyperplanes of dimension 4 (one constraining equation among 4 variables) that goes through the origin i.e. constraints like the follows

$$ax_1 + bx_2 + cx_3 + dx_4 = 0 \quad *$$

constraints involving 2 equations like the above (going through the origin)

$$ax_1 + bx_2 + cx_3 + dx_4 = 0 \quad \text{if this is effectively a 2D plane}$$

$$Ax_1 + Bx_2 + Cx_3 + Dx_4 = 0$$

if constraints involving 3 equations like * + going through the origin + finally the origin itself.

this is effectively a 1D line.

(15) (a) line

(b) point $(0,0,0)$

(c) let $x + y \in \text{SAT}$

Then $x + y \in \text{SAT}$

+ $cx \in \text{SAT}$ since $x + y$ or both in SAT

which are subspaces + $\therefore \begin{matrix} \text{if } x+y \text{ and } cx \\ \text{are both in SAT} \end{matrix}$

(16) a plane if the line is in the plane to begin with
or all of $\mathbb{R}^3$, ~~since~~

(17) (a) let $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ + $B = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$

which are both invertible. $A+B = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ which is Not

thus the set of invertible matrices is Not a subspace

(b) let ~~$A = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$~~ + ~~$B = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$~~

~~$A = \begin{bmatrix} 1 & 3 \\ 2 & 6 \end{bmatrix}$~~ + ~~$B = \begin{bmatrix} 2 & 3 \\ 4 & 3 \end{bmatrix}$~~ $\begin{bmatrix} 6 & 3 \\ 2 & 1 \end{bmatrix}$

which are both singular

But $A+B = \begin{bmatrix} 3 & 6 \\ 6 & 9 \end{bmatrix}$ $\begin{bmatrix} 7 & 6 \\ 4 & 6 \end{bmatrix}$ which

is Not singular, showing that the set of ~~invertible~~ singular
matrices is Not a subspace

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(18) (a) True since if $A + B$ are symmetric then

$$(A+B)^T = A^T + B^T = A + B \quad \text{is } \text{symmetric}$$

$$\text{+ } (CA)^T = CA^T = CA \quad \text{is symmetric}$$

(b) True since if $A + B$ are skew symmetric

$$\text{then } (A+B)^T = A^T + B^T = -A - B = -(A+B)$$

$$\text{+ } A + B \text{ is skew symmetric}$$

+ if A is skew symmetric then CA is also

$$\text{since } (CA)^T = CA^T = -CA$$

(c) False since if $A = \begin{bmatrix} 1 & 3 \\ 2 & 5 \end{bmatrix}$ which is unsymmetric

$$\text{+ } B = \begin{bmatrix} 0 & -1 \\ 0 & 0 \end{bmatrix} \text{ which is unsymmetric}$$

then $A+B = \begin{bmatrix} 1 & 2 \\ 2 & 5 \end{bmatrix}$ should be unsymmetric but it is not

so the set of unsymmetric matrices is not closed under addition + $\therefore$ is not a subspace.

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(19) If $A = \begin{bmatrix} 1 & 2 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$ then the column space is given by

$$\begin{bmatrix} 1 & 2 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{pmatrix} x_1 + 2x_2 \\ 0 \\ 0 \end{pmatrix}$$

which is a line in the x -axis all combinations of x_1 and x_2 on the x -axis

If $B = \begin{bmatrix} 1 & 0 \\ 0 & 2 \\ 0 & 0 \end{bmatrix}$ then the ^{column} space of B is

$\begin{pmatrix} x_1 \\ 2x_2 \\ 0 \end{pmatrix}$ or the $x+y$ plane.

If $C = \begin{bmatrix} 1 & 0 \\ 2 & 0 \\ 0 & 0 \end{bmatrix}$ then Cx is given by $\begin{pmatrix} x \\ 2x \\ 0 \end{pmatrix}$

~~or the xy plane~~ or a line in the xy plane.

(20) (a)
$$\left[\begin{array}{ccc|c} 1 & 4 & 2 & b_1 \\ 2 & 8 & 4 & b_2 \\ -1 & -4 & -2 & b_3 \end{array} \right]$$

let $E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$

Then $E_{21} \left[\begin{array}{ccc|c} 1 & 4 & 2 & b_1 \\ 2 & 8 & 4 & b_2 \\ -1 & -4 & -2 & b_3 \end{array} \right] = \left[\begin{array}{ccc|c} 1 & 4 & 2 & b_1 \\ 0 & 0 & 0 & b_2 - 2b_1 \\ 0 & 0 & 0 & b_3 + b_1 \end{array} \right]$

So $b_2 = 2b_1 + b_1 = -b_3$

(b)
$$\begin{bmatrix} 1 & 4 \\ 2 & 9 \\ -1 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

let $E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} + E_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$

Then $E_{21} \begin{bmatrix} 1 & 4 \\ 2 & 9 \\ -1 & -4 \end{bmatrix} = \begin{bmatrix} 1 & 4 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$

$E_{31} E_{21} \begin{bmatrix} 1 & 4 & | & b_1 \\ 2 & 9 & | & b_2 \\ -1 & -4 & | & b_3 \end{bmatrix} = \begin{bmatrix} 1 & 4 & | & b_1 \\ 0 & 1 & | & b_2 - 2b_1 \\ 0 & 0 & | & b_1 + b_3 \end{bmatrix}$

= Requiring $b_1 + b_3 = 0$ or $b_1 = -b_3$

(21) A combination of the columns of B_n or also a combination of the columns of A . These two matrices have the same column span.

(22) For the 1st system

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

For any values of b the system will have a solution

For the 2nd system

$$\begin{bmatrix} 1 & 1 & 1 & | & b_1 \\ 0 & 1 & 1 & | & b_2 \\ 0 & 0 & 0 & | & b_3 \end{bmatrix} \quad \text{we must have } \cancel{b_3} \neq 0 \quad b_3 = 0$$

For the 3rd system

$$\begin{bmatrix} 1 & 1 & 1 & | & b_1 \\ 0 & 0 & 1 & | & b_2 \\ 0 & 0 & 1 & | & b_3 \end{bmatrix}$$

~~Any values of b_1, b_2, b_3 will have a solution~~

(23) $\begin{bmatrix} 1 & 1 & 1 & | & b_1 \\ 0 & 0 & 1 & | & b_2 \\ 0 & 0 & 0 & | & b_3 - b_2 \end{bmatrix}$ so $b_2 = b_3$

(23) Unless b is a combination of the ~~previous~~ columns of A
 if $\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$ & with $b = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ has a larger column space

but if $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$ & $b = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}$ the column space doesn't change

Because b can be written as a linear combination of the columns of A & $\therefore$ Adds no new information to the column space

(24) The column space of AB is contained in the column space of A & possibly equal to the column space of A .

If $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ then $B = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$

$$AB = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \text{ which is of smaller } \text{dimension than}$$

the original column space of A .

(25) If ~~$z = y$~~ $z = x + y$ is a solution to $Az = b + b^*$

If $b + b^*$ is in the column space of A then so is $b + b^*$.

(26) If A is any 5×5 invertible matrix has $\mathbb{R}^5$ as its column space. Since $Ax = b$ always has a solution then A is invertible.

(27) (a) ~~if $b \notin \text{Col}(A)$~~

~~Then the sum of two~~ ~~yes this is true~~

(b) True

(c) True

(d) False the matrix I adds a full set of pivots
(linear independent rows)

$$\text{let } A = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \text{ w/ } I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

A has a column space of the zero vector +

$$A - I = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \text{ has all of } \mathbb{R}^2 \text{ as its column space}$$

(a) False let $A = \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix}$ then $x_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ + $x_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

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one each not in the column space but $x_1 + x_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ is
in the column space. Thus the set of vectors ~~in the column~~ not in
the column space is not a ~~subset~~ subspace.

(28)

$$\begin{bmatrix} 1 & 1 & 2 \\ 1 & 0 & 0 \\ 0 & 1 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

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- ① ~~The matrices (a) + (b) ARE in ordinary echelon form.~~
For the matrix (a)

$$A = \begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 1 & 2 & 3 & 6 & 9 \\ 0 & 0 & 1 & 2 & 3 \end{bmatrix}$$

$$\text{let } E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{Then } E_{21}A = \begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 2 & 3 \end{bmatrix}$$

$$\text{let } E_{33} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} \text{ then } E_{33}E_{21}A = \begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = T$$

Which has pivot variables $x_1 + x_3$
+ Free variables in $x_2, x_4, + x_5$

For the matrix (b)

$$A = \begin{bmatrix} 2 & 4 & 2 \\ 0 & 4 & 4 \\ 0 & 8 & 8 \end{bmatrix} \text{ let } E_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}$$

$$\text{Then } E_{32}A = \begin{bmatrix} 2 & 4 & 2 \\ 0 & 4 & 4 \\ 0 & 0 & 0 \end{bmatrix} = T$$

Then the free variables are $x_3 +$
the pivot variables are $x_1 + x_2$

(2) Since the ordinary echelon form for the matrix in (a) is

$$U = \begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

We find a special solution to each free variable that corresponds to each free variable by assigning ones to each free variable in turn. & then solve for the ~~other~~ ^{pivot} variables

For example since the free variables are $x_2, x_4, \& x_5$

let $x_2 = 1$
 ~~$x_2 = 0$~~ , $x_4 = 0, x_5 = 0$ then our system is

$$\begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ \cancel{x_2} \\ x_3 \\ 0 \\ 0 \end{bmatrix} = 0$$

$$\rightarrow \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_3 \end{bmatrix} = \begin{bmatrix} -2 \\ 0 \\ 0 \end{bmatrix}$$

Giving $x_3 = 0$ & $x_1 = -2$

So our special solution is given

~~$\begin{bmatrix} -2 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$~~ $\begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$

let $x_2 = 0, \cancel{x_4 = 0}, x_4 = 1, x_5 = 0$

Then our special solution is

$$\begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ 0 \\ x_3 \\ 1 \\ 0 \end{bmatrix} = 0$$

Then $\begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_3 \end{bmatrix} = \begin{bmatrix} -4 \\ -2 \end{bmatrix}$

Then $x_3 = -2$ $x_1 + 2(-2) = -4$
 $\Rightarrow x_1 = 0$

Then the 2nd special solution is given by $\begin{bmatrix} 0 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix}$

Our final special solution is obtained by setting

$$x_2 = 0, x_4 = 0, x_5 = 1$$

Then our system is

$$\begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = 0 \quad \text{which reduces to}$$

$$\begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_3 \end{bmatrix} = \begin{bmatrix} -6 \\ -3 \end{bmatrix}$$

So $x_3 = -3$

+ $x_1 = -6 - 2(-3) = -6 + 6 = 0$

giving

$$\begin{bmatrix} 0 \\ 0 \\ -3 \\ 0 \\ 1 \end{bmatrix}$$

Let's check: let $N = \begin{bmatrix} -2 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & -2 & -3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ then

$$AN = \begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} -2 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & -2 & -3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \checkmark$$

For the matrix in (b) we have $U = \begin{bmatrix} 2 & 4 & 2 \\ 0 & 4 & 4 \\ 0 & 0 & 0 \end{bmatrix}$

then the pivot variables are x_1 & x_2 ,
while the free variables are x_3 .

Setting $x_3 = 1$ we obtain the system

$$\begin{bmatrix} 2 & 4 \\ 0 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -2 \\ -4 \end{bmatrix}$$

$$\text{So } x_2 = -1 \quad \text{+} \quad x_1 = \frac{-2 - (4)(-1)}{2} = \frac{-2 + 4}{2} = 1$$

Giving a special solution of $\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$

③ From problem #2 we have 3 special solutions

$$v_1 = \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \quad v_2 = \begin{bmatrix} 0 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix} \quad \text{+} \quad v_3 = \begin{bmatrix} 0 \\ 0 \\ -3 \\ 0 \\ 1 \end{bmatrix}$$

Then any solution to $Ax = 0$ can be expressed as a linear combination of these special solutions. The nullspace of A contains the vector $x = 0$ only when its ~~column~~ there are no free variables or there exist n pivot variables

④ The reduced echelon form R has ones in the pivot columns of U .

For problem #1 ^(a) we ~~have~~ have

$$U = \begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Then let $E_{13} = \begin{bmatrix} 1 & -2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Then $E_{13}T = \begin{bmatrix} 1 & 2 & 0 & 0 & 0 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \equiv R$

The nullspace of R is equal to the nullspace of T since row operations don't change the nullspace

For ~~question~~ question #1 pt (b) our matrix T is given by

$T = \begin{bmatrix} 2 & 4 & 2 \\ 0 & 4 & 4 \\ 0 & 0 & 0 \end{bmatrix}$ then let $E_{12} = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Then $E_{12}T = \begin{bmatrix} 2 & 0 & -2 \\ 0 & 4 & 4 \\ 0 & 0 & 0 \end{bmatrix}$ let $D = \begin{bmatrix} 1/2 & 0 & 0 \\ 0 & 1/4 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Then $DE_{12}T = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$

(5) For pt (a) we have that

$A = \begin{bmatrix} -1 & 3 & 5 \\ -2 & 6 & 10 \end{bmatrix}$ then

Let $E_{21} = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix}$ we get that

$E_{21}A = \begin{bmatrix} -1 & 3 & 5 \\ 0 & 0 & 0 \end{bmatrix}$

Then since $E_{21}^{-1} = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}$ we have that

$$A = E_{21}^{-1} \bar{A} = \underbrace{\begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}}_{\equiv L} \begin{bmatrix} -1 & 3 & 5 \\ 0 & 0 & 0 \end{bmatrix}$$

For pt (b) we have that

$$A = \begin{bmatrix} -1 & 3 & 5 \\ -2 & 6 & 7 \end{bmatrix}$$

Then E_{21} is the same +

$$E_{21}A = \begin{bmatrix} -1 & 3 & 5 \\ 0 & 0 & -3 \end{bmatrix}$$

so that $A = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} -1 & 3 & 5 \\ 0 & 0 & -3 \end{bmatrix}$

⑥ For pt (c) we have since

$$\bar{A} = \begin{bmatrix} -1 & 3 & 5 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{we see that } x_1 \text{ is a pivot variable}$$

+ $x_2 + x_3$ are the free variables

Then 2 special solutions can be ~~also~~ computed by setting $x_2=1, x_3=0$

+ $x_2=0, x_3=1$ + solving for x_1 . In the 1st case we have

$$-x_1 + 3 = 0 \Rightarrow x_1 = 3 \text{ giving a special vector of}$$

$$v_1 = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}$$

In the 2nd case we have

$$-x_2 + 5 = 0 \text{ giving } x_2 = 5$$

Thus the 2nd special vector is given by $v_2 = \begin{pmatrix} 5 \\ 0 \\ 1 \end{pmatrix}$

~~For a given matrix to find a pivot~~

Thus all special solutions to $Ax = 0$ are contained in the set

$$c_1 \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix}$$

For part (b) we have the

$$U = \begin{bmatrix} -1 & 3 & 5 \\ 0 & 0 & -3 \end{bmatrix} \quad \text{Showing that } x_1 + x_3 \text{ are pivot variables while } x_2 \text{ is free.}$$

To solve for the ~~single~~ ~~free~~ vector in the null space set $x_2 = 1$ & solve for $x_1 + x_3$. This gives

$$\begin{bmatrix} -1 & 3 & 5 \\ 0 & 0 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ 1 \\ x_3 \end{bmatrix} = 0$$

$$\Rightarrow \begin{bmatrix} -1 & 5 \\ 0 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_3 \end{bmatrix} = \begin{bmatrix} -3 \\ 0 \end{bmatrix}$$

This gives $x_3 = 0$ & $x_1 = 3$

So our special solution is given by $\begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}$

For an $m \times n$ matrix the # of free variables plus the number of pivot variables equals n .

⑦ For pt (a) the Null space ~~of~~ A are all ~~vector~~ pts (x, y, z)

Such that
$$\begin{pmatrix} 3y + 5z \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad \text{on the plane} \quad x = 3y + 5z$$

This is a plane in xyz space. This space can also be described as ~~the span of~~ All possible linear combinations of the two vectors

$$\begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix}$$

For pt (b) the null space of A are all pts that are multiples of the vector $\begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix}$ this is a line in $\mathbb{R}^3$

or $x = 3c$ so $x = 3y + z = 0$
 $y = c$
 $z = 0$

⑧ For pt (a) in problem 5 we have

$$U = \begin{bmatrix} -1 & 3 & 5 \\ 0 & 0 & 0 \end{bmatrix}$$

let $D = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$ then

$$DU = \begin{bmatrix} 1 & -3 & -5 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{which is in reduced row echelon form}$$

The Identity matrix is simply a 1 giving

$$DT = \begin{bmatrix} [1] & -3 & -5 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{for the box around the identity.}$$

For part (b) we have that $T = \begin{bmatrix} -1 & 3 & 5 \\ 0 & 0 & -3 \end{bmatrix}$ so that

Defining $D = \begin{bmatrix} -1 & 0 \\ 0 & -1/3 \end{bmatrix}$ we have that

$$DT = \begin{bmatrix} 1 & -3 & -5 \\ 0 & 0 & 1 \end{bmatrix} \quad \text{is ~~the reduced row echelon form.~~}$$

Then let $E_{13} = \begin{bmatrix} 1 & 5 \\ 0 & 1 \end{bmatrix}$ we have that

$$E_{13}DT = \begin{bmatrix} 1 & -3 & 0 \\ 0 & 0 & 1 \end{bmatrix}. \quad \text{to or reduced row echelon form.}$$

or box around the identity in the ~~row~~ matrix R is around the pivot rows + pivot columns is given by

$$\begin{bmatrix} [1] & -3 & [0] \\ 0 & 0 & [1] \end{bmatrix}$$

9) (a) False ~~this~~ this depends on what the reduced echelon matrix looks like - consider $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$

Then the reduced Echelon matrix R is $\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$

Which has x_2 as a free variable

(b) True. An invertible matrix is defined as one that has a complete set of pivots i.e. no free variables.

(c) True. Since the # of free variables plus the # of pivot variables ~~is~~ equals n in the case of no free variables we have the maximal # of pivot variables of n .

(d) True. If $m > n$ then by pt (c) the # of pivot variables must be less than n & this is equivalent to less than m .

If $m < n$ Then we ~~must~~ have fewer equations than unknowns ~~if~~ ~~if~~ when reduced to reduced Echelon form we have a

maximal set of pivot variables. ~~we can have at~~ we can have at most m , corresponding to the ~~identity~~ ~~in the~~ block identity in the reduced row echelon form in the $m \times m$ position.

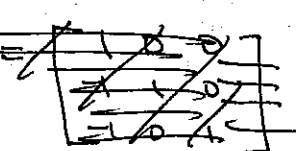
The remaining $n-m$ variables must be free

(10) (a) This is not possible since going from A to U involves

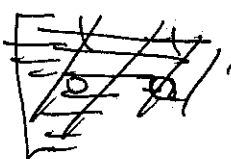
zeroing elements below the diagonal only. Thus if an element is non zero above the diagonal it will stay so for all elimination steps.

(b) let $A =$ 

(What's really required is to have 3 linearly independent columns/rows)

Then let $E =$ 

gives

$E \cdot A =$  let $A = \begin{bmatrix} 1 & 2 & 3 \\ -1 & -1 & -3 \\ -1 & -2 & -2 \end{bmatrix}$

then with $E = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$ we have

$EA = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ continuing let $E' = \begin{bmatrix} 1 & -2 & -3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Then $E'EA = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = R = I$

(C) I don't think it's possible for this to be true & the reason is as follows. R must have rows above each of its pivot variables.

What about $A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \end{bmatrix}$ which has no zero entries

Then $U = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix} A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ which also equals R .

(d) If $A = U = 2R$ then $R = \frac{1}{2}A = \frac{1}{2}U$

$$\text{so let } R = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = \frac{1}{2}A = \frac{1}{2}U$$

So

$$A = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

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(11)

(a)

$$\begin{bmatrix} 0 & 1 & x & x & x & x & x \\ 0 & 0 & 0 & 1 & x & x & x \\ 0 & 0 & 0 & 0 & 1 & x & x \\ 0 & 0 & 0 & 0 & 0 & x & 0 \end{bmatrix}$$

Here the symbol "1" corresponds

(b)

$$\begin{bmatrix} 1 & x & x & x & x & x & 0 \\ 0 & 0 & 1 & x & x & x & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & x \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

(c)

$$\begin{bmatrix} 0 & 0 & 0 & 1 & x & x & x \\ 0 & 0 & 0 & 0 & 0 & 1 & x \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

(12)

(a)

$$P = \begin{bmatrix} 0 & 1 & x & x & x & x & x & x \\ 0 & 0 & 0 & 1 & x & x & x & x \\ 0 & 0 & 0 & 0 & 1 & x & x & x \\ 0 & 0 & 0 & 0 & 0 & 1 & x & x \end{bmatrix}$$

this is the pivot variables
are 2, 4, 5, 6

~~(b)~~ $P = \begin{bmatrix} 1 & x & x & x & x & x & x & x \\ 0 & 0 & 1 & x & x & x & x & x \\ 0 & 0 & 0 & 0 & 1 & x & x & x \\ 0 & 0 & 0 & 0 & 0 & 1 & x & x \end{bmatrix}$ For the free variables to be 2, 4, 5, 6

we have

$$P = \begin{bmatrix} 1 & x & x & x & x & x & x & x \\ 0 & 0 & 1 & x & x & x & x & x \\ 0 & 0 & 0 & 0 & 1 & x & x & x \\ 0 & 0 & 0 & 0 & 0 & 1 & x & x \end{bmatrix}$$

1 2 3 4 5 6 7 8

$$R = \begin{bmatrix} 1 & x & 0 & x & x & x & 0 & 0 \\ 0 & 0 & 1 & x & x & x & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

(b) $R = \begin{bmatrix} 0 & 1 & X & X & 0 & X & X & X \\ 0 & 0 & 0 & 0 & 1 & X & X & X \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

$x_1 \ x_2 \ x_3 \ x_4 \ x_5 \ x_6 \ x_7 \ x_8$

$$R = \begin{bmatrix} 0 & 1 & X & 0 & 0 & X & X & X \\ 0 & 0 & 0 & 1 & 0 & X & X & X \\ 0 & 0 & 0 & 0 & 1 & X & X & X \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$x_1 \ x_2 \ x_3 \ x_4 \ x_5 \ x_6 \ x_7 \ x_8$

- (13) x_4 is certainly a free variable & the special solution is $x = (0, 0, 0, 1, 0)$

- (14) ~~Then~~ x_5 is a free variable. The special solution is $x = (1, 0, 0, 0, -1)$

- (15) $m \times n$ has r pivots the # of special solutions is $n - r$. The null space contains only 700 when $r = n$. The column space is $\mathbb{R}^m$ when $r = m$

- (16) When the matrix has 5 pivots. The column space is $\mathbb{R}^5$ when there are 5 pivots. Since $m = n$ the ~~problem~~ #15 the rank must equal $m = n$

①

$$A = \begin{bmatrix} 1 & -3 & -1 \end{bmatrix}$$

$$X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

The free variables are y & z

Let $y=1$ & $z=0$ then $x=3$ giving the 1st

special soln of $\begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}$. The 2nd special soln is given by

$$y=0, z=1$$

Then $x-1=0 \rightarrow x=1$ so we have

$$\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

②

$$x - 3y - z = 12$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 12 \\ 0 \\ 0 \end{bmatrix} + y \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix} + z \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

③

x in the Nullspace of B means that $Bx=0$

Thus $ABx = A0 = 0$ & thus is in the null space of AB

Then $ABx=0$

The Null space of B is contained in the Null space of AB

~~But~~ An obvious example where the Null space of AB is larger than that of B is when

$$B = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$$

which has a Null space given by
span of $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$

If $A = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ then $AB = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$

It has a Null space given by ~~the~~ the span of
 $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ + $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ which is larger than that of B

② If A is invertible then $\text{Nullspace}(AB) = \text{Null}(B)$.

If $v \in \text{Nullspace}(AB)$ then

$$ABv = 0 \Rightarrow Bv = 0 \text{ by multiplying by } A^{-1}.$$

$\therefore v \in \text{Nullspace}(B)$

But that L is invertible

② Does like x_3 + x_4 or free variables since

we set $x_3 = 1$ + $x_4 = 0$ + then $x_3 = 0$ + ~~$x_4 = 1$~~
 $x_3 = 1, x_4 = 0$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$$

In the same way when $x_3=0$ & $x_4=1$

$$\begin{bmatrix} 1 & 0 & -3 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_4 \end{bmatrix} \quad \text{Combining these two we get}$$

$$\begin{bmatrix} 1 & 0 & -2 & -3 \\ 0 & 1 & -2 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = 0$$

$$\text{So } A = \begin{bmatrix} 1 & 0 & -2 & -3 \\ 0 & 1 & -2 & 1 \end{bmatrix}$$

(22) $x_4=1$ & the other variables are solved for

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 4 \\ 3 \\ 2 \\ 1 \end{bmatrix} \quad (1)$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 & -4 \\ 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = 0$$

$$\text{So } A = \begin{bmatrix} 1 & 0 & 0 & -4 \\ 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & -2 \end{bmatrix}$$

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(23)

~~Q~~ 3 equations, rank = 2, nullity = 1

$$\Rightarrow m = 3 + n = 2 + 1 = 3$$

let $A = \begin{bmatrix} 1 & 0 & a \\ 1 & 3 & b \\ 5 & 1 & c \end{bmatrix}$ for some a, b, c

Then if $\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$ is to be in the nullity of A we have

$$A \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & a \\ 1 & 3 & b \\ 5 & 1 & c \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1+2a \\ 1+3+2b \\ 5+1+2c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow a = -\frac{1}{2}; b = -2; c = -3$$

Thus our matrix A is then

$$A = \begin{bmatrix} 1 & 0 & -\frac{1}{2} \\ 1 & 3 & -2 \\ 5 & 1 & -3 \end{bmatrix}$$

(24) ~~# of equations = 3; rank = 2, nullity = 2~~

$$\Rightarrow \text{~~n = 2 + 2 = 4, then~~}$$

let $A = \begin{bmatrix} 1 & 0 & x & a \\ 1 & 1 & y & b \\ 0 & 1 & z & c \end{bmatrix}$ for some ~~x, y, z~~ a, b, c

let $A = \begin{bmatrix} 1 & 0 & a \\ 1 & 1 & b \\ 0 & 1 & c \end{bmatrix}$ for ~~some~~ a, b, c

(24) The # of equations equals 3 + the rank = 2
 We are requiring that the Nullspace $\mathbb{R}^4$ of dimension 2 (2 vectors)
 Thus $m=3$ + $n=4$. But the dimension of the vectors in
 the Null space is $3 \neq 4$ + thus it is not possible to
 find a matrix with such properties

(25) will ~~not~~ $A = \begin{bmatrix} 1 & -1 & 0 & 0 \\ 1 & 0 & -1 & 0 \\ 1 & 0 & 0 & -1 \end{bmatrix}$ work?

then if the column space contains $(1,1,1)$ then $m=3$.

If the nullspace is $(1,1,1,1)$ then $n=4$.

$$\Rightarrow A \Rightarrow \begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1 \end{bmatrix}$$

so If $A\underline{x} = 0$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = 0$$

$\Rightarrow x=w=0; y-w=0, z-w=0$ the

$$\underline{x} = \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = w \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \quad \text{+ so matrix } A \text{ is correct}$$

26) A key to solving this problem is to recognize that the column space of A is also its null space.

$AA = 0$ since AA represents A acting on each column of A (it produces zero since the column space is a null space).

Thus we need a matrix A such that

$$A^2 = 0 \quad \text{or if} \quad A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} a^2 + bc & ab + bd \\ ac + cd & cb + d^2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

This gives 4 equations for a, b, c, d .

let $a=1$ then $d=-1$ ~~is true~~ (By element at $(1,2)$) & we have

$$\begin{bmatrix} 1+bc & 0 \\ 0 & cb+1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\text{let } 1+bc=0$$

say $b=1$ & $c=-1$ then

$$A = \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix}$$

Let's check

Then A 's row space is given by the span of $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$

+ its nullity is given by computing the R matrix

$$R = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \quad \text{giving } \underline{n} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

(27) In a 3×3 matrix we have $m=3$ + $n=3$

~~the~~ the column space has dimension r + the nullity must have dimension $n-r$ & let r can be either 1, 2, or 3

It we ~~not~~ consider each in turn

r	$n-r = 3-r$
1	2
2	1
3	0

we never have the column space equal to the row space

(28) If $AB = 0$ then the column space of B is contained in the nullity of A for example

$$AB = A \begin{bmatrix} b^1 & b^2 & \dots & b^n \end{bmatrix} = \begin{bmatrix} Ab^1 & Ab^2 & \dots & Ab^n \end{bmatrix} = 0$$

$$\Rightarrow Ab^1 = Ab^2 = \dots = Ab^n = 0.$$

let $A = \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix}$ which has nullity given by the span of $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$

Then consider $B = \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix}$ then

$$AB = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

(29) Almost sure to be the identity.

$$R = \begin{bmatrix} 1 & 0 & 0 & * \\ 0 & 1 & 0 & * \\ 0 & 0 & 1 & * \\ 0 & 0 & 0 & * \end{bmatrix} \quad \text{let } * \neq 0$$

With a random 4×3 matrix one is ~~almost~~ most likely to end with

$$R = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

(30) (a) let $A = \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix}$ then A has $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ as its null space

but $A^T = \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix}$ has $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ as its null space

(b) $A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 2 \end{bmatrix}$ then x_2 is a free variable

$$\text{but } A^T = \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 1 & 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 2 \\ 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$$

which has No free variable

A similar case happens when $A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}$ then A has x_2 as a free variable
but A^T has x_3 as a free variable

(C) Let $A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 2 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ has $x_1 + x_2$ as pivot column.

$A^T = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 2 \\ 1 & 0 & 0 \end{bmatrix}$ has $x_1 + x_3$ as pivot columns

(31) $A = [I \ I]$

Null space ^{to A} is $\begin{bmatrix} I \\ -I \end{bmatrix}$

$B = \begin{bmatrix} I & I \\ 0 & 0 \end{bmatrix}$ has Null space of $\begin{bmatrix} I \\ -I \end{bmatrix}$

$C = I$ has Nullspace of 0

(32) $x = (2, 1, 0, 1)$ is 4 dimensional so $n=4$

the nullspace is a single vector so $n-r=1 \Rightarrow 4-r=1$

$\Rightarrow r=3$ so 3 pivots, ~~also~~ spec is 0

(33) we must have $RN=0$ if $N = \begin{bmatrix} 2 & 3 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$ then

let ~~R~~ $R = \begin{bmatrix} 1 & -2 & -3 \\ 0 & 0 & 0 \end{bmatrix}$ $[1 \ -2 \ -3]$

Nullity is $\dim \text{null} = 2$

$\& n=3 \therefore n-r=2 \Rightarrow 3-r=2 \Rightarrow r=1$ we have only

1 non zero row in R

7

If $N = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ the nullity is dimension 1 & $n=3$

so $n-r=1$

$\Rightarrow 3-r=1 \Rightarrow r=2$ we have two

Non zero rows in R

$$R = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

If $N = \begin{bmatrix} \end{bmatrix}$ I'll assume this means $N = \emptyset \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ the

Nullity is dimension 0 & $n=3 \Rightarrow n-r=0$

$\Rightarrow r=3$ & we have 3 non zero rows in R

$$R = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

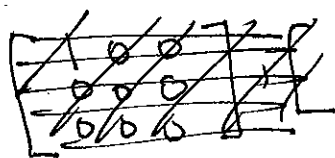
~~7A~~

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(34)

$$(a) R = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

(b)



1x3

...

2/9

$$\begin{bmatrix} 1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \end{bmatrix},$$

$$\begin{bmatrix} 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 1 \end{bmatrix}$$

They are all in Reduced Row echelon form.

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①

(a) ~~True~~ True(b) ~~No~~(c) ~~True~~(d) ~~False~~② The 3×5 matrix considered is

$$A = \begin{bmatrix} 1 & 3 & 0 & 2 & -1 \\ 0 & 0 & 1 & 4 & -3 \\ 1 & 3 & 1 & 6 & -4 \end{bmatrix}$$

Let $E_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}$ then

$$E_{31}A = \begin{bmatrix} 1 & 3 & 0 & 2 & -1 \\ 0 & 0 & 1 & 4 & -3 \\ 0 & 0 & 1 & 4 & -3 \end{bmatrix}$$

$$E_{33}E_{31}A = \begin{bmatrix} 1 & 3 & 0 & 2 & -1 \\ 0 & 0 & 1 & 4 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\text{w/ } E_{33} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

so $r=2$

Then $A = E_{31}^{-1}E_{33}^{-1}R$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 & 0 & 2 & -1 \\ 0 & 0 & 1 & 4 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 & 0 & 2 & -1 \\ 0 & 0 & 1 & 4 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Delete the $m-r = 3-2 = 1$ ~~rows~~ ~~from~~ zero rows from R

& the last $m-r$ columns from E

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 & 0 & 2 & -1 \\ 0 & 0 & 1 & 4 & -3 \end{bmatrix}$$

Check:

$$\begin{bmatrix} 1 & 3 & 0 & 2 & -1 \\ 0 & 0 & 1 & 4 & -3 \\ 1 & 3 & 1 & 6 & -4 \end{bmatrix} \quad \text{which is } A$$

③ (a) $A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

(b) $A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 6 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & -1 & -2 & -3 \\ 0 & -2 & -4 & -6 \end{bmatrix}$

$$\Rightarrow \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 3 \\ 0 & -2 & -4 & -6 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & -1 & -2 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

(c) $A = \begin{bmatrix} (-1)' & 1 & -1 & 1 \\ (-1)' & 1 & -1 & 1 \\ (-1)' & 1 & -1 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & -1 & 1 & -1 \\ -1 & 1 & -1 & 1 \\ -1 & 1 & -1 & 1 \end{bmatrix}$

$$\Rightarrow \begin{bmatrix} 1 & -1 & 1 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$(4) \quad A = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 3 \\ 2 & 4 & 6 \end{bmatrix} \Rightarrow \begin{bmatrix} 2 & 4 & 6 \\ 0 & 0 & 3 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 3 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \equiv R$$

$$\text{Then } B = [A \ A] \Rightarrow [R \ R]$$

$$\downarrow C = \begin{bmatrix} A & A \\ A & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} R & R \\ 0 & 0 \end{bmatrix}$$

$$(5) \quad R = \begin{bmatrix} A & B \\ C & D \end{bmatrix}$$

Then B is the $r \times r$ identity matrix

$$C = D = 0$$

~~A~~ A is a $r \times (n-r)$ matrix of ~~zeros~~ zeros, since if it was not we could make ~~more~~ pivot variables from.

$$\text{The Null space } N = \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} \begin{bmatrix} I \\ 0 \end{bmatrix}$$

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R_1

R_2

$$A_1 = E_1 R_1$$

$$A_2 = E_2 R_2$$

$$\text{Then } A_1 + A_2 = E_1 R_1 + E_2 R_2 \stackrel{\uparrow}{=} E(R_1 + R_2)$$

Require $E = E_1 + E_2$ then this will be true

Thus the elementary elimination matrices must add

$$\rightarrow E = \begin{bmatrix} \text{[scribbled out]} \\ \vdots \end{bmatrix}$$

Don't follow how to do this?

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~~A is m x n then with r pivot columns we will have~~

~~n - r free variables.~~ A & A^T both have rank r & $\therefore A^T$ must have r pivot columns

$$\text{let } A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

Then A has pivot variables at x_1 & x_3 .

$$\text{But } A^T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \text{ has } x_1 \text{ & } x_2 \text{ as pivot variables}$$

(8) If $R = \begin{bmatrix} 1 & 0 & 2 & 3 \\ 0 & 1 & 4 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

Then ~~the~~ ~~the~~ ~~the~~ the pivot ~~columns~~ variables are x_1 & x_2 while the free variables are x_3 & x_4 . let $x_3 = 1$ & $x_4 = 0$

to solve $R \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = 0$ we get

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -2 \\ -4 \end{bmatrix} \Rightarrow \begin{matrix} x_1 = -2 \\ x_2 = -4 \end{matrix}$$

so $\underline{x} = \begin{bmatrix} -2 \\ -4 \\ 1 \\ 0 \end{bmatrix}$ similarly let $x_3 = 0$ & $x_4 = 1$ to get

$$\underline{x} = \begin{bmatrix} -3 \\ -5 \\ 0 \\ 1 \end{bmatrix}$$

Now $y^T R = 0 \Leftrightarrow R^T y = 0$

Then $R^T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 4 & 0 \\ 3 & 5 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

So the null space is $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

For $R = \begin{bmatrix} 0 & 1 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

Then $x_1 + x_3$ are free variables while x_2 is a pivot variable

to find the null space let $x_1 = 1$ & $x_3 = 0$ & solve for x_2

This gives an element in the null space of $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

Let $x_1 = 0$ & $x_3 = 1$ & solve for x_2 to get

$$\begin{bmatrix} 0 & 1 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ x_2 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow x_2 = -2$$

So the 2nd element of the null space is $\begin{bmatrix} 0 \\ -2 \\ 1 \end{bmatrix}$

For $Y^T R = 0$ consider $R^T = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 2 & 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

Then the two vectors in the null space are

$$\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

9 $A = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 4 \end{bmatrix}$

$$\Rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 1 \end{bmatrix}$$

So we have a rank of 2 thus we remove $m-r = 2-2=0$ row + $n-r = 3-2=1$ column, to produce a $r \times r$ invertible matrix. We should remove the free column/variable given.

$\begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix}$ Add back in the ^{inverse of} elementary matrices that produce the row reduced echelon form gives

$$E^T \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 1 & 4 \end{bmatrix}$$

For $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \end{bmatrix}$ or rank is $r=1$

~~So the rank is $m-r = 2-1=1$ by $n-r=3$~~

So we should remove $m-r = 2-1=1$ row

+ $n-r = 3-1=2$ columns to produce an invertible matrix

pick the two free variables, i.e. x_2 & x_3 given

$$\begin{bmatrix} 1 \end{bmatrix}$$

For $A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ we have a rank of 2

So we should remove $m-r = 3-2 = 1$ row

+ $n-r = 3-2 = 1$ column. Giving the matrix

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

- (10) For Each of the pivot columns can not be constructed from other columns, thus ~~by~~ by extracting just these r columns. No combination of other columns can produce any of them. P will have rank r .

- (11) The rank of P^T is r also

$$\text{If } A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 2 & 4 & 7 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\text{Thus } P = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \quad \text{so } P^T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$\text{let } S^T = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \text{only the pivot columns of } P^T$$

$$\text{so } S = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

But we should work this problem on the original matrix not the row reduced one so

$$P = \begin{bmatrix} 1 & 2 \\ 2 & 4 \\ 2 & 4 \end{bmatrix} \quad P^T = \begin{bmatrix} 1 & 2 & 2 \\ 2 & 4 & 4 \end{bmatrix} \text{ which has its last 2 columns}$$

so pivot columns let $S^T = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$ then $S = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$

(12) (a) If $b_j = \sum_{k=1}^{j-1} a_k b_k$

Then $Ab_j = \sum_{k=1}^{j-1} Aa_k b_k = \sum_{k=1}^{j-1} (Ab)_k b_k$ or the sum combination of the columns of

AB

(b) Thus AB cannot have any new pivot columns (i.e. ones that are not linear combinations of the previous columns since AB cannot produce any non pivot columns than A has) thus

$$\text{rank}(AB) \leq \text{rank}(B)$$

Find A_1 & A_2 such that $\text{rank}(A_1 B) = \text{rank}(B)$

& $\text{rank}(A_2 B) \leq \text{rank}(B)$

Taking $A_1 = I$ gives a matrix such that

$\text{rank}(A_1 B) = \text{rank}(B)$. in general any invertible A_1 will work

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to 19
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For A_2 let $A_2 = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$ & w/ $B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

Then $A_2 B = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$ which has rank 1

$$\text{so } \text{rank}(A_2 B) = 1 \leq \text{rank}(B) = 2$$

For the given B we can still pick $A_1 = I$

$$\text{+ } A_2 = \underline{0}.$$

(13) $\text{rank}(B^T A^T) \leq \text{rank}(A^T)$ just by replacing A w/ B^T
+ B w/ A^T in

$\text{rank}(AB) \leq \text{rank}(B)$ How do we show

$\text{rank}(AB) \leq \text{rank}(A)$? By using the fact that

$$\text{rank}(A^T) = \text{rank}(A)$$

$$\text{+ } B^T A^T = (AB)^T$$

+ $\text{rank}((AB)^T) = \text{rank}(AB)$ so replacing both we get

~~rank~~ ~~rank~~ $\text{rank}(AB) \leq \text{rank}(A)$ the requested result

(18)

So A is $m \times n$ the R is $m \times n$ with ~~the~~ $m-r$ rows at the bottom rows

$$\begin{matrix} r \\ m-r \end{matrix} \left\{ \begin{bmatrix} 1 & x & \dots & x & 0 & x & \dots & x & 0 & x \\ 0 & 0 & & 0 & 1 & x & & x & 0 & x \\ \vdots & \vdots & & \vdots & \vdots & \vdots & & \vdots & \vdots & \vdots \\ 0 & 0 & & 0 & 0 & 0 & & 1 & x & 0 \\ & & & \vdots & \vdots & \vdots & & \vdots & \vdots & \vdots \end{bmatrix} \right.$$

$$\text{Then } R^T = \begin{bmatrix} 1 & 0 & 0 & & 0 \\ x & 0 & 0 & & 0 \\ \vdots & \vdots & \vdots & & \vdots \\ 0 & 1 & x & & 0 \\ \vdots & \vdots & \vdots & & \vdots \\ 0 & 0 & 0 & 1 & x \\ & & & \vdots & \vdots \end{bmatrix}$$

$\underbrace{\hspace{10em}}_r \quad \underbrace{\hspace{10em}}_{m-r \text{ columns of zeros}}$

is a matrix of size $n \times m$
with the last $m-r$ columns
zeros.

When we perform rref on R^T we get the following.

$$R^T \rightarrow \begin{bmatrix} 1 & 0 & 0 & \dots & 0 & 0 & 0 \\ 0 & 1 & 0 & \dots & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & \dots & 0 & 0 \\ & & & & & 1 & 0 \\ 0 & & & & & 0 & 1 \\ \vdots & & & & & \vdots & \vdots \end{bmatrix} = \begin{bmatrix} \overline{I} & | & 0 \\ \hline 0 & | & 0 \end{bmatrix}$$

$\begin{matrix} \uparrow r \\ \downarrow n-r \end{matrix} \quad \begin{matrix} \leftarrow r \rightarrow & \leftarrow m-r \rightarrow \end{matrix}$

with each submatrix
of dimension

I is $r \times r$; 0 in the $(1,2)$ block position of $r \times (m-r)$

0 in the $(2,1)$ block position of $(n-r) \times r$ + the 0
at position $(2,2)$ ~~$(n-r) \times m-r$~~ $(n-r) \times (m-r)$

Then $(\text{rref}(R^T))'$

is the row a matrix

$$\begin{array}{c} \uparrow r \\ \uparrow m-r \\ \left[\begin{array}{c|c} I & 0 \\ \hline 0 & 0 \end{array} \right] \end{array} \quad \begin{array}{c} \leftarrow r \rightarrow \quad \leftarrow n-r \rightarrow \end{array} \quad m \times n$$

or a matrix with the same size as

the original but ~~with the identity~~ of all zeros except for the identity in the upper left corner

(19) A' is of size $n \times m$.

then $\text{ref}(A') =$ $\left[\begin{array}{cccc} 1 & x & \dots & x \\ 0 & \dots & 1 & x \\ \vdots & & \vdots & \vdots \\ 0 & \dots & 0 & 1 \end{array} \right]$

$n-r$ rows

Then $\text{ref}(A')' =$ $\left[\begin{array}{cc} \begin{array}{c} 1 \\ x \\ x \\ x \end{array} & \begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \end{array} \\ \vdots & \vdots \end{array} \right]_{m \times n}$

$r \quad n-r$

so $\text{ref}(\text{ref}(A')') =$ $\left[\begin{array}{c|c} I & 0 \\ \hline 0 & 0 \end{array} \right]$

where I is of size $r \times r$

0 in the $(1,2)$ position

is of size $r \times (n-r)$, the ~~top~~ block zero in the
 (2,1) position is of size $(m-r) \times r$ + the ~~block~~ block
 zero in the position (2,2) is ~~just by~~ ^{at least} $(m-r) \times (n-r)$.

Which is the same result as in problem 18.

In one line the rank of $A + R$ or equivalent,
 thus $Y + Z$ or equivalent, because the form is
 completely determined by the rank which is the same
 between $A + A^T$.

$$(20) \quad [R \ E] = \text{rref}([A \ I])$$

$$[S \ F] = \text{rref}([R' \ I])$$

$$\text{So} \quad \cancel{R} E \quad EA = R \Rightarrow R^T = A^T E^T \\ + \quad FR' = S$$

E is of size ~~max~~ $n \times m$

+ F is of size $m \times n$

A
 $m \times n$

R'
 $n \times m$

$$\text{So} \quad S = FR^T = F(A^T E^T)$$

Then $Z = S^T = EA F^T$ ~~is the relationship between Z~~

So to relate Z to the original R we have

$$A = \cancel{E} E^T R$$

giving ~~A~~ $Z = E(E^T R) F^T = R F^T$

which is a combination of the columns of R .

Problem 2, Section 3.4

~~Now we have 2 special solutions to find to $Ax=0$~~

Try In ²

let $x_2 = 1$ + $x_4 = 0$ + we find that x_1 + x_3 must solve

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_3 \end{bmatrix} = -\begin{bmatrix} 3 \\ 0 \end{bmatrix} \Rightarrow x_1 = -3; x_3 = 0$$

let $x_2 = 0$ + $x_4 = 1$ + we find that x_1 + x_3 must solve

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ -2 \end{bmatrix} \Rightarrow x_1 = 0, x_3 = -2.$$

Thus our total solution x to this problem is given by

$$x = \begin{bmatrix} 1/2 \\ 0 \\ 1/2 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$

We can check this with

$$Ax = \begin{bmatrix} 1 & 3 & 1 & 2 \\ 2 & 6 & 4 & 8 \\ 0 & 0 & 2 & 4 \end{bmatrix} \left(\begin{bmatrix} 1/2 \\ 0 \\ 1/2 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 0 \\ -2 \\ 1 \end{bmatrix} \right)$$

$$= \begin{bmatrix} 1 \\ 1+2 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} -3+3 \\ -6+6 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -2+2 \\ -8+8 \\ -4+4 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix}$$

③ consider
$$\begin{bmatrix} 1 & 2 & -2 & b_1 \\ 2 & 5 & -4 & b_2 \\ 4 & 9 & -8 & b_3 \end{bmatrix}$$

Then reduction of this system to reduced row echelon form gives

$$\Rightarrow \begin{bmatrix} 1 & 2 & -2 & b_1 \\ 0 & 1 & 0 & b_2 - 2b_1 \\ 0 & 1 & 0 & b_3 - 4b_1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & -2 & b_1 - 2(b_2 - 2b_1) \\ 0 & 1 & 0 & b_2 - 2b_1 \\ 0 & 0 & 0 & b_3 - 4b_1 - b_2 + 2b_1 \end{bmatrix}$$

Thus so that the 3rd row is consistent we ~~see~~ ^{see} that

$$b_3 - 4b_1 - b_2 + 2b_1 = 0$$

or $-2b_1 - b_2 + b_3 = 0$ is ~~required~~ required for this system to

be solvable. If this condition ~~holds~~ holds true we have a rank of 2 + a null space of dimension 1.

Solving for a particular solution x_p we ~~set~~ ^{set} the free variables equal to 0 + solve for the pivot variables. Performing this gives

$$x_1 = b_1 - 2(b_2 - 2b_1) = b_1 - 2b_2 + 4b_1 = 5b_1 - 2b_2$$

$$x_2 = -2b_1 + b_2 \quad \text{+} \quad x_3 = 0$$

Then to find a basis for the null space set $x_3 = 1$ + solve for

x_1 + x_2 . we obtain

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix} \quad \text{giving } x_1 = 2 \text{ + } x_2 = 0$$

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We can check this solution with

$$X = x_p + x_h = \begin{bmatrix} 5b_1 - 2b_2 \\ -2b_1 + b_2 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}$$

lets check this solution

$$\begin{aligned} & \begin{bmatrix} 1 & 2 & -2 \\ 2 & 5 & -4 \\ 4 & 9 & -8 \end{bmatrix} \begin{bmatrix} 5b_1 - 2b_2 \\ -2b_1 + b_2 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 1 & 2 & -2 \\ 2 & 5 & -4 \\ 4 & 9 & -8 \end{bmatrix} \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 5b_1 - 2b_2 + 2(-2b_1 + b_2) \\ 2(5b_1 - 2b_2) + 5(-2b_1 + b_2) \\ 4(5b_1 - 2b_2) + 9(-2b_1 + b_2) \end{bmatrix} + x_3 \begin{bmatrix} 2-2 \\ 4-4 \\ 8-8 \end{bmatrix} \\ &= \begin{bmatrix} b_1 \\ b_2 \\ 20b_1 - 8b_2 - 18b_1 + 9b_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \underbrace{2b_1 + b_2}_{b_3 \text{ for consistency}} \end{bmatrix} \end{aligned}$$

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(4) For the 1st problem

$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \\ 2 & 5 \\ 3 & 9 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix} \quad \text{From the augmented matrix}$$

$$A = \begin{bmatrix} 1 & 2 & b_1 \\ 2 & 4 & b_2 \\ 2 & 5 & b_3 \\ 3 & 9 & b_4 \end{bmatrix} \quad \text{then perform row reduction on it obtaining}$$

$$\rightarrow \begin{bmatrix} 1 & 2 & b_1 \\ 0 & 0 & b_2 - 2b_1 \\ 0 & 1 & b_3 - 2b_1 \\ 0 & 3 & b_4 - 3b_1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & b_1 \\ 0 & 1 & b_3 - 2b_1 \\ 0 & 3 & b_4 - 3b_1 \\ 0 & 0 & b_2 - 2b_1 \end{bmatrix}$$

$$\text{So } b_2 - 2b_1 = 0$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & b_1 - 2(b_3 - 2b_1) \\ 0 & 1 & b_3 - 2b_1 \\ 0 & 0 & b_4 - 3b_1 - 3(b_3 - 2b_1) \\ 0 & 0 & b_2 - 2b_1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 5b_1 - 2b_3 \\ 0 & 1 & -2b_1 + b_3 \\ 0 & 0 & b_4 - 3b_1 - 3b_3 + 6b_1 \\ 0 & 0 & -2b_1 + b_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 5b_1 - 2b_3 \\ 0 & 1 & -2b_1 + b_3 \\ 0 & 0 & 3b_1 - 3b_3 + b_4 \\ 0 & 0 & -2b_1 + b_2 \end{bmatrix}$$

So in addition we must also have

$3b_1 - 3b_3 + b_4 = 0$. From the above the rank of this matrix is 2 + since $n=2$ the dimension of the

null space is $n-r = 2-2 = 0$. Thus the only solution

$$x_1 = 5b_1 - 2b_3$$

$$x_2 = -2b_1 + b_3$$

For the 2nd system ~~again~~ again form the augmented matrix

$$\begin{bmatrix} 1 & 2 & 3 & b_1 \\ 2 & 4 & 6 & b_2 \\ 2 & 5 & 7 & b_3 \\ 3 & 9 & 12 & b_4 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 3 & b_1 \\ 0 & 0 & 0 & b_2 - 2b_1 \\ 0 & 1 & 1 & b_3 - 2b_1 \\ 0 & 3 & 3 & b_4 - 3b_1 \end{bmatrix}$$

exchanging row 2 + row 4 we have

$\Rightarrow$

$$\begin{bmatrix} 1 & 2 & 3 & b_1 \\ 0 & 1 & 1 & b_3 - 2b_1 \\ 0 & 3 & 3 & b_4 - 3b_1 \\ 0 & 0 & 0 & b_2 - 2b_1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 1 & b_1 - 2b_3 + 4b_1 \\ 0 & 1 & 1 & b_3 - 2b_1 \\ 0 & 0 & 0 & b_4 - 3b_1 - 3(b_3 - 2b_1) \\ 0 & 0 & 0 & b_2 - 2b_1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 1 & 3b_1 - 2b_3 & 5b_1 - 2b_3 \\ 0 & 1 & 1 & -2b_1 + b_3 \\ 0 & 0 & 0 & \cancel{b_4 - 3b_1 - 3b_3 + 6b_1} & \cancel{-b_1 - b_3 + b_4} \\ 0 & 0 & 0 & b_2 - 2b_1 \end{bmatrix} \leftarrow \cancel{b_4 - 3b_1 - 3b_3 + 6b_1} \quad 3b_1 - 3b_3 + b_4$$

Thus for a solution we must have

$$b_2 - 2b_1 = 0 \quad + \quad \frac{-b_1 - b_3 + b_4}{3b_1 - 3b_3 + b_4} = 0$$

Thus since $n=3$ + the rank is $r=2$ so the dimension of the null space is $n-r = 3-2=1$.

Setting the free variable $x_3=0$ we get one particular solution of

$$x_1 = \cancel{3b_1 - 2b_3} \quad 5b_1 - 2b_3$$

$$+ x_2 = -\cancel{2b_1 + b_3} \quad -2b_1 + b_3$$

+ a vector in the null space is given by assigning the free variable to be 1 + then we have

$$x_1 = -1$$

$$x_2 = -1$$

so $\underline{x} = x_3 \begin{bmatrix} \cancel{5} \\ \cancel{3} \\ \cancel{1} \\ \cancel{1} \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$

lets check this

$$\begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 2 & 5 & 7 \\ 3 & 9 & 12 \end{bmatrix} \begin{bmatrix} 5b_1 - 2b_3 \\ -2b_1 + b_3 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 5b_1 - \cancel{2b_3} - 4b_1 + \cancel{2b_3} \\ 10b_1 - \cancel{4b_3} - 8b_1 + \cancel{4b_3} \\ \cancel{10b_1} - 4b_3 - \cancel{10b_1} + 5b_3 \\ 15b_1 - 6b_3 - 18b_1 + 9b_3 \end{bmatrix} + x_3 \begin{bmatrix} -1 - 2 + 3 \\ -2 - 4 + 6 \\ -2 - 5 + 7 \\ -3 - 9 + 12 \end{bmatrix}$$

$$= \begin{bmatrix} b_1 \\ 2b_1 \\ b_3 \\ -3b_1 + 3b_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix} \quad \checkmark$$

5 Forming the augmented matrix we have

$$[A|b] = \left[\begin{array}{ccc|c} 1 & 3 & 1 & b_1 \\ 3 & 8 & 2 & b_2 \\ 2 & 4 & 0 & b_3 \end{array} \right]$$

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & 3 & 1 & b_1 \\ 0 & -1 & -1 & b_2 - 3b_1 \\ 0 & -2 & -2 & b_3 - 2b_1 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|c} 1 & 3 & 1 & b_1 \\ 0 & 1 & 1 & -b_2 + 3b_1 \\ 0 & -2 & -2 & b_3 - 2b_1 \end{array} \right]$$

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & -2 & b_1 - 3(-b_2 + 3b_1) \\ 0 & 1 & 1 & -b_2 + 3b_1 \\ 0 & 0 & 0 & b_3 - 2b_1 - 2b_2 + 6b_1 \end{array} \right]$$

$$= \left[\begin{array}{ccc|c} 1 & 0 & -2 & 4b_1 - 2b_2 + b_3 \\ 0 & 1 & 1 & 3b_1 - b_2 \\ 0 & 0 & 0 & 4b_1 - 2b_2 + b_3 \end{array} \right]$$

This matrix has rank 2 & a null space of

dimension equal to 1

to have a solution we must have $4b_1 - 2b_2 + b_3 = 0$

& the particular solution is given by can be obtained by setting

the first variable equal to zero & solving for

$x_1 + x_2$

This gives $x_1 = -8b_1 + 3b_2$

+ $x_2 = 3b_1 - b_2$

The A basis for the null space can be determined by setting $x_3 = 1$
 + solving for x_1 + x_2 . we get

$$\underline{x} = x_3 \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$$

we can check w/

$$\begin{bmatrix} 1 & 3 & 1 \\ 3 & 8 & 2 \\ 2 & 4 & 0 \end{bmatrix} \left(\begin{bmatrix} -8b_1 + 3b_2 \\ 3b_1 - b_2 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} \right)$$

$$= \begin{bmatrix} -8b_1 + 3b_2 + 9b_1 - 3b_2 \\ -24b_1 + 9b_2 + 24b_1 - 8b_2 \\ -16b_1 + 6b_2 + 12b_1 - 4b_2 \end{bmatrix} + x_3 \begin{bmatrix} 2 - 3 + 1 \\ 6 - 8 + 2 \\ 4 - 4 \end{bmatrix}$$

$$= \begin{bmatrix} b_1 \\ b_2 \\ -4b_1 + 2b_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} \quad \checkmark$$

The combination of the rows that gives 700 is ~~the~~ a vector such that $y^T A = 0$

or $A^T y = 0$ so y is in the null space of A^T .

~~But from the row elimination a basis for the~~
 one could do Gauss Jordan elimination on A^T to derive the null space of A^T or consider that

$$4b_1 - 2b_2 + b_3 = 0 \quad \text{so the unknowns}$$

$$\begin{bmatrix} 4 \\ -2 \\ 1 \end{bmatrix} \text{ of the rows gives the row vector}$$

The last $m-r$ rows of E give a basis for the left null space

(6)

$$\text{Let } A = \left[\begin{array}{ccc|c} 1 & 2 & 1 & b_1 \\ 2 & 6 & 3 & b_2 \\ 0 & 2 & 5 & b_3 \end{array} \right]$$

$$\text{Then } \left[\begin{array}{ccc|c} 1 & 2 & 1 & b_1 \\ 0 & 2 & 1 & b_2 - 2b_1 \\ 0 & 2 & 5 & b_3 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|c} 1 & 2 & 1 & b_1 \\ 0 & 1 & \frac{1}{2} & \frac{1}{2}(b_2 - 2b_1) \\ 0 & 2 & 5 & b_3 \end{array} \right]$$

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 0 & b_1 - b_2 + 2b_1 \\ 0 & 1 & \frac{1}{2} & \frac{1}{2}(b_2 - 2b_1) \\ 0 & 0 & 4 & b_3 - b_2 + 2b_1 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 0 & 3b_1 - b_2 \\ 0 & 1 & \frac{1}{2} & \frac{1}{2}(b_2 - 2b_1) \\ 0 & 0 & 1 & \frac{1}{4}(b_3 - b_2 + 2b_1) \end{array} \right]$$

$$\Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 0 & 3b_1 - b_2 \\ 0 & 1 & 0 & \frac{1}{2}(b_2 - 2b_1) - \frac{1}{8}(b_3 - b_2 + 2b_1) \\ 0 & 0 & 1 & \frac{1}{4}(b_3 - b_2 + 2b_1) \end{array} \right]$$

Which has a complete set of pivots $\therefore$ any vector is in the column space. The rank is 3
 $\therefore$ the only combination of the rows that gives zero is when all rows are multiplied by zero,
 i.e. No combination of the rows give zero.

For pt (b) we have for an augmented matrix

$$\begin{bmatrix} 1 & 1 & 1 & b_1 \\ 1 & 2 & 4 & b_2 \\ 2 & 4 & 8 & b_3 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 & 1 & b_1 \\ 0 & 1 & 3 & b_2 - b_1 \\ 0 & 2 & 6 & b_3 - 2b_1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & -2 & b_1 + b_1 - b_2 \\ 0 & 1 & 3 & b_2 - b_1 \\ 0 & 0 & 0 & b_3 - 2b_1 - 2b_2 + 2b_1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & -2 & 2b_1 - b_2 \\ 0 & 1 & 3 & b_2 - b_1 \\ 0 & 0 & 0 & b_3 - 2b_2 \end{bmatrix}$$

Thus for a solution ^{we must have} $b_3 - 2b_2 = 0$ to be in the column space
so $\mathbb{R}$ vectors of the form $\begin{pmatrix} b_1 \\ b_2 \\ 2b_2 \end{pmatrix}$.

Combinations of the rows that give zero are

$$(0, -2, 1)$$

$$\textcircled{7} \quad x_p = \begin{pmatrix} 2 \\ 4 \\ 0 \end{pmatrix}$$

$$x_n = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

let x_3 be the pivot variable

$$\begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

So the system is

$$\begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

Then this coefficient matrix has rank 2 & the nullity is given by $3-2=1$

let $x_3 = 0$ to get $x_1 = 2; x_2 = 4$

to get the null space let $x_3 = 1$ & solve for x_1 & x_2 .

$\textcircled{8}$ I ~~can~~ 1×3 system (Not all zeros)

is of rank 1 so the nullity then must be of dimension

$3-1=2$ & would require two basis functions

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(9) (a) let $v = x_1 - x_2$ then $Av = Ax_1 - Ax_2 = b - b = 0$

(b) Another solution to $Ax = 0$ is $c \cdot v$

$$\text{Since } A(cv) = cAv = c \cdot 0 = 0$$

Another solution to $Ax = b$ is $x = x_1 + cv$

$$\text{Since } Ax = Ax_1 + cAv = Ax_1 = b$$

(10) (a) ~~x_p must be multiplied by 1 arbitrary combinations are not allowed.~~

~~(b) See prob 13... from 3rd edition.~~

~~(c) See prob 13 from the 3rd edition~~

~~(d) See prob 13 from 3rd edition~~

Next few pages

(11) x_5 is a free variable. ~~The~~ Zero vector is not the only solution to $Ax = 0$ since column 5 ~~can~~ is a free variable

can be expressed as a linear combination of earlier columns.

If $Ax = b$ has a solution then it has infinitely many solutions

(12) row 3 has no pivot. Then that row is zero.

Eg $Ux = c$ is only solvable if the 3rd elt in c is

zero. The equation $Ax = b$ (might not be solvable)

one must have $\oplus$ if E is the elementary eliminator

Matrix that takes A to U the

$Eb = c$ + the appropriate combination ~~row~~ of b must sum to zero i.e. $b(3) = 0$ to be solvable

(13) largest rank is 3. Then there is a pivot in every row of U . The solution to $Ax = b$ always exists. The ~~null space~~ ^{row} of A is column space of A linearly ~~degenerate~~ dependent.

An example might be $A = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix}$

(14) largest possible rank of 6×4 matrix is 4. There is a pivot in every column of U . The solution of $Ax = b$ is unique (if it exists). The null space of A is the zero vector

An example of A is $A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

(15)

$$A = \begin{bmatrix} 1 & 4 & 0 \\ 2 & 11 & 5 \\ -1 & 2 & 10 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 4 & 0 \\ 0 & 3 & 5 \\ 0 & 6 & 10 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 4 & 0 \\ 0 & 1 & 5/3 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \text{which has rank 2}$$

$$A^T = \begin{bmatrix} 1 & 2 & -1 \\ 4 & 11 & 2 \\ 0 & 5 & 10 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & -1 \\ 0 & 3 & 6 \\ 0 & 5 & 10 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & 2 \\ 0 & 1 & 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & -5 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{which has rank 2}$$

$$\text{For } A = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ 1 & 1 & q \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & q-1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & q-2 \end{bmatrix}$$

~~It is not rank 2~~

It $q=2$ A is of rank 2. If $q \neq 2$ A is of rank 3

$$A^T = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 1 & 2 & q \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & q-1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & q-2 \end{bmatrix}$$

Which if $q \neq 2$ is of rank 3 & if $q=2$ is of rank 2

$$(16) \quad A = \begin{bmatrix} 1 & 1 & 5 \\ 1 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 5 \\ 0 & -1 & -4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & -1 & -4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 4 \end{bmatrix}$$

which is of rank 2.

$$A^T A = \begin{bmatrix} 1 & 1 \\ 1 & 0 \\ 5 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 5 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 6 \\ 1 & 1 & 5 \\ 6 & 5 & 26 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 5 \\ 2 & 1 & 6 \\ 6 & 5 & 26 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 1 & 5 \\ 0 & -1 & -4 \\ 0 & -1 & -4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 5 \\ 0 & 1 & 4 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{which is of rank 2}$$

$$A A^T = \begin{bmatrix} 1 & 1 & 5 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 0 \\ 5 & 1 \end{bmatrix} = \begin{bmatrix} 2+25 & 1+5 \\ 6 & 1+1 \end{bmatrix} = \begin{bmatrix} 27 & 6 \\ 6 & 2 \end{bmatrix}$$

$\Rightarrow$ which since $27 \cdot 2 - 12 \neq 0$ is ~~of rank 2~~ invertible $\therefore$ of rank 2

$$\text{For } A = \begin{bmatrix} 2 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 \\ 2 & 0 \\ 1 & 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 \\ 0 & -2 \\ 0 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \quad \text{which}$$

is of rank 2

$$A^T A = \begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 4+1+1 & 1+2 \\ 1+2 & 1+4 \end{bmatrix}$$

$$= \begin{bmatrix} 6 & 3 \\ 3 & 5 \end{bmatrix} \text{ which since } 6 \cdot 5 - 3^2 \neq 0 \text{ is invertible } \therefore \text{ of rank 2}$$

$$\text{Now } AA^T = \begin{bmatrix} 2 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} = \begin{bmatrix} 4 & 2 & 2 \\ 2 & 2 & 3 \\ 2 & 3 & 5 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 1/2 & 1/2 \\ 2 & 2 & 3 \\ 2 & 3 & 5 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1/2 & 1/2 \\ 0 & 1 & 2 \\ 0 & 2 & 4 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1/2 & 1/2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

which is of rank 2

$$(17) \quad A = \begin{bmatrix} 3 & 4 & 1 & 0 \\ 6 & 5 & 2 & 1 \end{bmatrix}$$

$$\text{let } E_{21} = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix} \text{ then}$$

$$E_{21}A = \begin{bmatrix} 3 & 4 & 1 & 0 \\ 0 & -3 & 0 & 1 \end{bmatrix} = U$$

$$\text{Then } L = E_{21}^{-1} = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}$$

$$\therefore A = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 3 & 4 & 1 & 0 \\ 0 & -3 & 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 2 & 2 & 0 & 3 \\ 0 & 6 & 5 & 4 \end{bmatrix}$$

Then let $E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Then $E_{21}A = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 2 & -2 & 3 \\ 0 & 6 & 5 & 4 \end{bmatrix}$

let $E_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -3 & 1 \end{bmatrix}$ then

~~Then~~ $E_{32}E_{21}A = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 2 & -2 & 3 \\ 0 & 0 & 11 & -5 \end{bmatrix} = U$

So $A = E_{21}^{-1}E_{32}^{-1}U$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 2 & -2 & 3 \\ 0 & 0 & 11 & -5 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 2 & -2 & 3 \\ 0 & 0 & 11 & -5 \end{bmatrix}$$

(18) (a) $x + y + z = 4$

$A = [1 \ 1 \ 1]$ which has $\text{rank} = 1$ $\therefore$ a nullity of dimension $3 - 1 = 2$. The free variables are y & z so a particular solution can be obtained by assigning $y = 0, z = 0$ to get $x = 4$ $\therefore x_p = \begin{bmatrix} 4 \\ 0 \\ 0 \end{bmatrix}$. To find the null space

let ~~$x = 1$~~ $y = 1$ & $z = 0$ & solve for x

to get $x + 1 + 0 = 0 \Rightarrow x = -1$

giving $v_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$

let $y = 0$ & $z = 1$ to get

~~$x = 1$~~ $x + 0 + 1 = 0 \Rightarrow x = -1$

giving $v_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$

Thus our solution vector v is

$$v = \begin{bmatrix} 4 \\ 0 \\ 0 \end{bmatrix} + y \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + z \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

(b) For the 2nd system or ~~or~~ $A = \begin{bmatrix} 1 & 1 & 1 & 4 \\ 1 & -1 & 1 & 4 \end{bmatrix}$

$$\Rightarrow \begin{bmatrix} 1 & 1 & 1 & 4 \\ 0 & -2 & 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 & 1 & 4 \\ 0 & 1 & 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 1 & 4 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

which is of rank = 2. Thus z is a free variable. Letting

$z=0$ we have a particular solution of $x=4$ & $y=0$

The letting $z=1$ we have a null space solution of

$x=-1$ & $y=0$. Giving a total solution of

$$\underline{V} = \begin{bmatrix} 4 \\ 0 \\ 0 \end{bmatrix} + z \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

(19) The # of solutions depends on the rank of the column space

or the rank of the matrix A . If to have no solutions we

must have a null space of dimension at least 1

So $n-r \geq 1$ to begin with a different right hand

side will not change this. If $m > r$ we have zero rows

in the reduced row echelon form for A & thus constraints

that must be satisfied on the right hand side. If these

constraints are not satisfied no solution exists

$$(20) A = \begin{bmatrix} 6 & 4 & 2 \\ -3 & -2 & -1 \\ q & 6 & q \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & \frac{2}{3} & \frac{1}{3} \\ -3 & -2 & -1 \\ q & 6 & q \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & \frac{2}{3} & \frac{1}{3} \\ 0 & 0 & 0 \\ 0 & 6 - \frac{2}{3}q & q - \frac{1}{3}q \end{bmatrix} = \begin{bmatrix} 1 & \frac{2}{3} & \frac{1}{3} \\ 0 & 0 & q-3 \\ 0 & 0 & 0 \end{bmatrix}$$

Which ~~for~~ if $q \neq 3$ has rank 2 or if $q=3$ is not rank 1.

$$\text{For } B = \begin{bmatrix} 3 & 1 & 3 \\ q & 2 & q \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & \frac{1}{3} & 1 \\ q & 2 & q \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & \frac{1}{3} & 1 \\ 0 & 2 - \frac{q}{3} & q - 1 \end{bmatrix}$$

Then ~~if~~ if $2 - \frac{q}{3} = 0 \Rightarrow q = 6$ B is of rank 1.

if $q \neq 6$ B is of rank 2

$$(21) A = \begin{bmatrix} 1 & 2 & 4 \\ 2 & & \\ 4 & & \end{bmatrix} \text{ can only have one unique row/column}$$

so the others ~~must~~ must be multiples of the 1st

$$\Rightarrow A = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 4 & 8 \\ 4 & 8 & 16 \end{bmatrix}$$

$$B = \begin{bmatrix} 2 \\ 1 \\ 2 \quad 6 \quad -3 \end{bmatrix}$$

Again can only have multiples of a given row or column so constructing rows 1 + 2 from 3 we have

$$B = \begin{bmatrix} 2 & 6 & -3 \\ 1 & 3 & -3/2 \\ 2 & 6 & -3 \end{bmatrix}$$

$$M = \begin{bmatrix} a & b \\ c & \cdot \end{bmatrix} \quad \text{Follows the Schur pattern}$$

$$\rightarrow \begin{bmatrix} a & b \\ c & \frac{c}{a} \cdot b \end{bmatrix}$$

(22) The column ~~space~~ space is a line in $\mathbb{R}^M$.

The nullspace is a plane in $\mathbb{R}^N$. The column space of A^T = row space of A is a line in $\mathbb{R}^N$.

(23) $A = UV^T$ for

U column v the multiples of the column to get A

$$A = \begin{bmatrix} 3 & 6 & 6 \\ 1 & 2 & 2 \\ 4 & 8 & 8 \end{bmatrix}$$

$$= \begin{bmatrix} 3 \\ 1 \\ 4 \end{bmatrix} \begin{bmatrix} 1 & 2 & 2 \end{bmatrix}$$

$$\text{For } A = \begin{bmatrix} 2 & 2 & 6 & 4 \\ -1 & -1 & -3 & -2 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 3 & 2 \end{bmatrix}$$

(24) A is rank 1 the 2nd row of U is zero.

$$\text{let } A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$$

$$4+12=16$$

$$2+4$$

$$4+12$$

$$8+24=32$$

(25) $AB = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} 2 & 4 & 4 \\ 3 & 3/2 & 6 \end{bmatrix} = \begin{bmatrix} 8 & 4 & 16 \\ 16 & 8 & 32 \end{bmatrix}$

which is rank 1

$$A\vec{v} = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} 1 & b \\ c & bc \end{bmatrix} = \begin{bmatrix} 1+2c & b+2bc \\ 2+4c & 2b+4bc \end{bmatrix}$$

$$= \begin{bmatrix} 1+2c & b+2bc \\ 2(1+2c) & 2b(1+2c) \end{bmatrix}$$

which is rank 1

(26) $(U \cdot v^T)(w z^T) = U(v^T w) z^T = (v^T w) \cdot U z^T$

times the number $v^T w$. This has rank one unless

$$v^T w = 0$$

(27) (a) $\begin{bmatrix} 1 & 2 & x_1 & 1 \\ 2 & 4 & x_2 & b_2 \end{bmatrix}$

if $b_2 = 2$ we have a

(a) see next p

(b) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$

has $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ in the null space & $\therefore$ always has an ∞ # of solutions

(a) out

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

consider $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$

then we require $b_1 + b_2 = b_3$ or $b_1 + b_2 = b_3$ if true then we have a solution, if this is true then the solution is $x = b_1$ & $y = b_2$.
 If not only one solution, if not we have no solutions.

(c) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$

Again ~~we~~ we must have

$x + y = b_3$ but $x = b_1$ & $y = b_2$ so we have

the condition that $b_1 + b_2 = b_3$ if true then we have an ∞ # of solutions (null space is not empty) if not

No solutions

(d) $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

139 steps

28

(a) To have no solution we must have a contradictory equation

Thus $r < m$ so that one row in the reduced row echelon form is all zero (the corresponding component in b will then not be zero). Then

(b) $r < n$ since ~~there are~~ we must have ~~at least~~ a non zero null space i.e. more columns (free variables) than pivots (the rank of A)

(c) Again as in part (a) we must have $r < m$ ~~is not~~

~~It will have a non zero null space~~ In this case

if E is the elimination matrix that turns A into R .

i.e. $EA = R$ where $r < m$ will have zero rows

The $Ax = b$ requires

$$EAX = Eb$$

Therefore the zero rows of EAX must have a corresponding

zero elements of Eb , thus ~~restricting~~ restricting the types of b 's that solutions exist for

(d) If $m = n = r$ then we have one solution for every b .

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$$(29) \quad V = \begin{bmatrix} 2 & 4 & 4 \\ 0 & 3 & 6 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\text{For } V = \begin{bmatrix} 2 & 4 & 4 \\ 0 & 3 & 6 \\ 0 & 0 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(30) Since V is square each pivot has pivot magnitude of 1 & zeros above and below i.e. it is the identity.

$$(31) \quad [V \ 0] = \begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & 0 & 4 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

~~we~~ set the free variable $x_2 = 1$ to obtain the null solution



$$\text{so } x_3 = 0$$

$$x_1 = -2$$

$$\text{so } x_n = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}$$

to find x_p perform Gauss Jordan elimination

we have

$$\begin{bmatrix} 1 & 2 & 3 & 5 \\ 0 & 0 & 4 & 8 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 & 5 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 2 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

So setting the x_2 variable $x_2 = 0$ then $x_1 = -1$ + $x_3 = 2$

$$\text{so } \underline{x} = \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$$

$$(32) \quad [U \ 0] = \begin{bmatrix} 3 & 0 & 6 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

So x_1 & x_3 are pivot variables

x_2 , ~~or~~ x_4 is a free variable

the null vector ~~for~~ pick $x_2 = 1$ + solve for x_1 + x_3

$$x_1 = 0 + x_3 = 0 \text{ giving } \underline{x}_n = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

The particular solution is given by

$$[U \ c] = \begin{bmatrix} 3 & 0 & 6 & 9 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 2 & 3 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 5 \end{bmatrix}$$

But from the last row no solution can exist

33) $Ax = b$

$$\Rightarrow \left[\begin{array}{cccc|c} 1 & 0 & 2 & 3 & 2 \\ 1 & 3 & 2 & 0 & 5 \\ 2 & 0 & 4 & 9 & 10 \end{array} \right] \Rightarrow \left[\begin{array}{cccc|c} 1 & 0 & 2 & 3 & 2 \\ 0 & 3 & 0 & -3 & 3 \\ 0 & 0 & 0 & 3 & 6 \end{array} \right] \quad \text{Gauss elimination}$$

$$\Rightarrow \left[\begin{array}{cccc|c} 1 & 0 & 2 & 3 & 2 \\ 0 & 1 & 0 & -1 & 1 \\ 0 & 0 & 0 & 1 & 2 \end{array} \right] \Rightarrow \left[\begin{array}{cccc|c} 1 & 0 & 2 & 0 & -4 \\ 0 & 1 & 0 & 0 & 3 \\ 0 & 0 & 0 & 1 & 2 \end{array} \right] \quad \text{Gauss-Jordan elimination}$$

The pivot variables are x_1, x_2 , & x_4 with x_3 a free variable.

The particular solution is given by taking $x_3 = 0$ & we get

$$x_1 = -4; x_2 = 3; x_4 = 2 \quad \text{giving}$$

$$x_p = \begin{bmatrix} -4 \\ 3 \\ 0 \\ 2 \end{bmatrix}$$

For the ~~homogeneous~~ homogeneous solution set the free variable to 1 & solve for the pivot variables

i.e.

$$x_1 = -2, x_2 = 0, x_3 = 1, x_4 = 0$$

giving

$$x_h = \begin{bmatrix} -2 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

(34) The only solution of $Ax = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ is $x = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

So A must be 2×3 + the requirement that

$$Ax = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \text{ requires that } A = \begin{bmatrix} x & 1 \\ x & 2 \\ x & 3 \end{bmatrix}$$

~~which has rank~~ to have 1 solution the rank must equal n

The # of variables so that the null space is zero. This can be

$$\text{obtained if we fill } A \text{ w/ } A = \begin{bmatrix} 1 & 1 \\ 0 & 2 \\ 0 & 3 \end{bmatrix}$$

For B the only solution to

$$Bx = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \text{ is } x = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \text{ so } B \text{ is } \cancel{3 \times 2} 2 \times 3$$

Thus ~~we~~ to have only one solution we must have a zero null

space so $n-r = 0 = 3-r = 0 \rightarrow r=3$ but this is not possible

Since we ~~could~~ would have to see ~~if~~ ~~the~~ ~~vectors~~ ~~are~~ ~~linearly~~ ~~independent~~

$$\begin{bmatrix} x & x & x \\ x & x & x \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

~~independent~~

3 linearly independent vectors which

is not possible since they are elements of $\mathbb{R}^2$. (only

two linearly independent vectors can exist. So this is not possible.

35) let the concatenated system be

$[A|b|b_2]$ + we get

$$\begin{bmatrix} 1 & 3 & 1 & 1 & 1 \\ 1 & 2 & 3 & 3 & 0 \\ 2 & 4 & 6 & 6 & 0 \\ 1 & 1 & 5 & 8 & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 1 \\ 1 & 2 & 3 \\ 2 & 4 & 6 \\ 1 & 1 & 5 \end{bmatrix}$$

let $E_2 A =$ $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

$$\rightarrow \begin{bmatrix} 1 & 3 & 1 \\ 0 & -1 & 2 \\ 0 & -2 & 4 \\ 0 & -2 & 4 \end{bmatrix} \rightarrow \left\{ \begin{array}{l} \text{When } E_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ -2 & 0 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{bmatrix} \end{array} \right.$$

$$\rightarrow \begin{bmatrix} 1 & 3 & 1 \\ 0 & 1 & -2 \\ 0 & -2 & 4 \\ 0 & 0 & 0 \\ & -2 & 4 \end{bmatrix} \quad w/ \quad E_2 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 3 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad w/ \quad E_3 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 2 & 0 & 1 \end{bmatrix}$$

$$\Leftrightarrow \quad E_3 E_2 E_1 A = L$$

$$\Rightarrow A = E_1^{-1} E_2^{-1} E_3^{-1} L$$

$$\therefore A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 2 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -2 & 1 & 0 \\ 0 & -2 & 0 & 1 \end{bmatrix} U$$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 2 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 2 & 0 & 1 \end{bmatrix} U$$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 2 & 2 & 1 & 0 \\ 1 & 2 & 0 & 1 \end{bmatrix} U$$

Then $LUx = b$

let $Ly = b$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 2 & 2 & 1 & 0 \\ 1 & 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ 6 \\ 5 \end{bmatrix}$$

$$\Rightarrow y_1 = 1 ; -y_2 = 3 - 1 = y_2 = -2$$

$$y_3 = 6 - 2y_1 - 2y_2 = 6 - 2(1) - 2(-2) \\ = 4 + 4 = 8$$

$$y_4 = 5 - y_1 - 2y_2 = 5 - 1 - 2(-2) = 5 - 1 + 4 = 8$$

Then solve for

$$Ux = y$$

$$\Rightarrow \begin{bmatrix} 1 & 3 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 8 \\ 8 \end{bmatrix}$$

which can have no solution since the last two rows are not zero. So we have no solution.

For the 2nd set of b's, we have

$Ly = b$ is

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 2 & 2 & 1 & 0 \\ 1 & 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$y_1 = 1; \quad 1 - y_2 = 0 \Rightarrow y_2 = 1; \quad 2 + 2 + y_3 = 0 \Rightarrow y_3 = -4;$$

$$1 + 2 + y_4 = 0 \Rightarrow y_4 = -3$$

$$\text{So } y = \begin{bmatrix} 1 \\ 1 \\ -4 \\ -3 \end{bmatrix}$$

then $Ux = y$ is

$$\begin{bmatrix} 1 & 3 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ -4 \\ -3 \end{bmatrix}$$

Again, no ~~scalar~~ ~~matrix~~

$$(36) \quad Ax = A \begin{bmatrix} 1 \\ 0 \end{bmatrix} + cA \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

$$\text{So } A = \begin{bmatrix} 1 & x \\ 3 & x \end{bmatrix} \text{ to have a nullspace of } \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\text{we must have } A = \begin{bmatrix} 1 & 0 \\ 3 & 0 \end{bmatrix}$$

pg 150 Strong

- ① To show $v_1, v_2, + v_3$ are independent let we can construct a matrix with $v_1, v_2, + v_3$ as its column + show that this matrix has 3 pivots. Such a matrix looks like

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ + has 3 pivots } \therefore v_1, v_2, + v_3 \text{ are independent}$$

To show that $v_1, v_2, v_3, + v_4$ are dependent we have to show that a matrix with these vectors as columns will have at least one free variable.

$$\begin{bmatrix} 1 & 1 & 1 & 2 \\ 0 & 1 & 1 & 3 \\ 0 & 0 & 1 & 4 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 1 & 3 \\ 0 & 0 & 1 & 4 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 4 \end{bmatrix}$$

which has x_4 as a free variable + $\therefore v_1, v_2, v_3, + v_4$ cannot be linearly independent.

pg 150 Stray

- ② We can have at maximum 4 linearly independent vectors from the set of vectors in $\mathbb{R}^4$.

v_1, v_2, v_3 are linearly independent by observation. To find the linearly independent vectors we can form the matrix of concatenated column vectors & perform row reduction.

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 0 \\ 7 & 0 & 0 & 1 & 1 & 0 \\ 0 & 7 & 0 & -1 & 0 & 1 \\ 0 & 0 & -1 & 0 & -1 & -1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 1 & 0 \\ 0 & 7 & 0 & -1 & 0 & 1 \\ 0 & 0 & -1 & 0 & -1 & -1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 & -1 & -1 & 0 \\ 0 & 1 & 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & -1 & 0 & -1 & -1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 & -1 & -1 & 0 \\ 0 & 1 & 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} = R$$

$\Rightarrow$ Which we see has rank 3 + pivot variables in the $x_1, x_2, + x_3$ variables or the columns of A (column 1, 2 + 3) are linearly independent. ~~The elementary matrices~~

used to obtain R are

$$E_{21} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$E_{32} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 7 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$E_{43} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

So we have the

$$E_{43} E_{32} E_{21} A = R$$

$$\dagger E_{43} E_{32} E_{21} = E$$

$$\text{so } A^T E^T = R^T$$

$$\text{so } E^{-1} = E_{21}^{-1} E_{32}^{-1} E_{43}^{-1}$$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 & 1 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

so

$$A = E^T R =$$

$$\text{Thus } R^T =$$

To determine the combinations of the vectors that result in the zero vector we are looking for the null space of A , setting each free variable equal to 1, ^{in turn} we have

$$x_4 = 1, x_5 = 0, x_6 = 0 \Rightarrow x_1 = 1, x_2 = -1, x_3 = 0$$

giving
$$x = \begin{bmatrix} 1 \\ -1 \\ 0 \\ -1 \\ 0 \\ 0 \end{bmatrix}$$

$$\text{If } x_5 = 1, x_4 = 0, x_6 = 0 \Rightarrow x_1 = 0, x_2 = 0, x_3 = -1$$

$$x = \begin{bmatrix} 0 \\ 0 \\ -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\text{If } x_6 = 1, x_4 = 0, x_5 = 0 \Rightarrow x_1 = 0, x_2 = 1, x_3 = -1$$

giving

$$x = \begin{bmatrix} 0 \\ 1 \\ -1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

To determine the invariant subspace that all 6 columns must be a member of we are looking for y 's such that

$$y^T A = 0$$

∴ $A^T y = 0$, thus we are looking for the null space for A .

Since $A^T = \begin{bmatrix} 1 & -1 & 0 & 0 \\ 1 & 0 & -1 & 0 \\ 1 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1 \end{bmatrix}$ ✓

we have (reducing A^T) that

$$\Rightarrow \begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & -1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

which has x_4 as a free variable + an element of the null space given by

$$\frac{x}{n} = \begin{bmatrix} 1 \\ -1 \\ -1 \\ 0 \end{bmatrix}$$

So ~~the~~ ~~space~~ ~~is~~ each of the v_i vectors is in the hyperplane

$$x_n^T v_i = 0 = [1 \ 1 \ 1 \ 1] v_i = 0$$

(3) For the columns of T to be ~~linearly~~ ⁱⁿ dependent we would need to be able to apply elementary row operations to T to produce R . This is possible if we can $\div$ by $a, d + f$ requiring that $a \neq 0, d \neq 0 + f \neq 0$ if any of these cases is ~~incorrect~~ false T does not have linearly independent columns

(4) The only solution to $Tx = 0$ can be obtained by back substitution ^{+ gives $x=0$} . It is unique since every step is ~~unique~~ ^{unique} ~~invertible~~ ^{invertible} ~~operations~~ ^{operations}. Since the only linear combinations of the columns of T that gives zero is the zero vector the columns are linearly independent.

(5) (a) Consider the Nullspace of $\begin{bmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \\ 2 & 3 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & -5 & -7 \\ 0 & -1 & -5 \end{bmatrix}$

$$\Rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & \frac{7}{5} \\ 0 & 1 & 5 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 3 - \frac{7}{5}(2) \\ 0 & 1 & \frac{7}{5} \\ 0 & 0 & \underbrace{5 - \frac{7}{5}}_{\neq 0} \end{bmatrix}$$

Which since this matrix has $\text{rank} = 3$, it is invertible
 $\therefore$ the columns are linearly independent.

(b) Consider $N =$ the null space of $A = \begin{bmatrix} 1 & 2 & -3 \\ -3 & 1 & 2 \\ 2 & -3 & 1 \end{bmatrix}$

$$\Rightarrow \begin{bmatrix} 1 & 2 & -3 \\ 0 & 7 & -7 \\ 0 & -7 & 7 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & -3 \\ 0 & 7 & -7 \\ 0 & 0 & 0 \end{bmatrix} \text{ which has rank} = 2$$

$\therefore$ the 3 vectors are linearly dependent

(c) let $T = \begin{bmatrix} 2 & 3 & 4 & 1 \\ 0 & 6 & 7 & 0 \\ 0 & 0 & 0 & 9 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ From the T given

the free variable is x_3 $\therefore$ 3 independent columns are

v_1, v_2, v_4 , ~~the~~ another ^{obvious} choice is v_1, v_2, v_3 , another

choice is can be obtained from $v_2, v_3 + v_4$ since together

$v_2 + v_3$ span the dimension of $x_1 + x_2$.

Since A is simply $E = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 2 & 0 & 0 & 1 \end{bmatrix}$ times

$\therefore$ the ~~same~~ same columns 0 from T choice are linearly

independent in A.

⑦ Consider ~~$V_1 + V_2 + V_3$~~

$$= \cancel{V_2} - \cancel{V_3} + \cancel{w_1} - \cancel{w_3} + w_1 - \cancel{V_2} =$$

$$V_1 + V_3 = \cancel{w_2} - \cancel{w_3} + \cancel{w_1} - \cancel{V_2} = \cancel{w_3 + w_1} V_2 = \cancel{V_2}$$

$$\text{consider } V_1 - V_2 + V_3 = w_2 - w_3 - \cancel{w_1} + w_3 + \cancel{w_1} - \cancel{V_2} = 0$$

Since a non-zero linear combination of flux vectors gives zero, they are linearly dependent.

⑧ Consider $c_1 V_1 + c_2 V_2 + c_3 V_3 = 0$ or in terms of w_1, w_2, w_3 we have

$$c_1 w_2 + c_2 w_3 + c_2 w_1 + c_2 w_3 + c_3 w_1 + c_3 w_2 = 0$$

$$\Rightarrow (c_2 + c_3) w_1 + (c_1 + c_3) w_2 + (c_2 + c_1) w_3 = 0$$

Since w_1, w_2, w_3 are linearly independent the only sum that gives the zero vector is when

All coefficients are zero, or

$$c_2 + c_3 = 0$$

$$c_1 + c_3 = 0$$

$$c_2 + c_1 = 0$$

This system has only the solution $c_1 = c_2 = c_3 = 0$ + $\therefore$ the vectors v_1, v_2 , & v_3 are independent.

(9)

(a) These four vectors are dependent because the dimension of the space $\mathbb{R}^3$ is 3.

(b) Two vectors will be dependent if one is a multiple of the other.

(c) The vectors v_1 & $\underline{0}$ are dependent because given $c \neq 0$

$$0 \cdot v_1 + c \underline{0} = \underline{0} \quad \text{a non zero linear combination gives zero}$$

(10)

Consider the matrix which represents the planes all space

$$A = \begin{bmatrix} 1 & 2 & -3 & -1 \end{bmatrix}$$

~~the plane~~ ~~the plane~~ ~~the plane~~ ~~the plane~~ The plane ^{as a constraint} will reduce the dimension of the space $\mathbb{R}^4$ (which is 4) by 1 (the rank of the matrix A) thus $4 - 1 = 3$ linearly independent

vectors in this space are possible. To find them
consider the ~~row reduced echelon form~~ null space of A
the free variables are $x_2, x_3, + x_4$ so the null space is spanned

$$\text{by } \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

(11) (a) Since $(1, 1, -1) + (-1, -1, 1)$ are ~~linear combinations~~
multiples of each other the subset of $\mathbb{R}^3$ is a line
in $\mathbb{R}^3$.

(b) Since $(0, 1, 1) + (1, 1, 0)$ are linearly independent in
 $\mathbb{R}^3$ they span a plane

(c) Since we have 2 pivots we effectively have only two
degrees of freedom in the columns of the matrix + thus
the span of these columns is a plane in $\mathbb{R}^3$.

(d) This is not a subspace since all linear combinations
of vectors with this property won't still have this
property. But if we extend it to all of $\mathbb{R}^3$, then
these vectors will span that space

- (12) When there is a solution to $Ax=b$, vector c is in the row space of A when there is a solution to $y^T A = c$.

The row space is the span of the columns of A^T which always contains the zero vector.

- (13) Since U is ^{obtained} ~~obtained~~ from A by elementary row operations the row spaces must be the same.

So the dimensions of the given spaces are:

$$\dim(\text{column space of } A) = \dim(\text{column space of } U) = 2$$

row space of A = row space of U which has dimension 2

- (14) (a) Pick $x = (0, 0, 0, 0)$ then S has dimension 0

(b) Pick $x = (1, 1, 1, 1)$ then S has dimension 1

(c) Pick $x = \cancel{(1, 1, 1, 1)} (1, 1, -1, -1)$ because all permutations are 1

(d) Pick $x = (1, 0, 0, 0)$ then S has dimension 4 to $(1, 1, 1, 1)$

- (15) Let $x = v + w$
 $+ y = v - w$

$$\text{Then } v = \frac{1}{2}(x + y) = \frac{1}{2}(v + w + v - w)$$

$$+ w = \frac{1}{2}(x - y) = \frac{1}{2}(v + w - (v - w))$$

The two pairs of vectors span the same subspace. They are a basis for the space when $v + w$ or a basis for the original space

(16) $v_1, v_2, \dots, v_n$ are linearly independent they span a space of dimension n . They are a basis for that space. If columns of a m by n matrix then $m \geq n$.

(17) (a) $(1, 1, 1, 1)$

(b) So we are looking for the Null space of

$$A = [1 \ 1 \ 1 \ 1] \text{ or the span of}$$

$$\mathcal{B} = \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix} \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

(c) So we are looking for the Null space of

$$A = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & -1 & -1 \end{bmatrix}$$

$\mathcal{B}$ which is

$$\begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix} \begin{bmatrix} -1 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$

(4) The column space is spanned by $\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

The Nullspace is spanned by

$$\begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

(18) All invertible transformations on the basis $\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ will also be a basis, examples of such are $\frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

$$\begin{bmatrix} 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \end{bmatrix}, + \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

For two different basis for the row space again an invertible ~~linear~~ ~~matrix~~ linear transformation applied to the rows yields another valid basis, Examples of such transformation are $E_1 = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} + E_2 = \begin{bmatrix} 3 & 0 \\ -1 & 1 \end{bmatrix}$

Then two additional basis ~~are~~ (equivalent basis for the rows of T or)

$$E_1 T = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 1 & 2 & 1 \\ 2 & 1 & 2 & 1 & 2 \end{bmatrix}$$

$$+ E_2 T = \begin{bmatrix} 3 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 3 & 0 & 3 & 0 & 3 \\ -1 & 1 & -1 & 1 & -1 \end{bmatrix}$$

(19) (a) Vectors might not span $\mathbb{R}^4$.

(b) Vectors are not linearly independent

(c) Any 4 of these vectors might be a basis for $\mathbb{R}^4$

(20) If they are linearly independent, ~~they span $\mathbb{R}^m$~~ the rank of A is A n . If they span $\mathbb{R}^m$ ~~there must be~~ there must be at least m linearly independent columns of the rank must be ~~at least~~ m . If they are a basis for $\mathbb{R}^m$, then there are exactly m of them & the matrix is square & invertible.

(21) To find a basis for the plane $x - 2y + 3z = 0$ we are looking for the null space for the vector $A = [1 \ -2 \ 3]$ or the span of $\begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}$

To find a basis for this plane & the intersection with the xy plane consider the augmented system with $AB = \begin{bmatrix} 1 & -2 & 3 \\ 0 & 0 & 1 \end{bmatrix}$ with the eq $z = 0$ or

$$A = \begin{bmatrix} 1 & -2 & 3 \\ 0 & 0 & 1 \end{bmatrix} \quad \text{with}$$

~~The~~ has reduced row echelon form of

$$A = \begin{bmatrix} 1 & -2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ + a Null space spanned by}$$

$$\begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

To find a basis of vectors $\perp$ to the plane we are looking for y 's such that $y^T x = 0$ where x is a point on the plane. Reading the coefficients from the linear constraint we have a basis for all vectors $\perp$ to this plane

$$\text{of } \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix}$$

- (22) (a) $Ax=0$ has only the solution $x=0$ since A is invertible, has 5 pivots, the columns are independent
- (b) $Ax=b$ is solvable since A is ~~invertible~~ ^{equivalently} invertible + the columns span $\mathbb{R}^5$

- (23) (a) True, the dimension of S is 5 + the dimension of $\mathbb{R}^6$ is 6 requiring one more vector to be added to the basis of S
- (b) ~~True~~ False

consider S given by the ~~space~~ column space of $A = \begin{bmatrix} 1 & -1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$

which here has a component of the x_6 variable.

Then let a basis of $\mathbb{R}^6$ be the column span of

$$A' = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \\ 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \quad \text{which even after removing}$$

one vector will have a span that includes the x_6 variable

(24) From $\mathcal{U}$ we see that ~~column~~ $x_1 + x_2$ are pivot variables $\therefore$ a basis for the column span of

$$A \text{ is given by the span of } \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 3 \\ 1 \\ 3 \end{bmatrix}$$

With a basis for the column span of $\mathcal{U}$ is given by
the span of $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix}$.

Basis for the row span is given by ~~the~~ ~~sp~~

$$\begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \quad \text{equivalently } \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix}$$

The basis for the two Null spaces is given by

letting $x_3 = 1$ + solving for $x_1 + x_2$ on the

$$\text{span of } \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

$$x_1 = -3(-1) - 2(1) = 3 - 2 = 1$$

25 ~~the~~ ~~the~~ ~~the~~

$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$$

$$\cancel{Ax=0}$$

$$Ax=0$$

$$x^T A^T = 0$$

combo of columns

combo of rows of A^T

combo of columns of A

(a)

(2) ~~True the false consider True the rank of A~~

~~$\begin{bmatrix} 1 & 1 \end{bmatrix}$ is the # of linearly independent columns & to have A have linearly dependent columns~~

~~we must have $n < n$ at ~~rank~~ this requires $m \geq r$~~

~~(if $m=r$ the columns may be linearly independent)~~

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

False ~~consider~~ in general we need

$n > m$ with rank $r=m$. For example

consider $A \rightarrow$ then the columns are ~~linearly~~ dependent
(because one column is all zeros) but the rows are linearly independent

(b) False consider $\begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$ Then the span of the rows is

the x axis while the span of the columns is the line

$$y=x$$

(c) True each has dimension ~~rank~~ equal to the rank of the matrix

(d) False the basis is the smallest ~~size~~ ~~that~~ number of vectors that span the space. Consider

$$A = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \quad \text{Then a basis is given by the 1st}$$

3 columns (the 4th is not needed)

(26) For $A = \begin{bmatrix} 1 & 2 & 5 & 0 & 5 \\ 0 & 0 & c & 2 & 2 \\ 0 & 0 & 0 & d & 2 \end{bmatrix}$ ^{By inspection} if $c=0$ & $d=2$
 A will have rank 2.

$\Leftrightarrow$ For $B = \begin{bmatrix} c & d \\ d & c \end{bmatrix}$ ~~Assume~~ to have rank 2

it must be invertible so $c^2 - d^2 \neq 0$ & $c \neq \pm d$

$\Rightarrow c \neq \pm d$

(27) (a) let ~~$B_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$~~ $B_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$; $B_2 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

+ let $B_3 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

(b) let $B_1 \neq \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, B_2 , & B_3 be the same as before

$$\dagger \text{ let } B_1 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \dagger B_5 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \dagger$$

$$B_6 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$(c) \text{ let } \cancel{B_1}, B_1 = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, B_2 = \begin{bmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \dagger$$

$$B_3 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$(28) \quad \cancel{V_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}}, \cancel{V_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}}, \cancel{V_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}} \quad (\text{Not valid})$$

$$\cancel{V_4 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}}, \cancel{V_5 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}}, \cancel{V_6 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}}$$

$$\text{others? } \cancel{V_7 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}}$$

1st only one pivot

$$V_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, V_2 = \begin{bmatrix} 0 & \cancel{1} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, V_3 = \begin{bmatrix} 0 & 0 & \cancel{1} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{Not valid} \\ (1,1) = 0$$

two pivots

No valid
(1,1) = 0

$$V_4 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, V_5 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}, V_6 = \begin{bmatrix} 0 & \cancel{1} & 0 \\ 0 & 0 & \cancel{1} \\ 0 & 0 & 0 \end{bmatrix} \quad \text{Not valid} \\ (1,1) = 0$$

What about $U_7 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$? This is not in Row echelon form

Since the elt $(1,1)$ ~~should~~ be must be non zero.

? Not an

(29) If the columns add to zero

$$A = \begin{bmatrix} x & x & x \\ x & x & x \end{bmatrix} \begin{bmatrix} a_1 \\ b_1 \\ c_1 \end{bmatrix} =$$

Let $A = \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix}$ then $A \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 0$ is equivalent

to $a+b+c=0$
 $d+e+f=0$

Since eq is represented by the Null space of the matrix $\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$.

Which has a basis of $\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$

Thus I get a basis consisting of $A_1 = \begin{bmatrix} -1 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$, $A_2 = \begin{bmatrix} -1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$

+ $A_3 = \begin{bmatrix} -1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} + A_4 = \begin{bmatrix} -1 & 0 & 1 \\ -1 & 0 & 1 \end{bmatrix}$

$$A_1 = \begin{bmatrix} -1 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, A_2 = \begin{bmatrix} 0 & 0 & 0 \\ -1 & 1 & 0 \end{bmatrix},$$

$$A_3 = \begin{bmatrix} -1 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} + A_4 = \begin{bmatrix} 0 & 0 & 0 \\ -1 & 0 & 1 \end{bmatrix}$$

For the rows of A to add to zero we must have

$$\begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} = 0 \quad \text{or}$$

$$a + d = 0$$

$$b + e = 0$$

$$c + f = 0$$

So picking a specific pair like $a + d$ we have a Null space of $a + d = 0$ or the span of $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$. Thus a basis for this subspace is given by the span of

$$B_1 = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix}, B_2 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & -1 & 0 \end{bmatrix}, + B_3 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & -1 \end{bmatrix}$$

(30) From example 4 in section 2.7 consider the linear combination

$$I - P_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix}$$

$$\text{then } I - P_{31} - P_{32} = \begin{bmatrix} 0 & 0 & -1 \\ 0 & 0 & -1 \\ -1 & -1 & 0 \end{bmatrix}$$

$$\text{the } I - P_{31} - P_{32} + P_{32}P_{21} + P_{21}P_{32} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Constructing the sum in this way is difficult, consider

$$aI + bP_{11} + cP_{32}P_{21} + dP_{31} + eP_{32} + fP_{31}P_{32} = 0$$

$$\Rightarrow \begin{bmatrix} a & 0 & 0 \\ 0 & a & 0 \\ 0 & 0 & a \end{bmatrix} + \begin{bmatrix} 0 & b & 0 \\ b & 0 & 0 \\ 0 & 0 & b \end{bmatrix} + \begin{bmatrix} 0 & c & 0 \\ 0 & 0 & c \\ c & 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 & d \\ 0 & d & 0 \\ d & 0 & 0 \end{bmatrix} +$$

$$\begin{bmatrix} e & 0 & 0 \\ 0 & 0 & e \\ 0 & e & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 & f \\ f & 0 & 0 \\ 0 & f & 0 \end{bmatrix} = \begin{bmatrix} a+e & b+c & d+f \\ b+f & a+d & c+e \\ c+d & e+f & a+b \end{bmatrix} = \underline{\underline{0}}$$

$$\text{or } a+e=0 \quad + \quad a+b=0$$

$$b+c=0$$

$$d+f=0$$

$$b+f=0$$

$$a+d=0$$

$$c+e=0$$

$$c+d=0$$

$$e+f=0$$

This is equivalent to the Nullspace of the following operator

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 & 0 & 0 \end{bmatrix}$$

a b c d e f

using the matlab code elim
we obtain the following row reduced
echelon form
of

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 & 1 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Final...

(31) (a) All 3×3 matrices

(b) Upper triangular matrices

(c) All 3×3 matrices w/ zeros on the ~~all~~ diagonal & a constant value on the diagonal

(32) Basis such that $\begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = 0$ Thus we are looking for two

vectors that span the plane $2x + y + z = 0$

is the Null space of $A = [2 \ 1 \ 1]$ this is the span

of $\begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}$ & $\begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}$ Thus $\begin{bmatrix} -1/2 \\ 1 \\ 0 \end{bmatrix}$ & $\begin{bmatrix} -1/2 \\ 0 \\ 1 \end{bmatrix}$

or the span of $\begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}$ & $\begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$

Thus let a basis be

$$A_1 = \begin{bmatrix} -1 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \quad A_2 = \begin{bmatrix} 0 & 0 & 0 \\ -1 & 2 & 0 \end{bmatrix},$$

$$A_3 = \begin{bmatrix} 0 & 0 & 0 \\ -1 & 0 & 2 \end{bmatrix} + A_4 = \begin{bmatrix} -1 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

(33) (a) $y_h = C$

(b) pick $k_p = 3x$

(c) $y = y_p + y_h = 3x + C$

(34) ~~pick~~ $y(0) = \text{~~zeros~~ } A + B + C = D$

Then the Nullspace of this ^{space is} $\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$

Thus A our allowed combination is given by

$$y(x) = \cancel{C_1 \cos x} + \cancel{C_2 \cos 2x} \begin{bmatrix} \cancel{(-C_1 - C_2) \cos x} \\ \cancel{(C_1) \cos 2x} \\ \cancel{(C_2) \cos 3x} \end{bmatrix}$$

$$\begin{bmatrix} A \\ B \\ C \end{bmatrix} = C_1 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + C_2 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$$\text{Then } y(x) = \begin{bmatrix} A \\ B \\ C \end{bmatrix}^T \begin{bmatrix} \cos x \\ \cos 2x \\ \cos 3x \end{bmatrix} = \left(\begin{bmatrix} -C_1 \\ C_1 \\ 0 \end{bmatrix} + \begin{bmatrix} -C_2 \\ 0 \\ C_2 \end{bmatrix} \right)^T \begin{bmatrix} \cos x \\ \cos 2x \\ \cos 3x \end{bmatrix}$$

$$= \begin{bmatrix} -C_1 - C_2 \\ C_1 \\ C_2 \end{bmatrix}^T \begin{bmatrix} \cos x \\ \cos 2x \\ \cos 3x \end{bmatrix} = C_1(-\cos x + \cos 2x) + C_2(-\cos x + \cos 3x)$$

Thus a basis is given by

$$y_1(x) = -\cos x + \cos 2x$$

$$+ y_2(x) = -\cos x + \cos 3x$$

(35) (a) $\frac{dy}{dx} - 2y = 0$ has solution given by

$$y_1(x) = Ae^{2x}$$

$\therefore$ by the spec of e^{2x}

(b) $\frac{dy}{dx} - \frac{y}{x} = 0$ has solutions given by

$$\frac{dy}{y} = \frac{dx}{x}$$

$\int \frac{1}{y} dy = \int \frac{1}{x} dx + C \quad \ln y = \ln x + C_1 = \ln x + \ln C_2 = \ln(C_2 x)$

$\therefore y = \log(e^{C_2 x}) = y = C_2 x$

Thus a basis for the solutions is given by the function x .

(36) Of dimension 1 consider y_1, y_2, y_3 given by
 $2x, 3x, 5x$

Of dimension 2 consider

$$2x+1, 3x+5, 5x+3$$

of dimension 3 we have

$$1, 2x, 3x^2$$

(37) let our basis equal $1, x, x^2, x^3$

A basis of this subspace requires that $p(1) = 0$

which restricts the originally free 4 coefficients a, b, c, d in

the span of the functions $1, x, x^2, x^3$ requiring that

$$a + b + c + d = 0$$

This subspace has a null space given by the span of

$$\begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix} \quad \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} \quad \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

+ thus the ~~set~~ ^{function} $(-c_1 - c_2 - c_3)1 + (c_1)x$

$+ c_2x^2 + c_3x^3$ will satisfy the requirement $p(1) = 0 \forall c_1, c_2, c_3$

$$\text{Or } p(x) = c_1(-1+x) + c_2(-1+x^2) + c_3(-1+x^3)$$

Thus the functions

$-1+x, -1+x^2, -1+x^3$ span the space of all 3rd degree polynomials

with $p(1) = 0$ at $x=1$

38 When require that

at $c+d=0$ we are reducing ^{all} possible 4 vectors by one linear constraint, thus will have a dimension of 3. Looking for a basis for the null space for the operator $A = \begin{bmatrix} 1 & 0 & 1 & 1 \end{bmatrix}$ we see that b, c, d are the variables $\therefore$ the nullity ~~the~~ ~~dimension~~ is spanned by

$$\begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

For the space "T" we consider the operator A given by

$$\begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

from which we see that b & d are the variables & the null space is spanned by ~~$(b=1, d=0)$~~ $= (b=1, d=0) + (b=0, d=1)$ the vectors

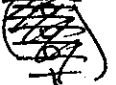
$$\begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$

The intersection will have dimension $4-1-2=1$

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- ① (a) The dimension of the column space $C(A)$ is 5
 The dimension of the row space $C(A^T)$ is 5
 The dimension of the Nullspace $N(A)$ is of ~~the~~ ~~the~~ dimension $9-5=4$
 The dimension of the left Nullspace $N(A^T)$ is of dimension $7-5=2$

(b) Its column space is $\mathbb{R}^3$

Its left Nullspace is  spanned by 

~~Since its row space must have dimension 3 +~~

~~$\therefore$ the left Nullspace has dimension $4-3=1$. By ~~by~~ reducing the matrix A into its row reduced echelon form~~

~~we will produce a row of ~~the~~ zeros ~~showing~~~~

~~The test $m-r=$~~

The dimension of the left Nullspace is $3-3=0$ so

the only element in the left Nullspace is ~~the~~ the zero vector

② For $A = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 4 & 8 \end{bmatrix}$ reducing to row echelon form

gives $A = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 4 & 8 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 4 \\ 0 & 0 & 0 \end{bmatrix}$ by $E_{21} = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix}$

which has $\text{rank} = 1$ $\therefore$ a basis for $C(A)$ can be obtained

from the 1st column of A or $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$

A basis for $C(A^T)$ is given by the 1st row in R or

$$\begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix}, \text{ A basis for the null space of } A \text{ is given}$$

by assigning ones to the free variables & solving for the pivot variables

Since x_2 & x_3 are free variables we have for a basis for the null space is given by

$$\begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} -4 \\ 0 \\ 1 \end{bmatrix}$$

A basis for the left nullspace is given by the last $m-r = 2-1=1$ rows of E_2 or $\begin{bmatrix} -2 \\ 1 \end{bmatrix}$

For $B = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 5 & 8 \end{bmatrix}$ we have row echelon form follows

$$\Rightarrow \begin{bmatrix} 1 & 2 & 4 \\ 0 & 1 & 0 \end{bmatrix} \text{ with } E_{21} = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix}$$

Thus B is of rank 2, It has a basis for the

column space given by

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} + \begin{bmatrix} 2 \\ 5 \end{bmatrix}$$

A basis for the row space given by

$$\begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad \text{or} \quad \overset{\text{equivalently}}{\begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix}} + \begin{bmatrix} 2 \\ 5 \\ 8 \end{bmatrix}$$

A basis for the null space is given by assigning x_3 (the free variable to 1) + solving for x_1 + x_2 the pivot variables

giving $\begin{bmatrix} 1 & 2 & 4 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -4 \\ 0 \\ 0 \end{bmatrix}$

$\Rightarrow x_2 = 0 \Rightarrow x_1 = -4$ so a basis is

$$\begin{bmatrix} -4 \\ 0 \\ 1 \end{bmatrix}$$

~~Further reducing R by with $E_{12} = \begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix}$ we get~~

~~$$E_{12} \begin{bmatrix} 1 & 2 & 4 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 4 \\ 0 & 1 & 0 \end{bmatrix}$$~~

Then ~~$$E_{12} E_{21} \begin{bmatrix} 1 & 2 & 4 \\ 2 & 5 & 8 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 4 \\ 0 & 1 & 0 \end{bmatrix}$$~~

~~$$\Rightarrow \begin{bmatrix} 1 & 2 & 4 \\ 2 & 5 & 8 \end{bmatrix} =$$~~

~~$$E_{21}^{-1} E_{12}^{-1} \begin{bmatrix} 1 & 0 & 4 \\ 0 & 1 & 0 \end{bmatrix}$$~~

4

Since $m=2$ & $r=2$ the dimension of the left nullspace is given by $m-r=0$.

③ Since A is given by A as ER , we can read the rank of A from R , which we see is 2.
Thus a basis with pivot variables given by x_2 & x_4 .

Thus a basis for the column space is given by

$$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 3 \\ 4 \\ 1 \end{bmatrix}$$

A basis for the row space is given by the span of the 1st two rows of A or R .

$$\text{i.e. } \begin{bmatrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 2 \end{bmatrix}$$

A basis for the nullspace is given by setting $x_1=1, x_3=0, x_5=0$ & solving for x_2 & x_4 , this gives

$$\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \text{by setting } x_1=0, x_3=1, x_5=0$$

giving $\begin{bmatrix} 0 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}$ + ~~for~~ for $x_1=0, x_3=0, x_5=1$

giving $\begin{bmatrix} 0 \\ 0 \\ 0 \\ -1 \\ 1 \end{bmatrix}$

$$\begin{bmatrix} 0 & 1 & 2 & 3 & 4 \\ 0 & 0 & 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ 0 \\ x_4 \\ 1 \end{bmatrix} = 0$$

~~$$\begin{bmatrix} 2 & 4 & 6 & 8 & 10 \\ 0 & 2 & 4 & 6 & 8 \end{bmatrix} =$$~~

$$\begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_2 \\ x_4 \end{bmatrix} = \begin{bmatrix} -3 \\ -1 \end{bmatrix}$$

$$x_4 = -1; \quad x_2 = -3 + 3 = 0$$

A basis for the left null space can be obtained by the last $m=3$ minus $r=2$ or 1 rows of E^{-1}

This is given by ~~the~~ $\begin{bmatrix} 0 \\ 0 \\ 0 \\ -1 \\ 1 \end{bmatrix}$ with

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \quad \text{so} \quad E^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & -1 & 1 \end{bmatrix}$$

So the last row of E^{-1} is given by ~~the~~

The ~~rows~~ vectors ~~the~~ $\begin{bmatrix} 0 \\ 0 \\ 0 \\ -1 \\ 1 \end{bmatrix}$ check $\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$

Check:

$$\begin{bmatrix} 1 & -1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 4 & 6 \\ 0 & 0 & 0 & 1 & 2 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{Yes}$$

(4) (a) $\begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$ has the two given vectors as a column space & since the row space is $\mathbb{R}^2$ both $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ $\begin{bmatrix} 3 \\ 5 \end{bmatrix}$

(b)  so $\text{rank} = 1$ & $\dim$ of nullity $= 1$
 $\therefore$ ~~rank~~ $\boxed{r + \dim \text{nullity} = n}$

$$\Rightarrow n = 2$$

~~But~~ But the # of components in both the column space vector & the null space vector is $3 \neq 2$

Thus this is not possible

(c) $\underbrace{\dim \text{null space}} = 1 + \dim \text{left null space}$

$$n - r = 1 + (m - r) \quad \text{Must be held constant}$$

$$\text{let } \text{rank} = 1 \quad + \quad m = 1 \quad + \quad n = 2$$

so pick $A = \begin{bmatrix} 1 & 2 \end{bmatrix}$ The $m = 1, \text{rank} = 1,$
 $n = 2$

$$\dim \text{nullity} = 2 - 1 = 1$$

$$\dim \text{left null space} = 1 - 1 = 0$$

& everything is

satisfied

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$$(d) \begin{bmatrix} 1 & 3 \end{bmatrix} \begin{bmatrix} 3 & 1 \\ a & b \end{bmatrix} = \begin{bmatrix} 3+3a & 1+3b \end{bmatrix} = \underline{0}$$

$\rightarrow a = -1$ & $b = -\frac{1}{3}$ so the matrix

$$A = \begin{bmatrix} 3 & 1 \\ -1 & -\frac{1}{3} \end{bmatrix} \text{ satisfies the } \text{required condition}$$

(e) ~~Let A =~~ ~~Then~~

$$\begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix} \text{ If row space} = \text{column space } m=n$$

Then dim of null space = $n-r$

+ dim of ~~left~~ nullspace = $n-r$

~~Let~~ $n=m=2$ & $r=1$ + ~~these~~ two spaces have equal dimension

& don't contain the linearly independent

~~rows~~ rows equivalently columns

$$\begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix}$$

~~that this is not possible~~

(5) let $A = \begin{bmatrix} 1 & 1 & 0 \\ 2 & 1 & 0 \end{bmatrix}$

For B to have V as its null space we must have

$$\text{let } B = \begin{bmatrix} a & b & c \\ \text{---} & \text{---} & \text{---} \end{bmatrix}$$

Then $B \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = 0$ & $B \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} = 0$

which imposes two constraints on B .

let $B = [1 \ a \ b]$ then the 1st condition requires

$$\text{that } B \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 1 + a + b = 0$$

$$\text{f The second that } B \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} = 2 + a = 0 \Rightarrow a = -2$$

$$\text{Then } b = -(1+a) = -(1-2) = 1$$

$$\text{so } B = [1 \ -2 \ 1]$$

⑥ ^{Now} ~~Since~~ A has rank 2, $m=3$, & $n=4$

The dimension of its column space is 2
 & its row space is 2

& its null space is $n-r=2$

& its left nullspace is $m-r=3-2=1$

To find basis for each of the spaces we simply need to
 find ^{enough} linearly independent vectors.

For the column space pick $\begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}$ & $\begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}$

For the row space pick $\begin{bmatrix} 0 \\ 3 \\ 3 \\ 3 \end{bmatrix}$ & $\begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}$

For the nullspace pick $\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix}$

For the left nullspace pick $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

For B we have $r=1, m=3, n=1$, then

The dimension of the column space is 1

" " " row space is 1

" " " null space is 0

" " left null space is $m-r = 2$

A basis for the column space is given by $\begin{bmatrix} 1 \\ 4 \\ 5 \end{bmatrix}$

A " " " row space is given by $[1]$

A " " " null space is given by 0

" " " left nullspace is given by $\begin{bmatrix} -1 \\ 1 \end{bmatrix} + \begin{bmatrix} 5 \\ 1 \end{bmatrix}$

$$\begin{bmatrix} -4 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} -5 \\ 0 \\ 1 \end{bmatrix}$$

⑦ For A we have $m=n=r=3$ then

The dimension of the column space is 3 + has a basis given by

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

The dimension of the row space is also 3 + has the same basis

The dimension of the null space is 0 + contains only the zero vector

" " " " left nullspace is 0 + " " " " "

For B we have $m=3, n=6, r=3$

so the dim of the column space is 3 + has the same basis choice,

The dim of the row space is still 3 ~~but~~ has a basis

given by $[1 \ 0 \ 0 \ 1 \ 0 \ 0]^T, [0 \ 1 \ 0 \ 0 \ 1 \ 0]^T,$

$[0 \ 0 \ 1 \ 0 \ 0 \ 1]^T$

The dim of the null space is given by $6-3=3$ + a basis can be determined by from

$[1 \ 0 \ 0 \ -1 \ 0 \ 0]^T, [0 \ 1 \ 0 \ 0 \ -1 \ 0]^T,$

$[0 \ 0 \ 1 \ 0 \ 0 \ -1]^T$

The dim of the left nullspace is given by $m-r=3-3=0$

+ has $\mathbf{0}$ the zero vector as its only element.

5
⑧ For A $m=3, n=3+2=5, + r=3$

So the $\dim(CA) = 3$

$$\dim(CA^T) = 3$$

$$\dim(N(A)) = n - r = 5 - 3 = 2$$

$$\dim(N(A^T)) = m - r = 0$$

For B $m=3+2=5, n=3+3=6, r=3$

So $\dim(CA) = 3$

$$\dim(CA^T) = 3$$

$$\dim N(A) = \cancel{m} - r = 3$$

$$\dim N(A^T) = m - r = 5 - 3 = 2$$

For C $m=3, n=2, + r=0$

So $\dim(CA) = 0$

$$\dim(CA^T) = 0$$

$$\dim N(A) = n - r = 2$$

$$\dim N(A^T) = m - r = 3$$

⑨

~~the rank of A~~ First the equivalence of the ranks

The rank of A alone is equivalent to the rank of $\begin{bmatrix} A \\ B \end{bmatrix}$

Because we can simply subtract each row of A from the corresponding "new" row in the concatenated matrix

~~we~~ effectively we are applying the elementary transformation matrix

$$E = \begin{bmatrix} I & 0 \\ -I & I \end{bmatrix} \text{ to the concatenated matrix } \begin{bmatrix} A \\ A \end{bmatrix}$$

to produce $\begin{bmatrix} A \\ 0 \end{bmatrix}$.

Now for $C = \begin{bmatrix} A & A \\ A & A \end{bmatrix}$ we can again multiply by the

E above directly

$$EC = \begin{bmatrix} I & 0 \\ -I & 0 \end{bmatrix} \begin{bmatrix} A & A \\ A & A \end{bmatrix} = \begin{bmatrix} A & A \\ 0 & 0 \end{bmatrix}$$

~~we~~ continuing to perform row operations on the top here to get this matrix we obtain

$$\begin{bmatrix} R & R \\ 0 & 0 \end{bmatrix} \text{ where } R \text{ is the reduced row echelon matrix}$$

for A . Since this has the same rank as R the composite matrix has the same rank as the original.

Now ~~for the theorem~~ for pt (a)

If A is $m \times n$ then B is $2m \times n$.

A & B have the same row space
(2) nullity

For pt (b)

~~It~~ If A is $m \times n$ then B is $2m \times n$ + C is $2m \times 2n$

Then $B + C$ have the same

(1) column space

(2) left null space

(16) $m=3$ + $n=3$ with random entries ~~it~~ is very likely that the matrix will be non singular so its rank = 3

$$\begin{aligned} \dim(CA) &= 3 \\ \dim(CA^T) &= 3 \\ \dim(N(A)) &= 0 \\ \dim(N(A^T)) &= 0 \end{aligned}$$

If A is 3×5 , $m=3$ + $n=5$ it is more likely that

$$\begin{aligned} \dim(CA) &= 3 \\ \dim(CA^T) &= 3 \end{aligned}$$

$$\dim(N(A)) = m - r = 3 - 3 = 0$$

$$\dim(N(A^T)) = m - r = 3 - 3 = 0$$



Pg 162 Strong

⑪ It is a PHS with no solution then when we perform

(a) or elementary row operations on A we are left with a row of zeros in R (or T) that does not have corresponding zero elements in E_b . Thus $r < m$ (since ~~we~~ ^{we} must have a row of zeros as always ~~$r \leq n$~~ $r \leq n$),

$$\begin{bmatrix} \text{ } & \text{ } \\ \text{ } & \text{ } \end{bmatrix} \begin{bmatrix} \text{ } & \text{ } \\ \text{ } & \text{ } \end{bmatrix} \begin{bmatrix} \text{ } & \text{ } \\ \text{ } & \text{ } \end{bmatrix}$$

(b) Because letting y be composed of r ~~zeros~~ ^{stacked} ~~stacked~~ ^{atop} vectors with ones in each component, i.e. in case

Then $\overrightarrow{y^T R} = 0$ $R = EA$

$$\nabla \cdot \vec{T} = \vec{0}$$

$r=2$ + $m=4$ consider the vectors

$$Y_1 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} \quad A Y_2 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

Then $Y_1^T R = 0$ & $Y_2^T R = 0$

5

$$y^T(EA) = 0 \quad \text{or} \quad (E^T y)^T A = 0$$

$\therefore E^T y$ is a non-zero vector in the left nullspace.

~~Alternatively~~ Alternatively if the ^{left} nullspace is non-empty it

must have a non-zero vector. Since the left nullspace dimension is given by $m-r$ ~~but~~ ~~know~~ which we know is greater than zero we have ~~the~~ the existence of a non-zero element.

(12)

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 2 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 0 & 2 & -1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

~~Let~~ $A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 1 \end{bmatrix}$ then ~~$[1 \ 0 \ 1] + [1 \ 2 \ 0]$ or the basis~~
for its row & column space

consider $A = \begin{bmatrix} 1 & 1 \\ 0 & 2 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 2 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 2 & 1 \\ 2 & 4 & 0 \\ 1 & 0 & 1 \end{bmatrix}$

It ~~is~~ $(1, 0, 1) + (1, 2, 0)$ is a basis for the

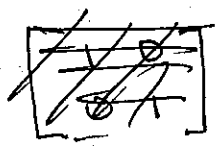
row space then $\dim(CA^T) = 2 = r$

To also be a basis for the nullspace means $n-r = 2$

~~The~~ ~~row~~ $\Rightarrow n=4$. But these vectors are in $\mathbb{R}^3$

resulting in a contradiction

13 (a) ~~True~~ False, consider

 $\begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix}$

Then the row space is spanned by $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ & the column space by $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ which are different

(b) True $-A$ is a linear transformation of A & as such cannot alter the subspaces

(c) ~~True~~ If A & B share the same χ spaces

then $E_1 A = R$ & $E_2 B = R$

Think A & B are related by an invertible transformation

i.e. $A = E_1^{-1} E_2^{-1} B$

Pick $A = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$ & $B = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$ then the ~~sub~~ subspaces

are the same but A is not a multiple of B

(14) The rank of A is 3 & a basis for the column space is ^{not} given by ~~$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}$~~

~~of dimension 3~~. But is given by

~~A basis~~ $\begin{bmatrix} 1 & 0 & 0 \\ 6 & 1 & 0 \\ 9 & 8 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 6 \\ 9 \end{bmatrix}$

& $\begin{bmatrix} 1 & 0 & 0 \\ 6 & 1 & 0 \\ 9 & 8 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 6 \\ 9 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ 8 \end{bmatrix} = \dots$

& last $\begin{bmatrix} 1 & 0 & 0 \\ 6 & 1 & 0 \\ 9 & 8 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} = \dots$

equivalently, since the 3×3 block composing the last 3 pivots of $\mathcal{U}$ is invertible

A basis for the row space of dimension 3 is given by

$(1 \ 2 \ 3 \ 4), (0 \ 1 \ 2 \ 3) \ (0, 0, 1, 2)$

The null space has dimension $4 - 3 = 1$ & has a basis

given by setting $x_4 = 1$ & solving for $x_1, x_2, \& x_3$ in

$\mathcal{U}x = 0$

or $\begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = - \begin{bmatrix} 4 \\ 3 \\ 2 \end{bmatrix}$

$\Rightarrow x_3 = -2 \quad x_2 - 4 = -3 \Rightarrow x_2 = 1 \quad \& \quad x_1 = -4 - 2(1) - 3(-2) = -4 - 2 + 6 = 0$

can be formed from the standard basis

or the vector $\begin{bmatrix} 0 \\ 1 \\ -2 \\ 1 \end{bmatrix}$

The left nullspace has dimension $m-r = 3-3=0$ $\therefore$ only consists of the zero vector

pg No 2 Strategy

(15) ~~say~~ The row space + the left null space will not change

If $v = (1, 2, 3, 4)$ is in the column space of the original matrix the vector in the column space of the new matrix is

$$(2, 1, 3, 4)$$

(16) If $v = (1, 2, 3)$ was a row of A then when we multiplied by A v this row would give the product of

$$\begin{bmatrix} 1 & 2 & 3 \\ x & x & x \\ \vdots & \vdots & \vdots \\ x & x & x \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 1^2 + 2^2 + 3^2 \\ x \\ \vdots \\ x \end{bmatrix} = \begin{bmatrix} 14 \\ x \\ \vdots \\ x \end{bmatrix} \text{ which cannot equal zero.}$$

row product must be at least 14

(17) For $A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ we have $\text{rank} = 2$

rank is 2

The ~~row~~ column space is all vectors $\begin{pmatrix} x \\ y \\ 0 \end{pmatrix}$

The row space is all vectors $\begin{pmatrix} 0 \\ y \\ z \end{pmatrix}$

The null space is all vectors $\begin{pmatrix} x \\ 0 \\ 0 \end{pmatrix}$

The left null space is all vectors $\begin{pmatrix} 0 \\ 0 \\ z \end{pmatrix}$

For $I+A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$

The rank is 3 the row space is given by all vectors $\begin{pmatrix} x \\ y \\ z \end{pmatrix}$

The column space is given by all vectors $\begin{pmatrix} x \\ y \\ z \end{pmatrix}$

The left null space & the null space contain only the zero vector

(18) $[A \ b] = \begin{bmatrix} 1 & 2 & 3 & b_1 \\ 4 & 5 & 6 & b_2 \\ 7 & 8 & 9 & b_3 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 3 & b_1 \\ 0 & -3 & -6 & b_2 - 4b_1 \\ 0 & -6 & -12 & b_3 - 7b_1 \end{bmatrix}$ with $E_1 = \begin{bmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 7 & 0 & 1 \end{bmatrix}$

$-14+8 = -6$
 $-21+9 = -12$
 $\Rightarrow \begin{bmatrix} 1 & 2 & 3 & b_1 \\ 0 & -3 & -6 & b_2 - 4b_1 \\ 0 & 0 & -3 & b_3 - 7b_1 - 2(b_2 - 4b_1) \end{bmatrix}$ with $E_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}$

$\Rightarrow \begin{bmatrix} 1 & 2 & 3 & b_1 \\ 0 & -3 & -6 & b_2 - 4b_1 \\ 0 & 0 & -3 & b_3 - 2b_2 + b_1 \end{bmatrix}$

The combination of the rows that produce the zero row is given by +1 times row 1, -2 times row two, +1 times row 3

Thus the vector $\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$ is in the null space of A^T .

A vector in the null space is given by $\underline{x} = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$
 (obtained by setting $x_3 = 1$ & solving for x_1 & x_2)

$x_1 + 2(-2) + 3(1) = 0 \Rightarrow x_1 = 4 - 3 = 1$

Which is the ~~same~~ ^{same vector space} thing as the ~~left~~ left null space

3

(19) pt (a)
$$\begin{bmatrix} 1 & 2 & b_1 \\ 3 & 4 & b_2 \\ 4 & 6 & b_3 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & b_1 \\ 0 & -2 & b_2 - 3b_1 \\ 0 & -2 & b_3 - 4b_1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 2 & b_1 \\ 0 & -2 & b_2 - 3b_1 \\ 0 & 0 & b_3 - 4b_1 - b_2 + 3b_1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & b_1 \\ 0 & -2 & b_2 - 3b_1 \\ 0 & 0 & b_3 - b_2 - b_1 \end{bmatrix}$$

Thus the vector $(-1, -1, 1)$ is in the left nullspace.
Which has dimension $m - r = 3 - 2 = 1$ ✓

For (b)
$$\begin{bmatrix} 1 & 2 & b_1 \\ 2 & 3 & b_2 \\ 2 & 4 & b_3 \\ 2 & 5 & b_4 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & b_1 \\ 0 & -1 & b_2 - 2b_1 \\ 0 & 0 & b_3 - 2b_1 \\ 0 & 1 & b_4 - 2b_1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 2 & b_1 \\ 0 & -1 & b_2 - 2b_1 \\ 0 & 0 & b_3 - 2b_1 \\ 0 & 0 & b_4 - 2b_1 + b_2 - 2b_1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & b_1 \\ 0 & -1 & b_2 - 2b_1 \\ 0 & 0 & b_3 - 2b_1 \\ 0 & 0 & b_4 + b_2 - 4b_1 \end{bmatrix}$$

Thus the vectors in the left nullspace are given by

$$\begin{bmatrix} -2 \\ 0 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} -4 \\ 1 \\ 0 \\ 1 \end{bmatrix}$$

Which has dimension $m - r = 4 - 2 = 2$ ✓

(20)

(a) we must have $\vec{v}x = 0$ which has 2 pivot variables $x_1 + x_3$
 & free variables $x_2 + x_4$. To find the null space we ~~get~~ set
 $x_2 = 1, x_4 = 0$ & solve for $x_1 + x_3$

Thus we get $\begin{bmatrix} -\frac{1}{2} \\ 1 \\ -3 \\ 0 \end{bmatrix}$

$4x_1 + 2 = 0 \Rightarrow x_1 = -\frac{1}{2}$

& setting $x_2 = 0$ & $x_4 = 1$ & solving for $x_1 + x_3$ we have

$\begin{bmatrix} \frac{1}{4} \\ 0 \\ -3 \\ 1 \end{bmatrix}$

$4x_1 + 2(0) + 0 + 1 = 0$
 $x_1 = -\frac{1}{4}$

(b) The # of independent solutions of $A^T y = 0$ is

$m - r = 3 - 2 = 1$

(c) The column space is spanned by

$\begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 4 & 1 \end{bmatrix} \begin{bmatrix} 4 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 4 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$
 $= \begin{bmatrix} 4 \\ 8 \\ 12 \end{bmatrix} \quad = \begin{bmatrix} 0 \\ 1 \\ 4 \end{bmatrix}$

28/6/23 Strang

(21)

(a) The vectors u & w

$$A = \begin{bmatrix} u & w \end{bmatrix} \begin{bmatrix} v^T \\ z^T \end{bmatrix}$$

(b) The vectors ~~u & w~~ v & z (c) ~~$v^T u = 0$~~ or ~~$z^T u = 0$~~ ? u & w are multiples of each other or are linearly dependent or v & z are multiples of each other or are(d) $u = z = (1, 0, 0)$ & $v = w = (0, 0, 1)$ linearly dependent.

$$uv^T = (1, 0, 0) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

$$+ wz^T = (0, 0, 1) \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\text{So } A = uv^T + wz^T = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \text{ which has rank} = 2$$

(22)

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 2 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

$3 \times 2 \cdot 2 \times 1$

$$= \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} + \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 0 & 0 \\ 4 & 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 2 & 2 \\ 0 & 2 & 2 \\ 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 2 \\ 2 & 2 & 2 \\ 4 & 1 & 1 \end{bmatrix}$$

- (23) A basis for the row space is $(3 \ 0 \ 3)$ & $(1 \ 1 \ 2)$ which are independent.
 A basis for the column space is given by $(1 \ 4 \ 2)$ & $(2 \ 5 \ 7)$ which are independent.

A is not invertible because it is the product of two rank 2 matrices & $\therefore \text{rank}(AB) \leq \text{rank}(B) = 2$

to be invertible $\text{rank}(AB) = 3$ which it's not

- (24) λ is in the span of its rows. Solution is unique
 When the left nullspace contains only the zero vector

- (25) (a) A & A^T have the same # of pivots, since they have the same rank, they have the same # of pivots

(b) False let $A = \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix}$

Then $y^T = [-2 \ 1]$ is in the left nullspace of A

Let $y^T(A^T) = [-2 \ 1] \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \neq \underline{0}$ & is not in the

left nullspace of A^T

- (c) False, pick any invertible matrix ^{say of size $m \times m$.} (then the row & column spaces are the entire of $\mathbb{R}^m$. But many invertible matrices exist such that $A \neq A^T$

For example let $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$.

(d) If $A^T = -A$ ~~is~~ $A = \begin{bmatrix} 0 & 2 \\ -2 & 0 \end{bmatrix}$ True since,

If $A^T = -A$ then the rows of A are the negative columns of

A $\therefore$ have exactly the same ~~same~~ span

(26) The rows of C are combinations of the rows of B .

The rank of C cannot be greater than the rank of B .

So the rows of C^T are the rows of A^T , so the rank of C^T
 $= \text{rank of } C$
 $\neq$ cannot be larger than the rank of $A^T = \text{rank of } A$.

(27) To have rank 1 the ^{two} rows must be multiples of each other
 $\therefore$ the two columns must be multiples of each other

~~not~~ $\begin{pmatrix} a \\ b \end{pmatrix}$

$C = ka$

~~$d = kb$~~

To make the rows multiples of each other assume row 2
 is a multiple k of row 1 or

$$ka = c \quad \text{and} \quad kb = d$$

$$\therefore k = \frac{c}{a} \quad \therefore d = \frac{c}{a} \cdot b$$

Since the rows
 are multiples of each other
 the columns must also be
 multiples of each other
 for the rank to be 1
 if the columns are not multiples
 of each other the rank is 2

A basis for the row space is then given by

the vector ~~$\begin{pmatrix} a \\ b \end{pmatrix}$~~ (a, b) + ~~the rest~~ a basis

for the Null space is given by $\begin{bmatrix} -\frac{b}{a} \\ 1 \end{bmatrix}$ & $\begin{bmatrix} -b \\ a \end{bmatrix}$

(28) The rank of B is 2 & has a basis for the row space given by the last two rows in its

Q representation. ~~It is left null space is given~~

~~try~~ (It must be of dimension $8-2=6$) + when reduced to Row echelon form looks like

$$\begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

And Thus a basis for the left Null space is given by

~~the rest~~

The reduced row echelon matrix looks like

$$\begin{bmatrix} 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & & & & & & & 0 \\ 0 & & & & & & & 0 \\ 0 & & & & & & & 0 \\ 0 & & & & & & & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

with E defined by $EA = R$ w/

$$E = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$