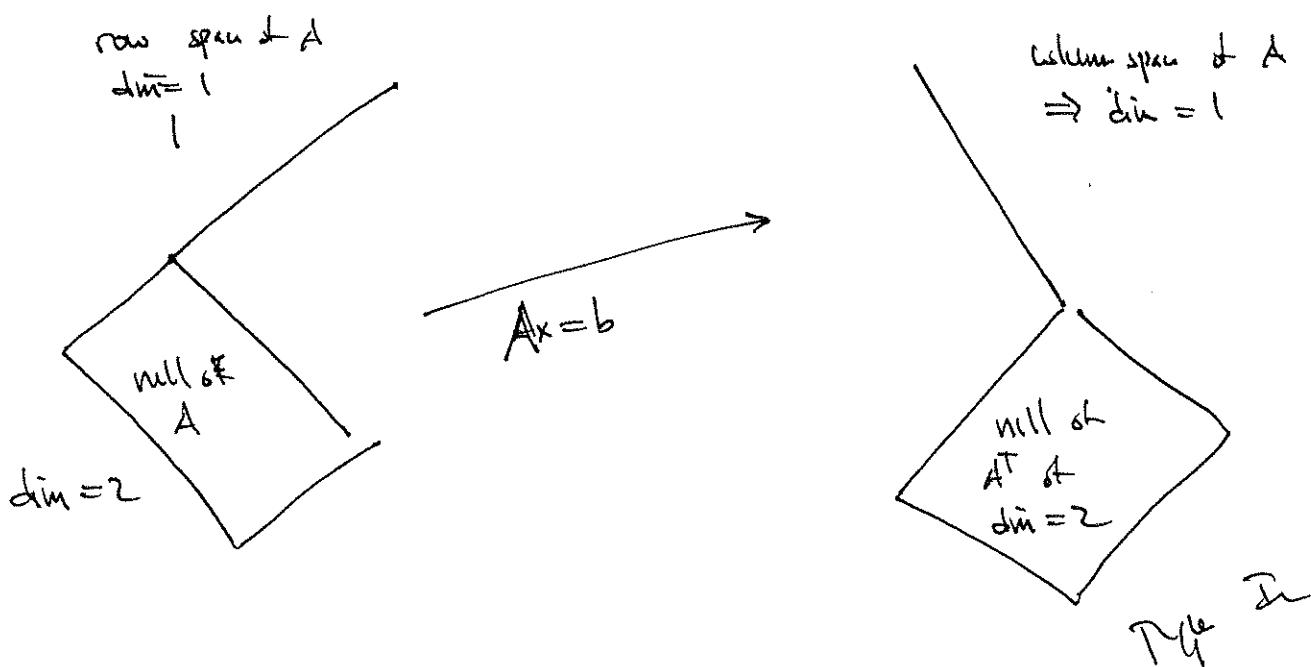


① A is  $2 \times 3$  so  $m=2 + n=3 + r=1$

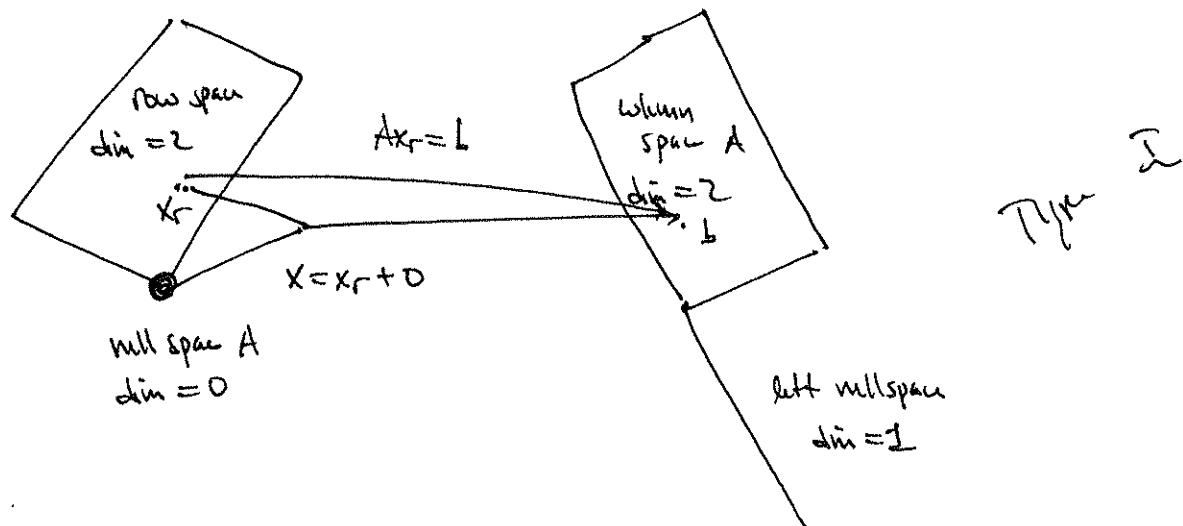
Then row space of A has dimension 1  
- columns space of A has dimension 1  
the null space of A has size  $n-r = 3-1 = 2$   
the left nullspace of A has size  $m-r = 2-1 = 1$



②  $m=3, n=2, r=2$

$$\dim N(A) = 2-2 = 0$$

$$\dim N(A^T) = 3-2 = 1$$



M 171 Stay

(e) ~~1 1 1~~ The fact that the columns add to the zero column

means that the vector of all ones is in the nullspace of this matrix.

Let's see if we can construct a  $2 \times 2$  example of a matrix that has the desired properties. 1st

$$\boxed{A} \quad \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = 0 \Rightarrow \begin{array}{l} a+b=0 \\ c+d=0 \end{array}$$

$$+ \quad \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} 1 & 1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} a+c & b+d \end{bmatrix} = \begin{bmatrix} 1 & 1 \end{bmatrix}$$

This is the system to solve:

$$\begin{array}{l} a+b=0 \\ c+d=0 \\ a+c=1 \\ b+d=1 \end{array} \Rightarrow$$

$$\left[ \begin{array}{cccc} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{array} \right] \left[ \begin{array}{c} a \\ b \\ c \\ d \end{array} \right] = \left[ \begin{array}{c} 0 \\ 0 \\ 1 \\ 1 \end{array} \right]$$

Take

performing row reduction on the augmented matrix we have

$$\left[ \begin{array}{ccccc} 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 & 1 \end{array} \right] \Rightarrow \left[ \begin{array}{ccccc} 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & -1 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 & 1 \end{array} \right] \Rightarrow \left[ \begin{array}{ccccc} 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & -1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 & 2 \end{array} \right]$$

$$\Rightarrow \left[ \begin{array}{ccccc} 1 & 0 & 1 & 0 & 1 \\ 0 & -1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 2 \end{array} \right] \quad \text{since the last two equations contradict each other I conclude this is not possible}$$

Also ~~if~~, a row of all ones will be in the nullspace but also in the row space, but since  $\mathbf{G}$  the vector is not zero this is a contradiction + no such matrix exists

- ④  ~~$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$~~  It is not possible for the ~~nullspace~~ <sup>row space</sup> to contain the ~~nullspace~~. ~~if~~ let  $x$  be nullspace  
a number of 5x1, then from the 2nd fundamental theorem of linear algebra  $x^T x = 0$  which is not true ~~unless~~ unless  $x = 0$   
that the row space + null space are orthogonal

⑤ (a)  $y$  is perpendicular to  $b$ , since  $b$  is in the column space of  $A$   
~~(b)~~  $A^T y$  is in  $A^T$ 's left nullspace

(b) ~~if  $A^T y$  is in the nullspace of  $A^T$~~

~~If  $A^T y$  is in the nullspace of  $A^T$~~  If  $Ax=b$  has no solution then  
 $b$  is not in the column space of  $A$  therefore  $y^T b \neq 0$

+  $y$  is not perpendicular to  $L$

⑥ If  $x = x_r + x_n$  Then  $Ax = Ax_r + Ax_n = Ax_r + 0 = Ax_r$   
~~because~~  $Ax_r$  is a linear combination of the columns It is in the column space  
 because  $Ax_r$  is a linear combination of the columns

⑦ For  $Ax$  to be in the Nullspace of  $A^T$  ~~it must be in the left nullspace of  $A$~~   
~~so~~  ~~$A^T A x = 0$~~  it must be in the left nullspace of  $A$   
~~so~~ the fact  $Ax$  is in the column space of  $A$  + these  
 two spaces are orthogonal. Because it is in both  
 it must be a zero vector

⑧ Its column space is perpendicular to its left nullspace but  
 by the symmetry of  $A$  the left nullspace is the sum of  
 its Nullspace

(b) If  $Ax = 0$  &  $Az = 5z$  then

$$z^T A^T = 5z^T$$

$$\text{or } z^T A x = 5z^T x$$

$\Rightarrow$  since  $Ax = 0$  then  $5z^T x = 0 \Rightarrow z^T x = 0$ .

In terms of subspace  $x$  is in the nullspace & left nullspace of  $A$ .

$z$  is in the column space of  $A$  &  $\therefore$  since the column space ~~is~~ left nullspace or  $\perp$  we have  $x \perp z$  perpendicular

⑨  $A = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix}$

Then the row space is given by  $\text{span} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

The column space is given by  $\text{span} \begin{bmatrix} 1 \\ 3 \end{bmatrix}$

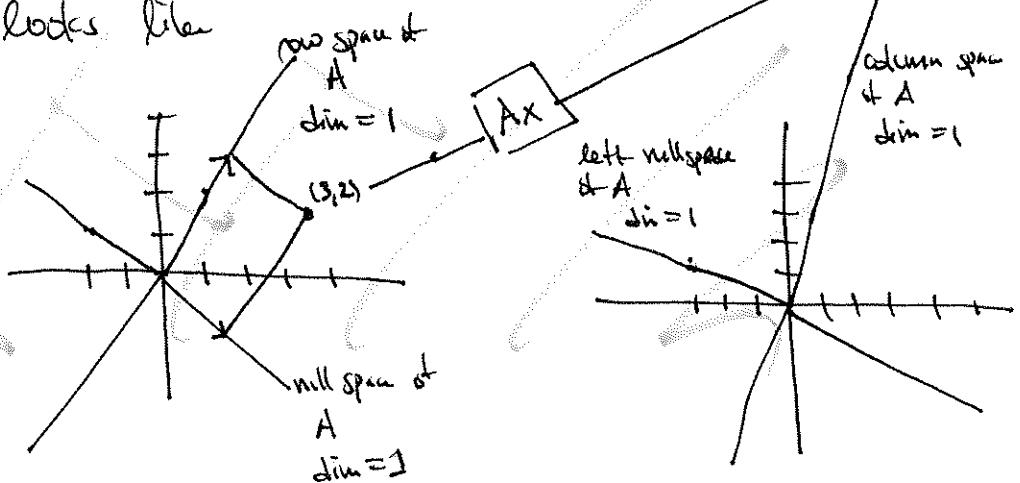
The nullspace is given by  $\text{span} \begin{bmatrix} -2 \\ 1 \end{bmatrix}$

The left nullspace is given by  $\text{span} \begin{bmatrix} -3 \\ 1 \end{bmatrix}$

Thus Figure 4.2 looks like

$$A \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 5 \\ 2 \end{bmatrix} \quad \begin{bmatrix} 5 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

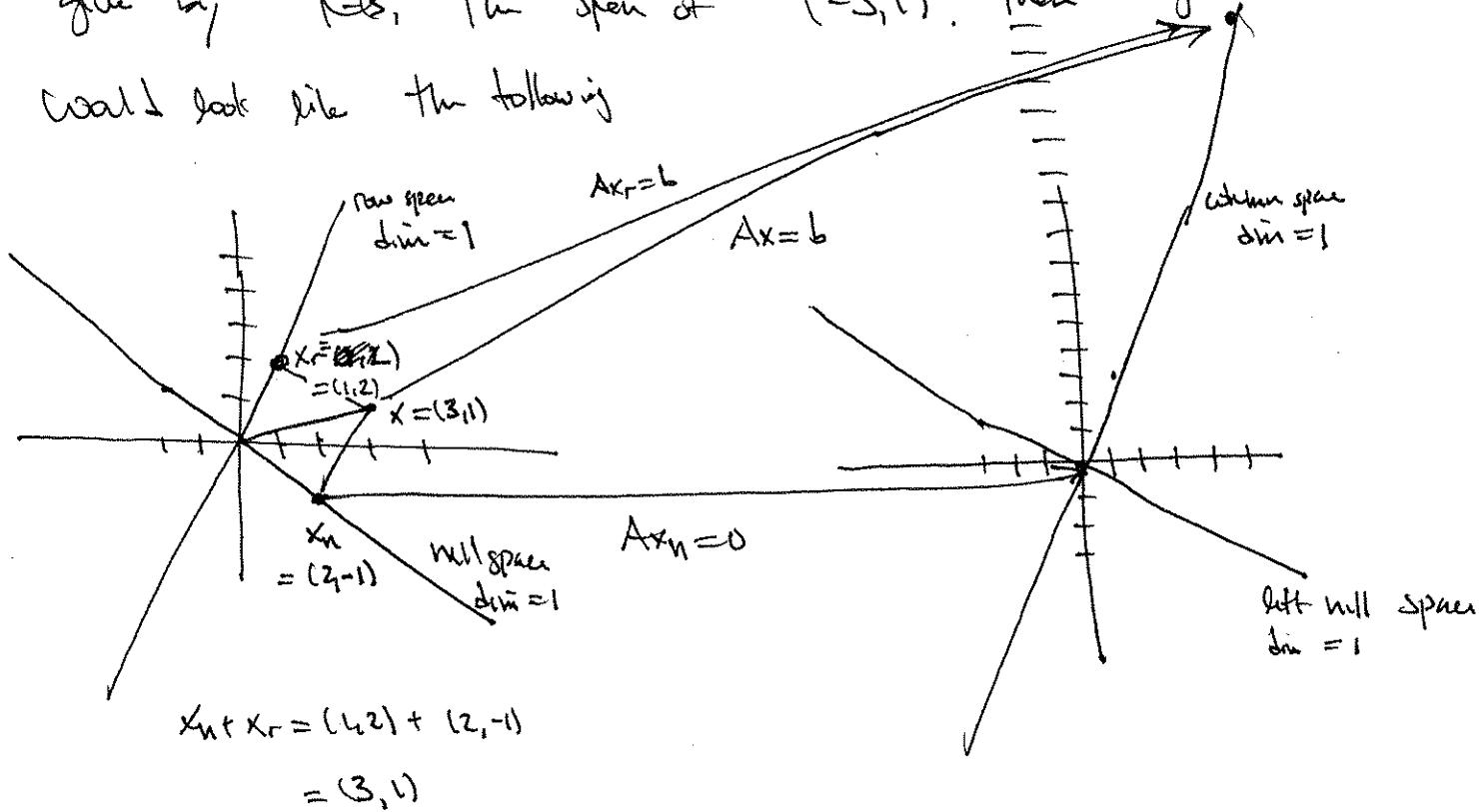
$$= \begin{bmatrix} 7 \\ 11 \end{bmatrix}$$



Pg 172 Stray

$$\textcircled{9} \quad A = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix}$$

has rank = 1 a ~~nullspace~~ given by the row space given by the span of  $(1, 2)$  a column space given by the span of  $(1, 3)$ , and a nullspace given by  $(-2, 1)$ , + a left nullspace given by GB, the span of  $(-3, 1)$ . Then Figure 4.2 would look like the following



Then  $Ax = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 5 \\ 9+6 \end{bmatrix} = \begin{bmatrix} 5 \\ 15 \end{bmatrix}$

$$Ax_n = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\text{For } B = \begin{bmatrix} 1 & 0 \\ 3 & 0 \end{bmatrix}$$

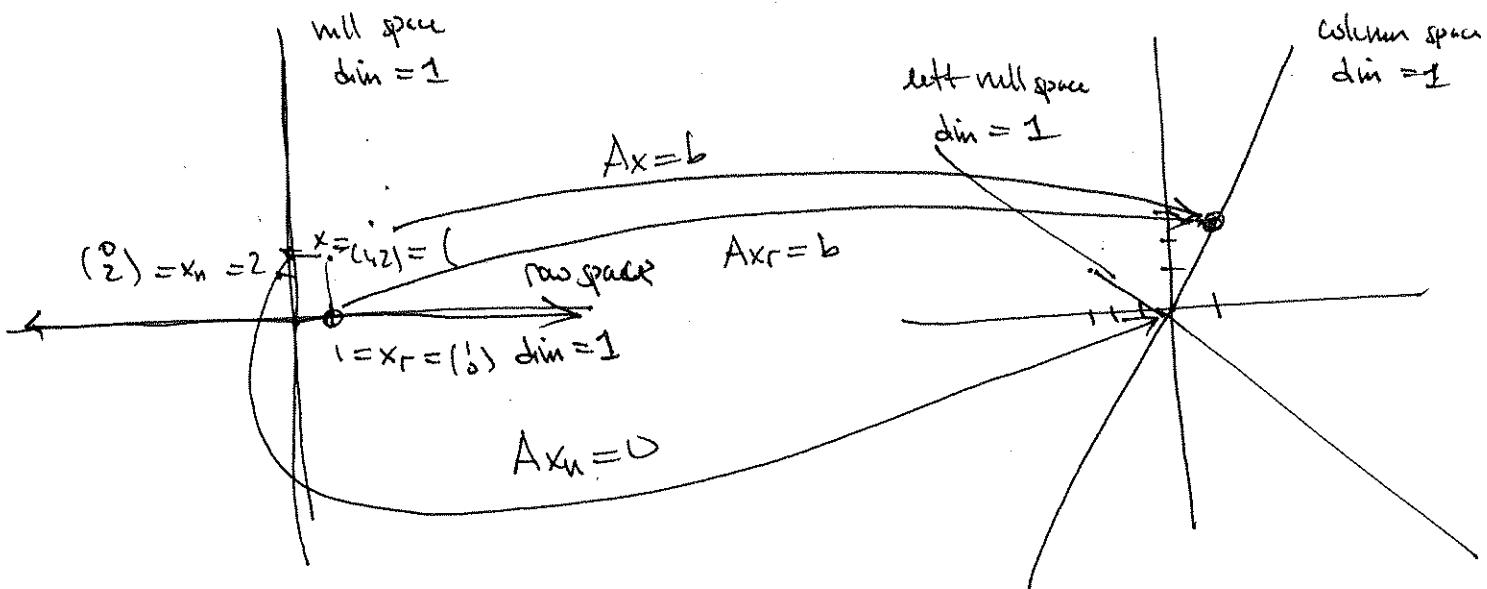
We have a rank of 1, a row space given by the span of  $(1, 0)$ ,

a column space given by the span of  $(1, 3)$ ,

A null space given by the span of  $(0, 1)$ , & finally a

left null space given by the span of  $(-3, 1)$ . Then Fig 4.2

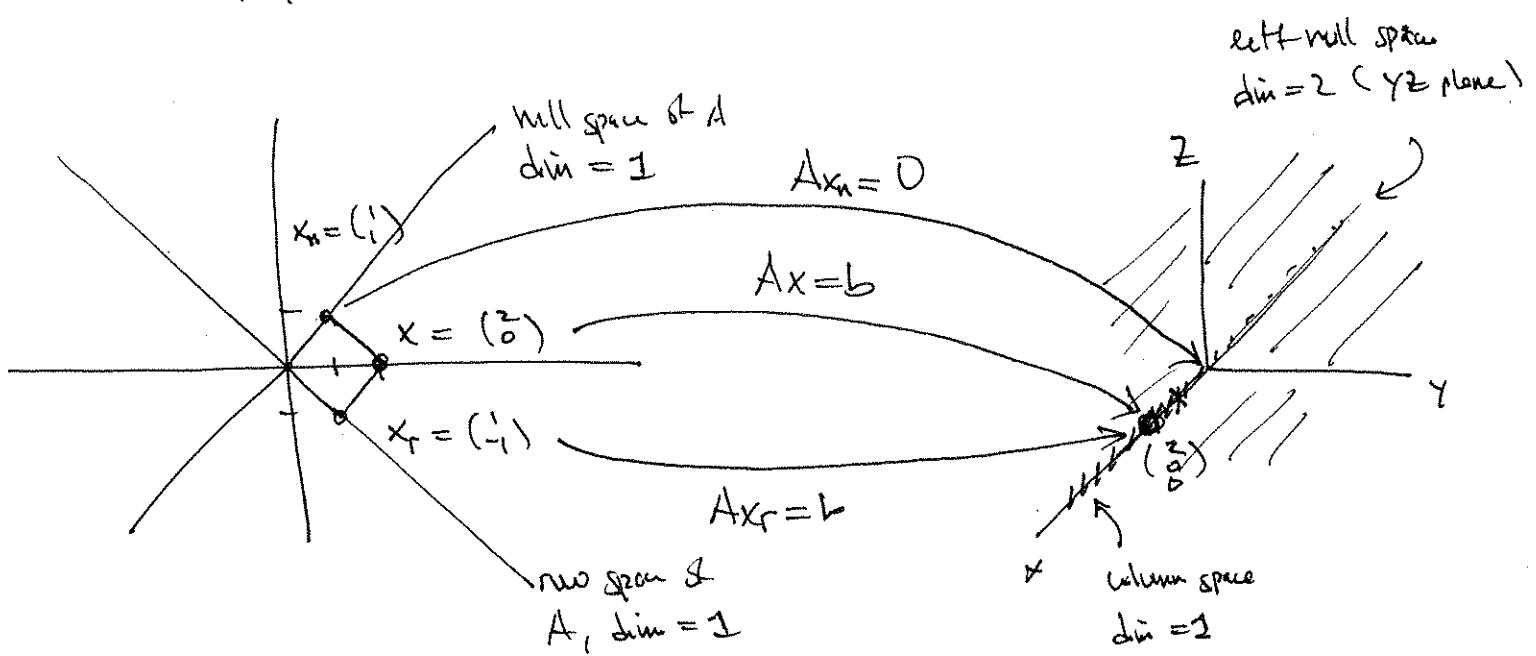
wall looks like



$$\text{Then } BX = \begin{bmatrix} 1 & 0 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

(10) let  $A = \begin{bmatrix} 1 & -1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$

Then  $A$  has rank  $r=2$ , a row space given by the span of  $(1, -1)$  a column space given by the span of  ~~$(1, 0, 0)$~~   $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ , a null space given by the span of  $(1, 1)$  + a left null space given by the span of  $(0, 1, 0)$  +  $(0, 0, 1)$ . Then Fig 4.2 will look like



The  $Ax = \begin{bmatrix} 1 & -1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}$

(11) let  $y \in N(A^T)$

Then  $A^T y = 0$

$$\therefore y^T A x = (\cancel{x^T A^T y})^T = (\cancel{x^T (A^T y)})^T = (y^T A x)^T$$

since  $y^T A x$  is a scalar. But  $(y^T A x)^T = x^T A^T y = x^T 0 = 0$   
~~so~~  $\therefore y$  is  $\perp$  to  $Ax$ .

(12) The Fredholm alternative is, exactly one of these two problems  
 has a solution

(1)  $Ax = b$   $b$  is in the column space of  $A$ .

(2)  $A^T y = 0 \quad \nmid b^T y \neq 0$  or there exist a ~~not~~ vector in  
 the left null space that is not  
 orthogonal to  $b$ .

To make case (2) hold

pick  $A = \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix}$  +  $b = \begin{bmatrix} 3 \\ 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$

Then  $Ax = b$  has no solution. We can show this by considering the

augmented matrix  $[A \ b] = \begin{bmatrix} 1 & 0 & 3 \\ 2 & 0 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 2 \\ 0 & 0 & -3 \end{bmatrix}$

Since the last row is not all zeros, ~~so~~  $\therefore Ax = b$  has no solution

For the second part of the Fadholm alternative, find  $y$  such

that  $A^T y = 0$  +  $b^T y \neq 0$

$A^T y$  is given by  $\begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

Then  $\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix} c$

so ~~it~~ <sup>then</sup>  $b^T y = 2(-2) + 1(1) = -3 \neq 0$ .

$\therefore$   $y = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$  will work.

(13)  $S = \{0\}$  then  $S^\perp = \mathbb{R}^3$ .

If  $S = \text{Span}\{(1,1,1)\}$  then  $S^\perp = \text{all vectors } y \text{ such}$

that  $y^T \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = 0 \Rightarrow y_1 + y_2 + y_3 = 0$

~~$S^\perp$~~  =  ~~$\text{Span}\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \}$~~

$\Rightarrow \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = 0$

$\therefore$  ~~all~~ the two elements in the Nullspace are given by

$$y_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + y_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

If  $S = \text{Span} \left\{ \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix} \right\}$  Then  $S^\perp$  consists of all

vectors  $y$  such that  $y^T \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} = 0 + y^T \begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix} = 0$

$$\text{So } 2y_1 = 0 + 3y_3 = 0 \Rightarrow y_1 = 0 + y_3 = 0$$

$$\text{So } S^\perp = \text{Span} \left[ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right]$$

⑭  $S^\perp$  is the nullspace of  $A = \begin{bmatrix} 1 & 5 & 1 \\ 2 & 2 & 2 \end{bmatrix}$

~~A~~

$\therefore S^\perp$  is a subspace of even if  $S$  is not.

⑮  $L^\perp$  is the plane  $\perp$  to this line. Then  $(L^\perp)^\perp$  is a line  $\perp$  to  $L^\perp$ , so  $(L^\perp)^\perp$  is the same line as originally

⑯  $V^\perp$  contains only the zero vector

The  $(V^\perp)^\perp$  contains all of  $\mathbb{R}^4$ , so  $(V^\perp)^\perp$  is the same as  $V$ .

⑰

- ⑯ Suppose  $S$  is spanned by  $(1, 2, 2, 3) + (1, 3, 3, 2)$   
 Then  $S^\perp$  is spanned by the null space to the metric

$$A = \begin{bmatrix} 1 & 2 & 2 & 3 \\ 1 & 3 & 3 & 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 2 & 3 \\ 0 & 1 & 1 & -1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 & 5 \\ 0 & 1 & 1 & -1 \end{bmatrix}$$

so a nullspace given by  $x_3 = 1, x_4 = 0 + x_1 = 0 + x_2 = -1$   
 $+ x_3 = 0, x_4 = 1 \therefore x_1 = -5, x_2 = 1$   
 so it is spanned by

$$\underline{x} = \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} -5 \\ 1 \\ 0 \\ 1 \end{bmatrix}$$

- ⑰ If  $P$  is the plane <sup>given</sup> then  $A = [1 \ 1 \ 1 \ 1]$  has  
 this plane as its Nullspace. Then  $P^\perp$  are the elements of  
 the left nullspace of  $A$  i.e. the nullspace of  $A^T$

sin  $A^T = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$  we have a null space

given by the span of  $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

(19) If  $S \subset V$  then  $S^\perp \supset V^\perp$

Pf:

let  $y \in V^\perp$  then  $\forall$  element  $x \in V$  we have  $x^T y = 0$ .

~~But~~ But we can say that  $\forall$  element  $x \in S$  if ~~is~~ also <sup>is</sup>  $x \in V^\perp$

in  $V^\perp$   $\therefore x^T y = 0$  so  $y \in S^\perp$ . Therefore  $V^\perp \subset S^\perp$

(20) The 1st column ~~is~~ <sup>spanned</sup> orthogonal of  $A^\perp$  is orthogonal to the sum of the 2nd through the ~~end~~ <sup>last</sup> columns of  $A$

(21)  $A^\perp A$  would be  $I$ .

$$\text{Q.E.D.}$$

$$A = \begin{bmatrix} 1 & -1 & x & 1 \\ -1 & 1 & y & -1 \\ 2 & 1 & z & 1 \end{bmatrix}$$

$$-1 -1 -1 \neq 0$$

We can pick two vector that are orthogonal to example easily.

$$\text{let } A_1 = \begin{bmatrix} 1 & -1 \\ -1 & 1 \\ 2 & 1 \end{bmatrix}$$

Then we are looking for a 3rd vector that is orthogonal to these two.

Pg 173 Stray

(22)

$$\text{Start if } I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

How compute a matrix like requested?

$A^T A$  must be diagonal since it represents every

~~row~~ times every column of  $A$ . When the rows + to

column of  $A$  times every column of  $A$ . When the two

columns are different the result is 0. When they are the same the result is the squared of that column result

(23) The lines  $3x+y=b_1$  +  $6x+2y=b_2$  are parallel

They are the same line if  $2b_1=b_2$ . Then  $(b_1, b_2)$  is

$\perp$  to the left nullspace of  $A = \begin{bmatrix} 3 & 1 \\ 6 & 2 \end{bmatrix}$  or

$$\begin{bmatrix} -2 \\ 1 \end{bmatrix} \quad (\text{check } \begin{bmatrix} -2 & 1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = -2b_1 + b_2 = -2b_1 + 2b_1 = 0)$$

The Nullspace of the matrix is the line  $3x+y=0$ .

One vector in the Nullspace is  $(-1, 3)$

(24) (a) As discussed in the book if two subspaces are orthogonal then they can only ~~meet~~ meet at the origin. But for these two planes we have many intersections. Solve the system

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0 \quad \text{then } (x, y, z) \text{ will be on both planes}$$

$$\Rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & -3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0$$

$$\Rightarrow \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0$$

So  $z=0$  +  $x+y=0$  so any vector of the form

$$Y = \begin{bmatrix} x \\ -x \\ 0 \end{bmatrix} = \text{Span} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \text{ is in both planes but}$$

~~cannot~~ ~~be~~ then spaces cannot be orthogonal

(b) The two lines specified are described as the span of the vectors  $\begin{bmatrix} 2 \\ 4 \\ 5 \end{bmatrix}$  +  $\begin{bmatrix} 1 \\ -3 \\ 2 \end{bmatrix}$  respectively.

For their subspaces to be orthogonal, the subspace generating vectors must be orthogonal. In this case

$$(2 \ 4 \ 5)^T \begin{pmatrix} 1 \\ -3 \\ 2 \end{pmatrix} = 2 - 12 + 10 = 0 \quad \checkmark$$

They are. So the subspaces are orthogonal, ~~but still~~ we still need to show that they are not orthogonal complements.

To do so it suffices to find a vector orthogonal to one, that is not in the other space. Consider space

$$\mathcal{A} = A = [2 \ 4 \ 5]$$

which has a null space given by

$$\begin{aligned} x_2 = 1, x_3 = 0 + x_1 = -2 &\Rightarrow x = \begin{bmatrix} \cancel{x_1} \\ \cancel{x_2} \\ 0 \\ \cancel{x_3} \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} \\ + x_2 = 0, x_3 = 1 + x_1 = -x_2 &\Rightarrow x = \begin{bmatrix} -x_2 \\ 0 \\ 1 \end{bmatrix} \end{aligned}$$

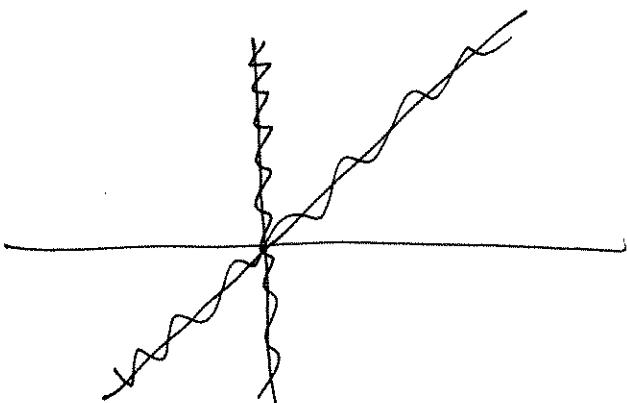
Now consider the vector  $\begin{bmatrix} -2 \\ 1 \end{bmatrix}$ . It is orthogonal to

$\begin{bmatrix} 2 \\ 4 \\ 5 \end{bmatrix}$  & thus is in its orthogonal complements but is

not in the span of  $\begin{bmatrix} 1 \\ -3 \\ 2 \end{bmatrix}$ . Thus the two spaces

are not the orthogonal complements of each other.

(c) consider the subspaces  $\text{span} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$  &  $\text{span} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$



They meet only at the origin  
but are not orthogonal

(25)

$$\text{let } A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 5 \\ 3 & 6 & 7 \end{bmatrix}$$

$\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$  is both row space + nullspace

$$\text{let } B = \begin{bmatrix} 1 & 1 & -1 \\ 2 & 2 & -2 \\ 3 & 3 & -3 \end{bmatrix}$$

The  $(1, 2, 3)$  is in the column space +

$$B \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \cdot 0 \\ 3 \cdot 0 \end{pmatrix} = \underline{0}$$

✓ could not be in the row space of  $A$  + the nullspace of  $A$

✓ could not be in the column space of  $A$  + the left nullspace of  $A$

But it could be in the ~~the~~ row space + left nullspace

or the nullspace + left nullspace

(26)

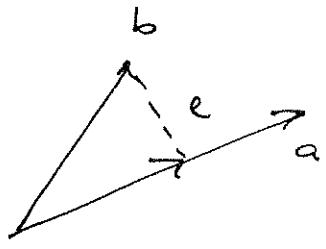
a basis for the left nullspace of  $A$

Ex 18) Stray

①

(a)

$$\hat{x} = \frac{a^T b}{a^T a} + p = a \frac{a^T b}{a^T a} + P = \frac{aa^T}{a^T a}$$



Then  $\hat{x} = \frac{1+2+2}{1+1+1} = \frac{5}{3}$

so  $P = \frac{5}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

Then  $e = b - p = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} - \frac{5}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{2}{3} \\ \frac{1}{3} \\ \frac{1}{3} \end{bmatrix} = \begin{bmatrix} -2/3 \\ 1/3 \\ 1/3 \end{bmatrix}$

$$= \frac{1}{3} \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}$$

Is  $e$  orthogonal to  $a$ ?

$$e^T a = \frac{1}{3} (-2 + 1 + 1) = 0 \quad \text{Yes}$$

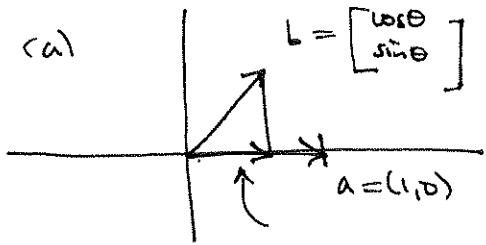
(b)  $\hat{x} = \frac{a^T b}{a^T a} = \frac{-1-9-1}{1+9+1} = -1$

so  $p = \hat{x} a = -a = \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix}$

The error is then  $e = b - p = 0$

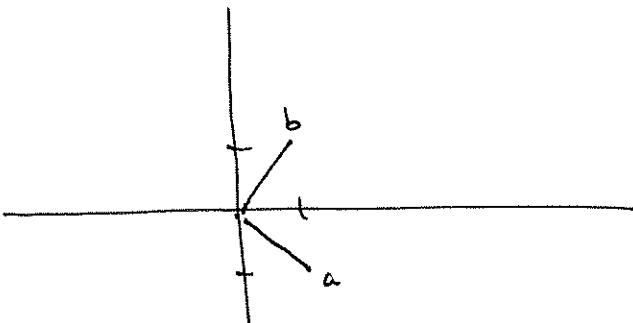
which is orthogonal to  $a$ .

(2) (a)



$$P = \hat{x}a = \frac{a^T b}{a^T a} a = \frac{\cos \theta}{1} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \cos \theta \\ 0 \end{bmatrix}$$

(b)



The projection of b onto a is zero.

$$P = \hat{x}a = \frac{a^T b}{a^T a} a = \frac{1-1}{2} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

(3) For pt (a)

$$P = \frac{aa^T}{a^T a} = \frac{\begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \end{bmatrix}}{3} = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

Then  $P^2 = \frac{1}{9} \begin{bmatrix} 3 & 3 & 3 \\ 3 & 3 & 3 \\ 3 & 3 & 3 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} = P$

$$Pb = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 5 \\ 5 \\ 5 \end{bmatrix}$$

For pt (b) we have

$$P = \frac{1}{11} \begin{bmatrix} -1 \\ 3 \\ -1 \end{bmatrix} \begin{bmatrix} -1 & -3 & -1 \end{bmatrix} = \frac{1}{11} \begin{bmatrix} 1 & 3 & 1 \\ 3 & 9 & 3 \\ 1 & 3 & 1 \end{bmatrix}$$

$$\text{Then } P = Pb = \frac{1}{11} \begin{bmatrix} 1 & 3 & 1 \\ 3 & 9 & 3 \\ 1 & 3 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix}$$

$$= \frac{1}{11} \begin{bmatrix} 11 \\ 22 \\ 11 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

$$+ \quad P^2 = \frac{1}{11^2} \begin{bmatrix} 1 & 3 & 1 \\ 3 & 9 & 3 \\ 1 & 3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 & 1 \\ 3 & 9 & 3 \\ 1 & 3 & 1 \end{bmatrix} = \frac{1}{11^2} \begin{bmatrix} 11 & 33 & 11 \\ 33 & 99 & 33 \\ 11 & 33 & 11 \end{bmatrix} = \frac{1}{11} \begin{bmatrix} 1 & 3 & 1 \\ 3 & 9 & 3 \\ 1 & 3 & 1 \end{bmatrix}$$

④ For  $P(a)$   $P_1 = \frac{aa^T}{a^T a} = \frac{\begin{bmatrix} 1 \\ 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \end{bmatrix}}{1} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$

+ For  $P_1 + P_2$   $P_1 = \frac{aa^T}{a^T a} = \frac{\begin{bmatrix} 1 \\ -1 \end{bmatrix} \begin{bmatrix} 1 & -1 \end{bmatrix}}{2} = \frac{1}{2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$

Then  $P_1^2 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = P_1$

+  $P_2^2 = \frac{1}{4} \begin{bmatrix} 2 & -2 \\ -2 & 2 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = P_2$

Which should be true since the action of one projection will not change when we do it again.

(5)

$$P_1 = \frac{aa^T}{a^T a} = \frac{\begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix} \begin{bmatrix} -1 & 2 & 2 \end{bmatrix}}{1+4+4} \quad \leftarrow \begin{bmatrix} 1 & -2 & -2 \\ -2 & 4 & 4 \\ -2 & 4 & 4 \end{bmatrix}$$

$$= \frac{1}{9} \begin{bmatrix} 1 & -2 & -2 \\ -2 & 4 & 4 \\ -2 & 4 & 4 \end{bmatrix} \checkmark$$

$$+ P_2 = \frac{\begin{bmatrix} 2 \\ 2 \\ -1 \end{bmatrix} \begin{bmatrix} 2 & 2 & -1 \end{bmatrix}}{4+4+1} = \frac{1}{9} \begin{bmatrix} 4 & 4 & -2 \\ 4 & 4 & -2 \\ -2 & -2 & +1 \end{bmatrix}$$

$$\text{so } P_1 \cdot P_2 = \frac{1}{81} \begin{bmatrix} 1 & -2 & -2 \\ -2 & 4 & 4 \\ -2 & 4 & 4 \end{bmatrix} \begin{bmatrix} 4 & 4 & -2 \\ 4 & 4 & -2 \\ -2 & -2 & +1 \end{bmatrix} \quad \checkmark$$

$$= \frac{1}{81} \begin{bmatrix} X-8+4 & 4-8+4 & -2+4+2 \\ -8+16-8 & -8+16-8 & 4-8+4 \\ -8+16-8 & -8+16-8 & 4-8+4 \end{bmatrix}$$

$$= \frac{1}{81} \begin{bmatrix} -8 & -8 & 4 \\ 16 & 16 & -8 \\ 16 & 16 & -8 \end{bmatrix} \quad 0$$

$$= \frac{4}{81} \begin{bmatrix} -2 & 1 \\ 4 & -2 \\ 4 & -2 \end{bmatrix}$$

Another way to see this is to consider

$$\overline{P_1 P_2} = \frac{\mathbf{a}_1 \mathbf{a}_1^T}{\mathbf{a}_1^T \mathbf{a}_1} \cdot \frac{\mathbf{a}_2 \mathbf{a}_2^T}{\mathbf{a}_2^T \mathbf{a}_2}$$

$$= \frac{1}{\mathbf{a}_1^T \mathbf{a}_1} \frac{1}{\mathbf{a}_2^T \mathbf{a}_2} \mathbf{a}_1 \mathbf{a}_1^T \mathbf{a}_2 \mathbf{a}_2^T$$

$$= (\quad)(\quad) \underbrace{\mathbf{a}_1 (\mathbf{a}_1^T \mathbf{a}_2)}_{\equiv 0} \mathbf{a}_2^T$$

$$= 0$$

$$\text{Since } \mathbf{a}_1^T \mathbf{a}_2 = 0$$

Then this is to be expected since  $\mathbf{a}_1 + \mathbf{a}_2$  or perpendicular  
a vector  
+ to project onto  $\mathbf{a}_1$  produces a vector that is perpendicular  
to  $\mathbf{a}_2$  + ∵ when projected onto  $\mathbf{a}_2$  will then produce the  
zero vector

(6)

~~From~~ From problem 5 we have

$$P_1 = \frac{1}{9} \begin{bmatrix} 1 & -2 & -2 \\ -2 & 4 & 4 \\ -2 & 4 & 4 \end{bmatrix} \quad \text{so} \quad P_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \frac{1}{9} \begin{bmatrix} 1 \\ -2 \\ -2 \end{bmatrix}$$

$$+ \quad P_2 = \frac{1}{9} \begin{bmatrix} 4 & 4 & -2 \\ 4 & 4 & -2 \\ -2 & -2 & 1 \end{bmatrix} \quad \text{so} \quad P_2 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \frac{1}{9} \begin{bmatrix} 4 \\ 4 \\ -2 \end{bmatrix}$$

$$\oplus \quad P_3 = \frac{a_3 a_3^T}{a_3^T a_3} = \frac{\begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix} \begin{bmatrix} 2 & -1 & 2 \end{bmatrix}}{4+1+4} = \frac{1}{9} \begin{bmatrix} 4 & -2 & 4 \\ -2 & 1 & -2 \\ 4 & -2 & 4 \end{bmatrix}$$

$$\text{so} \quad P_3 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \frac{1}{9} \begin{bmatrix} 4 \\ -2 \\ 4 \end{bmatrix}$$

Then  $P_1 + P_2 + P_3 = \frac{1}{9} \begin{bmatrix} 1+4+4 \\ -2+4-2 \\ -2-2+4 \end{bmatrix} = \frac{1}{9} \begin{bmatrix} 9 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

We can project onto 3 orthogonal axes  $a_1, a_2, + a_3$

$$a_3^T a_1 = -2-2+4 = 0$$

$$a_3^T a_2 = 4-2-2 = 0$$

$$\textcircled{7} \quad P_3 = \frac{\mathbf{a}_3 \mathbf{a}_3^T}{\mathbf{a}_3^T \mathbf{a}_3} = \frac{1}{4+1+4} \begin{bmatrix} 2 \\ -1 \\ 2 \end{bmatrix} \begin{bmatrix} 2 & -1 & 2 \end{bmatrix}$$

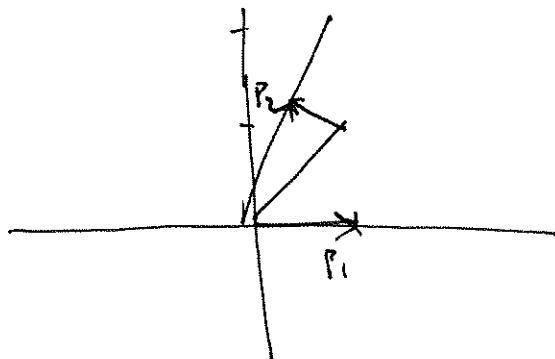
$$= \frac{1}{9} \begin{bmatrix} 4 & -2 & 4 \\ -2 & 1 & -2 \\ 4 & -2 & 4 \end{bmatrix}$$

Then  $P_1 + P_2 + P_3 = \frac{1}{9} \begin{bmatrix} 1+4+4 & -2+4-2 & -2-2+4 \\ -2+4-2 & 4+4+1 & 4-2-2 \\ -2-2+4 & 4-2-2 & 4+1+4 \end{bmatrix}$

$$= I$$

$$\textcircled{8} \quad \hat{x}_1 = \frac{\mathbf{a}_1^T \mathbf{b}}{\mathbf{a}_1^T \mathbf{a}_1} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \text{Then } P_1 = \hat{x}_1 \mathbf{a}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\hat{x}_2 = \frac{\mathbf{a}_2^T \mathbf{b}}{\mathbf{a}_2^T \mathbf{a}_2} = \frac{3}{5} \quad \text{so} \quad P_2 = \hat{x}_2 \mathbf{a}_2 = \frac{3}{5} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$



$$P_1 + P_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \frac{3}{5} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 8/5 \\ 6/5 \end{bmatrix} = \frac{2}{5} \begin{bmatrix} 4 \\ 3 \end{bmatrix} \neq$$

① The projection onto the plane  $a_1 + a_2$  is given by  
~~the matrix~~  $A(A^T A)^{-1} A^T$  The full  $\mathbb{R}^2$  so, a project.

~~W = A~~  $\Rightarrow$  Matrix is  $I$

Since  $A$  is  $2 \times 2$  with linearly independent columns

$$\begin{aligned} A^T A \text{ is invertible. } A^T A &= \begin{bmatrix} 1 & 1 \\ 0 & 2 \end{bmatrix}^T \begin{bmatrix} 1 & 1 \\ 0 & 2 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 5 \end{bmatrix} \end{aligned}$$

$$\therefore (A^T A)^{-1} = \frac{1}{4} \begin{bmatrix} 5 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\begin{aligned} \text{Now } A(A^T A)^{-1} A^T &= \begin{bmatrix} 1 & 1 \\ 0 & 2 \end{bmatrix} \frac{1}{4} \begin{bmatrix} 5 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \\ &= \frac{1}{4} \begin{bmatrix} 1 & 1 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 4 & -2 \\ 0 & 2 \end{bmatrix} \\ &= \frac{1}{4} \begin{bmatrix} 4 & 0 \\ 0 & 4 \end{bmatrix} = I \quad \text{as desired} \end{aligned}$$

$$\textcircled{10} \quad \hat{x} = \cancel{\frac{a_1^T b}{a_1^T a_1}} \quad \cancel{\frac{a_2^T b}{a_2^T a_2}} =$$

we know the ~~orthogonal~~ or given by  
 when we project  $b$  onto  $a$ ,  $\hat{x} = \frac{a^T b}{a^T a} + \text{proj } a_1 \text{ onto } a_2$   
 without giving

$$\text{we have, } \hat{x} = \frac{a_2^T b}{a_2^T a_2} = \frac{1}{5}$$

$$\text{+ the proj is given by } p = \hat{x}a_2 = \frac{1}{5} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

Then project this back onto  $a_1$ . We obtain

$$\hat{x} = \frac{P a_1}{a_1^T a_1} = \frac{1}{5} \frac{(1)}{1} = \frac{1}{5}$$

$$\begin{aligned} P_1 &= \frac{a_2 a_2^T}{a_2^T a_2} \\ &= \frac{1}{5} \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} \\ &= \frac{1}{5} \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \\ + P_2 &= \frac{a_1 a_1^T}{a_1^T a_1} \\ &= \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \end{aligned}$$

$$\text{The } \tilde{p} = \frac{1}{5} a_1 = \frac{1}{5} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\text{So } P_2 P_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \frac{1}{5} \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$$

$$= \cancel{\frac{1}{5} \begin{bmatrix} 1 \\ 2 \end{bmatrix}} = \frac{1}{5} \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}$$

I don't think this is ~~an~~ a projector but, since it  
 will have to be written as proportional to  
 w.r.t row which this could be

Pg 182 Stray

$$(11) \quad A^T A \hat{x} = A^T b + r = A \hat{x}$$

$$(a) \quad A^T A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$+ A^T b = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}$$

$$\text{so } A^T A \hat{x} = A^T b$$

$$\Rightarrow \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix} = \frac{1}{1} \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 4-5 \\ -2+5 \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

$$\text{so } r = A \hat{x} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} -1 \\ 3 \end{bmatrix} = \begin{bmatrix} -1+3 \\ 3 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}$$

$$\text{then } e = b - r = \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} - \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 4 \end{bmatrix}$$

$$(b) \quad A^T A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ 2 & 3 \end{bmatrix}$$

$$+ A^T b = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 4 \\ 3 \\ 6 \end{bmatrix} = \begin{bmatrix} 8 \\ 14 \\ 12 \end{bmatrix}$$

$$\text{so } A^T A \hat{x} = A^T b$$

$$\Rightarrow \hat{x} = \begin{bmatrix} 2 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix} = \begin{bmatrix} 8 \\ 14 \end{bmatrix}$$

$$\begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 3 & -2 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} 8 \\ 4 \end{bmatrix} = \begin{bmatrix} 3 & -2 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} 4 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} 12 - 14 \\ -8 + 14 \end{bmatrix} = \begin{bmatrix} -2 \\ 6 \end{bmatrix}$$

Then  $P = A\hat{x} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -2 \\ 6 \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \\ 6 \end{bmatrix}$

$$e = b - P = \begin{bmatrix} 4 \\ 4 \\ 6 \end{bmatrix} - \begin{bmatrix} 4 \\ 4 \\ 6 \end{bmatrix} = 0$$

⑫ The projection matrix is given by

$$A(A^T A)^{-1} A^T$$

$$P_1 = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \left( \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \right)^{-1} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ -1 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ -1 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Check  $P_1^2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = P_1$

$$\text{Form } P_1 b = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}$$

For the 2nd part we have

$$\begin{aligned} P_2 &= A(A^T A)^{-1} A^T \\ &= \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 0 & 1 \end{bmatrix} \left( \frac{1}{2} \begin{bmatrix} 3 & -2 \\ -2 & 2 \end{bmatrix} \right) \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix} \\ &= \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & -2 \\ 0 & 0 & 2 \end{bmatrix} \\ &= \frac{1}{2} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} \text{The } P_2^2 &= \frac{1}{4} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} = \frac{1}{4} \begin{bmatrix} 2 & 2 & 0 \\ 2 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix} \\ &= \frac{1}{2} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} = P_2 \end{aligned}$$

$$P = P_2 \begin{bmatrix} 4 \\ 9 \\ 6 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 8 \\ 8 \\ 12 \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \\ 6 \end{bmatrix}$$

$$(B) \quad A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

The projection matrix is given by  $A(A^T A)^{-1} A^T$

$$A^T A = \cancel{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{Then } A(A^T A)^{-1} A^T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

so  $P$  is  $4 \times 4$

$$\text{Then } \vec{r} b = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 0 \end{bmatrix}$$

$$(14) \quad b = \underline{\underline{2A(i+1)}}$$

Since  $b$  is in the span of the columns of  $A$  the projection  $P \neq I$  since for vectors not in the column space of  $A$ , their projection is not themselves will be  $b$  itself. As an example let

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 2 \\ 2 & 0 \end{bmatrix} \quad \text{then the projection matrix is given by}$$

$$P = A(A^T A)^{-1} A^T$$

$$\text{Now } A^T A = \begin{bmatrix} 0 & 1 & 2 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 2 \\ 2 & 0 \end{bmatrix} = \begin{bmatrix} 5 & 2 \\ 2 & 5 \end{bmatrix}$$

$$\text{so } (A^T A)^{-1} = \cancel{\begin{bmatrix} 5 & 2 \\ 2 & 5 \end{bmatrix}} * \frac{1}{21} \begin{bmatrix} 5 & -2 \\ -2 & 5 \end{bmatrix}$$

$$+ A(A^T A)^{-1} A^T = \begin{bmatrix} 0 & 1 \\ 1 & 2 \\ 2 & 0 \end{bmatrix} \left( \frac{1}{21} \begin{bmatrix} 5 & -2 \\ -2 & 5 \end{bmatrix} \right) \begin{bmatrix} 0 & 1 & 2 \\ 1 & 2 & 0 \end{bmatrix}$$

$$= \frac{1}{21} \begin{bmatrix} 0 & 1 \\ 1 & 2 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} -2 & 1 & 10 \\ 5 & 8 & 4 \end{bmatrix}$$

$$= \frac{1}{21} \begin{bmatrix} 5 & 8 & -4 \\ 8 & 17 & 2 \\ -4 & 2 & 20 \end{bmatrix}$$

$$\text{so } P = Pb = \frac{1}{21} \begin{bmatrix} 5 & 8 & -4 \\ 8 & 17 & 2 \\ -4 & 2 & 20 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \\ 4 \end{bmatrix} = \frac{1}{21} \begin{bmatrix} 16-16 \\ 34+8 \\ 4+80 \end{bmatrix} = \frac{1}{21} \begin{bmatrix} 0 \\ 42 \\ 84 \end{bmatrix}$$

$$= \frac{1}{7} \begin{bmatrix} 0 \\ 6 \\ 12 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 4 \end{bmatrix} = b.$$

- (15) The column space of  $2A$  is the same as  $A$ .  
 But  $\hat{x}$  is not the sum for  $A + 2A$  since  $b = A\hat{x} + P_A = 2A\hat{x}$   
 $+ P_A = P_{2A}$  the projection is the same  
 so instead  $\hat{x}_A = 2\hat{x}_{2A}$
- which can be seen by writing the equation for  
 $\hat{x}_A + \hat{x}_{2A}$  in terms of  $A$ . For example  
 the equation for  $\hat{x}_A$  is given by
- while that for  $\hat{x}_{2A}$  is given by
- From comparing the two we see that  $\hat{x}_A = 2\hat{x}_{2A}$ .

(16) Solve for  $\hat{x}$  in  $A^T A \hat{x} = A^T b$

with  $A = \begin{bmatrix} 1 & 1 \\ 2 & 0 \\ -1 & 1 \end{bmatrix}$  we have  $A^T A = \begin{bmatrix} 1 & 2 & -1 \\ 1 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 0 \\ 2 & 0 \end{bmatrix} = \begin{bmatrix} 6 & 0 \\ 0 & 2 \end{bmatrix}$

so  ~~$\hat{x}$~~   $\hat{x} = (A^T A)^{-1} A^T b$

$= \begin{bmatrix} 1/6 & 0 \\ 0 & 1/2 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1/6 & 0 \\ 0 & 1/2 \end{bmatrix} \begin{bmatrix} 3 \\ 3 \\ 3 \end{bmatrix}$

$= \begin{bmatrix} 1/2 \\ 3/2 \end{bmatrix}$

Pg 183 Stay

$$\textcircled{17} \quad (I-P)^2 = (I-P)(I-P) = I - P - P + P^2 \\ = I - 2P + P = I - P$$

$I-P$  projects onto the orthogonal complement of the column space of  $A$  or the <sup>left</sup> null space of  $A$ .

- \textcircled{18} (a)  $I-P$  is the projection onto the vector spanned by  $(-1, 1)$
- (b)  $I-P$  is the projection onto the plane  $\perp$  to this line i.e  $x+y+z=0$ . The ~~proj~~ projector matrix is derived from the column of  $A = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$  + has  $x+y+z=0$  as its left nullspace

- \textcircled{19} Consider the plane given by  $x-y-2z=0$   
 Setting the free variables equal to a basis  $(y=1, z=0)$   
 $+ (y=0, z=1)$

We have the following two vectors in the nullspace

$$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}$$

which are two vectors in the nullspace of the plane

2

we then have ~~that~~ by letting  $A = \begin{bmatrix} 1 & 2 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$  we get

that  $A^T A = \begin{bmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ 2 & 5 \end{bmatrix}$

so  $(A^T A)^{-1} = \frac{1}{6} \begin{bmatrix} 5 & -2 \\ -2 & 2 \end{bmatrix}$

$$P = A(A^T A)^{-1} A^T = \frac{1}{6} \begin{bmatrix} 1 & 2 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 5 & -2 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix}$$

$$= \frac{1}{6} \begin{bmatrix} 1 & 2 \\ 5 & -2 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix}$$

$$= \frac{1}{6} \begin{bmatrix} 5 & 1 & 2 \\ 1 & 5 & -2 \\ 2 & -2 & 2 \end{bmatrix}$$

(20) A vector  $\perp$  to the plane  $x-y-2z=0$  is

the vector  $\mathbf{e} = \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix}$  since  $\mathbf{e}^T \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0 \quad \forall x, y, z$

in the plane. Then the projection onto this vector is

given by  $\mathbf{Q} = \frac{\mathbf{e}\mathbf{e}^T}{\mathbf{e}^T\mathbf{e}} = \frac{1}{1+1+4} \begin{bmatrix} 1 & -1 & -2 \\ -1 & 1 & 2 \\ -2 & 2 & 4 \end{bmatrix}$

$$= \cancel{\frac{1}{1+1+4}} \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix}$$

$$= \frac{1}{6} \begin{bmatrix} 1 & -1 & -2 \\ -1 & 1 & 2 \\ -2 & 2 & 4 \end{bmatrix}$$

$$= \frac{1}{6} \begin{bmatrix} 1 & -1 & -2 \\ -1 & 1 & 2 \\ -2 & 2 & 4 \end{bmatrix}$$

Then the projection onto the plane is given by

$$\mathbf{I} - \mathbf{Q} = \cancel{\begin{bmatrix} 1 & -1 & -2 \\ -1 & 1 & 2 \\ -2 & 2 & 4 \end{bmatrix}} \quad \frac{1}{6} \begin{bmatrix} 6 & -1 & 1 & 2 \\ -1 & 6 & -1 & -2 \\ 2 & -2 & 6 & -4 \end{bmatrix}$$

$$= \frac{1}{6} \begin{bmatrix} 5 & 1 & 2 \\ 1 & 5 & -2 \\ -2 & -2 & 2 \end{bmatrix} \quad \text{or the same as obtained in problem 119}$$

(21) If  $P = A(A^T A)^{-1} A^T$

$$\text{then } P^2 = A(A^T A)^{-1} A^T A (A^T A)^{-1} A^T \\ = A(A^T A)^{-1} A^T = P$$

$$P(Pb) = Pb$$

Since  $Pb$  is in the column space of  $A$   $\therefore$  its projection is itself.

(22) If  $P = A(A^T A)^{-1} A^T$

$$\text{then } P^T = A (A (A^T A)^{-1} A^T)^T \\ = A (A^T A)^{-T} A^T \\ = A [(A^T A)^T]^{-1} A^T \\ = A (A^T A)^{-1} A^T = P$$

(23) When  $A$  is invertible the sum of its columns is equal to the ~~the~~ entire space from which we are deriving. Therefore since  $b$  is in ~~the~~  $\mathbb{R}^n$  its projection into

i.e.  $\mathbb{R}^n$

$\mathbb{R}^n$  must be itself. The error then is zero

(24) The Nullspace of  $A^T$  is perpendicular to the column space  $C(A)$  by the 2nd fundamental theorem of linear algebra.

If  $A^T b = 0$  the projection of  $b$  onto  $C(A)$  will be ~~itself~~,  $0$ . From the expression for the projection matrix we can see that this is so

$$Pb = A(A^T A)^{-1} A^T b = A(A^T A)^{-1} 0 = 0$$

(25) The projection  $Pb$  will the subspace  $S$  so  $S$  is the basis of  $P$ ?

(26)  $A^2 = A \quad + \quad \text{rank}(A) = m \quad \text{then} \quad A = I$

~~Assume~~  $A^2 = A$

$$I \Rightarrow A(A - I) = 0$$

But since rank of  $A$  is  $m$ ,  $A$  is invertible  $\therefore$  multiply by  $A^{-1}$  gives

$$A - I = 0 \quad \text{so} \quad A = I$$

(27)  $Ax$  is in the null space of  $A^T$ .  $Ax$  is always in the column space of  $A$ . To be in both spaces (which are perpendicular) we must have  $Ax = 0$ .

(28)  ~~$P^T = P + P^2 = P$~~

let  $x = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

Then  $Px =$  the 2nd column of  $P$ .

Then its length squared is given by  $(Px)^T (Px)$

$$= x^T P^T P x = x^T P^2 x = x^T Px = p_{22} \text{ element (2,2)}$$

in  $P$ .

Pg 192 Strang

$$\textcircled{1} \quad b = C + D t$$

The 4 equations are given by

$$0 = C + D \cdot 0$$

$$8 = C + D \cdot 1 \quad \cancel{\Rightarrow}$$

$$8 = C + D \cdot 3$$

$$20 = C + D \cdot 4$$

If the measurements are changed to what is given then

$$1 = C + D \cdot 0$$

$$5 = C + D \cdot 1 \Rightarrow C = 1 + D = 4$$

$$13 = C + D \cdot 3$$

$$17 = C + D \cdot 4$$

\textcircled{2} For the 5+ + given our matrix A is given by

$$A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 3 \\ 1 & 4 \end{bmatrix} \quad + \quad b = \begin{bmatrix} 0 \\ 3 \\ 8 \\ 20 \end{bmatrix}$$

so the norm eqs are given by

$$A^T A \hat{x} = A^T b$$

$$\Rightarrow \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 3 & 4 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 1 \\ 3 \\ 4 \end{bmatrix} \hat{x} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 3 & 4 \end{bmatrix} \begin{bmatrix} 0 \\ 3 \\ 8 \\ 20 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 4 & 1+3+4 \\ 1+3+4 & 1+9+16 \end{bmatrix} \begin{bmatrix} c \\ 0 \end{bmatrix} = \begin{bmatrix} 36 \\ \underbrace{8+24+80}_{\substack{8+104 \\ 112}} \end{bmatrix} = \begin{bmatrix} 36 \\ 112 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 4 & 8 \\ 8 & 26 \end{bmatrix} \begin{bmatrix} c \\ 0 \end{bmatrix} = \begin{bmatrix} 36 \\ 112 \end{bmatrix} \quad \cancel{\times 4} \quad 104 - 64 = 40$$

$$\Rightarrow \begin{bmatrix} c \\ 0 \end{bmatrix} = \begin{bmatrix} x \\ \frac{x}{2} \end{bmatrix}$$

$$\begin{bmatrix} c \\ 0 \end{bmatrix} = \frac{1}{104-64} \begin{bmatrix} 26 & -8 \\ -8 & 4 \end{bmatrix} \begin{bmatrix} 36 \\ 112 \end{bmatrix} = \frac{1}{40} \begin{bmatrix} 26 \cdot 36 - 8 \cdot 112 \\ -8 \cdot 36 + 4 \cdot 112 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

Then  $e = b - Ax = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 20 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 3 \\ 1 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 4 \end{bmatrix} = \begin{bmatrix} 0-1 \\ 0-1-4 \\ 0-1-12 \\ 20-1-16 \end{bmatrix}$

$$= \begin{bmatrix} -1 \\ 3 \\ -5 \\ 3 \end{bmatrix}$$

The 4 heights or given by  $A\tilde{x} = \begin{bmatrix} +1 \\ +5 \\ 13 \\ 17 \end{bmatrix}$

the error is given by

The smallest possible value of  $E = 1 + 9 + 2\tau + 9 =$

$$10 + 2\tau + 9 = 19 + 2\tau \\ = 44$$

(3) From previous problem 2  $P = \begin{bmatrix} 1 \\ 5 \\ 13 \\ 17 \end{bmatrix}$  so

that  $e = b - p$  is given by  $e = \begin{bmatrix} -1 \\ 3 \\ -8 \\ 3 \end{bmatrix}$

consider  $e^T A = [-1 \ 3 \ -5 \ 3] \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 3 \\ 1 & 4 \end{bmatrix}$   
 $= [-1+3-5+3 \quad 3-15+12] = [0 \ 0]$

The shortest distance is  $\|e\|_2 = E = 44$ .

(4)  $E = \|Ax - b\|^2$   
 $= (c+d \cdot 0 - 0)^2 + (c+d \cdot 1 - 8)^2 + (c+d \cdot 3 - 8)^2$   
 $+ (c+d \cdot 4 - 20)^2$

so that  $\frac{\partial E}{\partial c} = 2(c+d \cdot 0) + 2(c+d \cdot 1 - 8) +$   
 $2(c+d \cdot 3 - 8) + 2(c+d \cdot 4 - 20)$

+  $\frac{\partial E}{\partial d} = 2(c+d \cdot 0) \cdot 0 + 2(c+d \cdot 1 - 8) \cdot 1$   
 $+ 2(c+d \cdot 3 - 8) \cdot 3 + 2(c+d \cdot 4 - 20) \cdot 4$

Then  $\therefore$  by 2 we have the ~~about eqs for~~  $C + D$  follows

~~given by~~

$$(C+D \cdot 0 - D) + (C+D \cdot 1 - B) + (C+D \cdot 3 - B) + (C+D \cdot 4 - 2D) = 0$$

$$+ \quad \cancel{(C+D \cdot 0 - D)} +$$

$$\cancel{(C+D \cdot 0)} = 0$$

$$(C+D \cdot 0) + (C+D \cdot 1) + (C+D \cdot 3) + (C+D \cdot 4) = 0 + B + B + 2D$$

$$+ (C+D \cdot 0) \cdot 0 + (C+D \cdot 1) \cdot 1 + (C+D \cdot 3) \cdot 3 + (C+D \cdot 4) \cdot 4 =$$

$$0 \cdot 0 + B \cdot 1 + B \cdot 3$$

$$+ 2D \cdot 4$$

$$B + 24 + 8D$$

$$= 104 + 8 = 112$$

or in system form

$$\begin{array}{c} \text{[ } C+D \text{ ]} \\ \text{[ } 1+1+1+1 \text{ ]} \\ \text{[ } 0 \text{ ]} \\ \text{[ } 24 \text{ ]} \end{array} \quad \text{=} \quad \left[ \begin{array}{c|cc} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & 0 & 0 \\ \hline 0 & 0 & 24 \end{array} \right]$$

Grouping by  $C + D$  the following:

$$4 \cdot (C + B \cdot D) = 36$$

$\Updownarrow$

$$(1+3+4)(C + (1+9+16)D) = 112$$

$$\begin{bmatrix} 4 & 8 \\ 8 & 24 \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 36 \\ 112 \end{bmatrix}$$

⑤ Best horizontal line is given by  $y = c$ . By least squares  
the coefficient vector  $A$  is given by

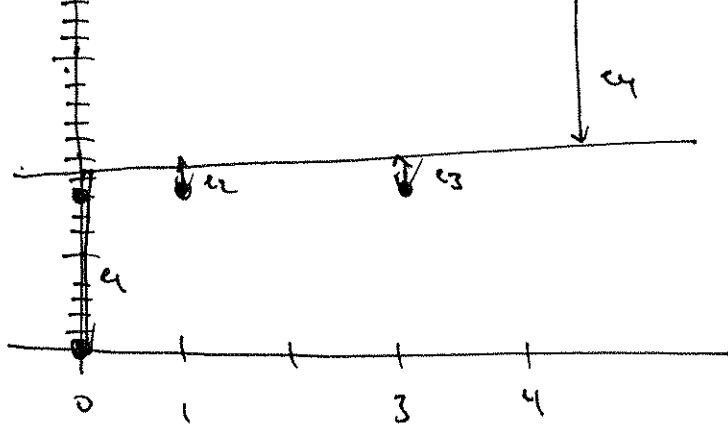
$$\hat{A}^T = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \quad c = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 20 \end{bmatrix}$$

which has Normal eqs. given by

$$\hat{A}^T \hat{A} x = \hat{A}^T b$$

$$\Rightarrow 4c = 16 + 20 = 36 \Rightarrow c = 9$$

Figure 4.9 would now look like



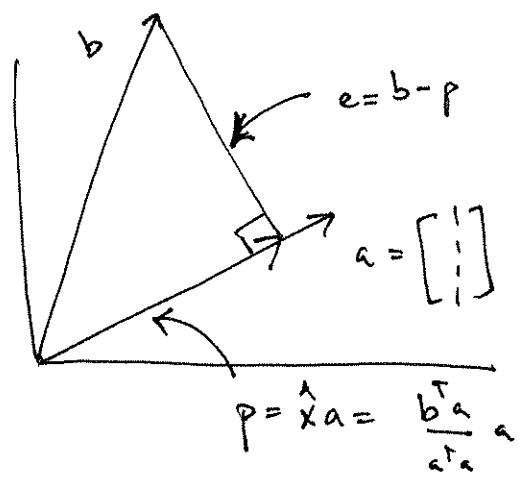
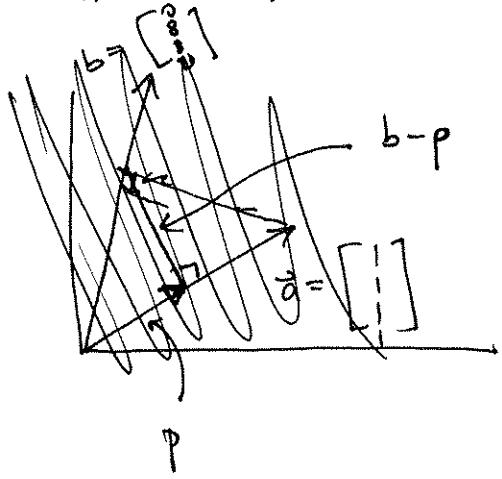
$$e = b - \hat{A}^T \hat{x} = \begin{bmatrix} 0 \\ 8 \\ 8 \\ 20 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}_9 = \begin{bmatrix} -9 \\ -1 \\ -1 \\ 11 \end{bmatrix}$$

$$\textcircled{6} \quad \hat{x} = \frac{\hat{a}^T b}{\hat{a}^T a} = \frac{(8+8+20)}{4} = 2+2+5 = 9$$

Then  $p = \hat{x}a = \begin{bmatrix} 9 \\ 9 \\ 9 \\ 9 \end{bmatrix}$  +  $e = b - p = \begin{bmatrix} 0-9 \\ 0-9 \\ 0-9 \\ 0-9 \end{bmatrix} = \begin{bmatrix} -9 \\ -9 \\ -9 \\ -9 \end{bmatrix}$

$$e^T a = [ -9 \ -1 \ -1 \ +11 ] \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = 0 \quad \text{yes}$$

$$\text{Then } \|e\|_1 = \|b-p\|_1 = \sqrt{81+1+1+121} = \sqrt{2+202} = \sqrt{204}$$



$$\textcircled{7} \quad b = Dt$$

In this case our linear system is given by

$$A\hat{x} = b \quad \text{where } A = \begin{bmatrix} 0 & 1 & 3 \\ 1 & 0 & 4 \end{bmatrix}, \quad b = \begin{bmatrix} 0 \\ 0 \\ 8 \\ 20 \end{bmatrix}$$

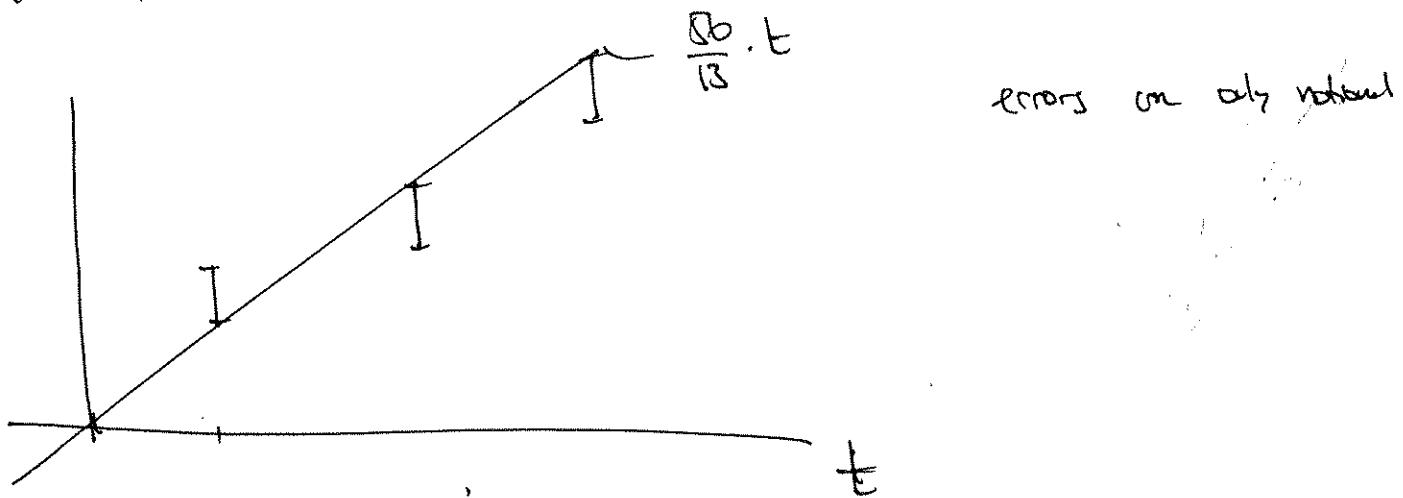
$$\hat{x} = [D]$$

$$\text{Then } A^T A = \begin{bmatrix} 1+9+16 \end{bmatrix} = \begin{bmatrix} 26 \end{bmatrix}$$

$$+ A^T b = \begin{bmatrix} 0+8+24+80 \end{bmatrix} = \begin{bmatrix} 8+104 \end{bmatrix} = \begin{bmatrix} 112 \end{bmatrix}$$

$$\therefore \hat{x} = \frac{112}{26} = \frac{56}{13}$$

Then Fig 1.9a looks like



$$(8) \quad \hat{x} = \frac{a^T b}{a^T a} = \frac{0+8+24+80}{1+9+16} = \frac{104+8}{26} = \frac{112}{26} = \frac{56}{13}$$

$$\text{So } P = \frac{56}{13} \begin{bmatrix} 0 \\ 1 \\ 3 \\ 4 \end{bmatrix} = \cancel{\frac{56}{13}}$$

In problems 1-4 the best  $(c, d) = (1, 4)$

while in problems 5-6 for  $c +$

7-8 for  $d$  we have  $(c, d) = (9, \frac{56}{13})$

Because  $(1, 1, 1, 1) \perp (0, 1, 3, 4)$  or Not perpendicular

⑨ Or matrix then it is the case is

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 3 & 9 \\ 1 & 4 & 16 \end{bmatrix} + b = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 20 \end{bmatrix}$$

The Normal equations are given by

$$A^T A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 3 & 4 \\ 0 & 1 & 9 & 16 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 3 & 9 \\ 1 & 4 & 16 \end{bmatrix} = \begin{bmatrix} 4 & 1+3+4 & 1+9+16 \\ 1+3+4 & 1+9+16 & 1+27+64 \\ 1+9+16 & 1+27+64 & 1+81+256 \end{bmatrix}$$

$$\begin{bmatrix} 16+24+40+20=64 \\ 16 \cdot 4=0 \\ 16 \cdot 16=256 \\ 16 \cdot 9=144 \\ 16 \cdot 1=16 \end{bmatrix} \quad \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 3 \\ 0 & 1 & 9 \end{bmatrix} \quad \begin{bmatrix} 0 \\ 8 \\ 3 \\ 20 \end{bmatrix} = \begin{bmatrix} 4 & 8 & 26 \\ 8 & 26 & 92 \\ 26 & 92 & 338 \end{bmatrix}$$

$$+ A^T b = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 3 \\ 0 & 1 & 9 \end{bmatrix} \begin{bmatrix} 0 \\ 8 \\ 3 \\ 20 \end{bmatrix} = \begin{bmatrix} 16+20 \\ 8+24+80 \\ 8+72+320 \end{bmatrix} = \begin{bmatrix} 36 \\ 112 \\ 420 \end{bmatrix}$$

~~$\begin{bmatrix} 16 \\ 8 \\ 8 \\ 20 \end{bmatrix}$~~

In Fig 4.9 b we are fitting or estimating the plane computing the best fit to the span of 3 vectors which best is measured in the least squares sense

⑩  $A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 3 & 9 & 27 \\ 1 & 4 & 16 & 64 \end{bmatrix}$

Since  $Ax=b$  has a solution if

$$\begin{array}{c} A \\ \times \\ \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 8 \\ 1 & 3 & 9 & 27 & 8 \\ 1 & 4 & 16 & 64 & 20 \end{bmatrix} \\ \hline b \\ \begin{bmatrix} 24 \\ -144 + 60 \\ 84 \end{bmatrix} \end{array}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 8 \\ 0 & 3 & 9 & 27 & 8 \\ 0 & 4 & 16 & 64 & 20 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 8 \\ 0 & 0 & 6 & 24 & -16 \\ 0 & 0 & 12 & 60 & -12 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 8 \\ 0 & 0 & 6 & 24 & -16 \\ 0 & 0 & 0 & -84 & \dots \end{bmatrix}$$

Now  $\hat{x} = \begin{bmatrix} 0 \\ 47 \\ -28 \\ 5 \end{bmatrix}$

Then  $p = b + e = 0$

⑪ (a) The best line is  $l+4t$

$$\text{so } l+4\hat{t} = l+4(2) = 9 = \hat{b}$$

(b) The 1st Normal equation is given by eq 9 in the text

$$t \text{ is } m \cdot C + \sum t_i \cdot D = \sum b_i.$$

Multiplying by  $m$  gives the required expression

Pg 193 strong

(12)

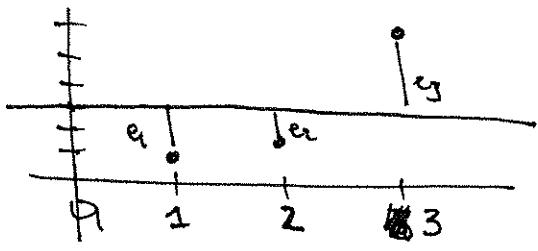
(a)  $a^T a \hat{x} = a^T b$  is given by

$$m\hat{x} = \sum_i b_i \quad \text{so} \quad \hat{x} = \frac{1}{m} \sum_i b_i \quad \text{or the mean of the } b_i's$$

$$(b) e = b - \hat{x} \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} = \begin{bmatrix} b_1 - \hat{x} \\ b_2 - \hat{x} \\ \vdots \\ b_m - \hat{x} \end{bmatrix}$$

$$\text{Then } \|e\|^2 = \sum_{i=1}^m (b_i - \hat{x})^2 \quad \text{so} \quad \|e\| = \sqrt{\sum_{i=1}^m (b_i - \hat{x})^2}$$

$$(c) \text{ If } b = [1, 2, 6]^T \text{ then } \hat{x} = \frac{1}{3}(1+2+6) = 3$$



$$P = 3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$e = \begin{bmatrix} 1 \\ 2 \\ 6 \end{bmatrix} - \begin{bmatrix} 3 \\ 3 \\ 3 \end{bmatrix} = \begin{bmatrix} -2 \\ -1 \\ 3 \end{bmatrix}$$

$$\text{Check } P^T e = 3(-2 - 1 + 3) = 0 \quad \checkmark$$

$$P = \frac{aa^T}{a^T a} = \frac{\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}}{3} = \frac{\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}}{3}$$

$$= \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

(13)

I interpret the question as follows. For each iteration  
the residual will be one of the values listed  $(\pm 1, \pm 1, \pm 1)$

considering  $b - Ax = (\pm 1, \pm 1, \pm 1)$

we have multiplying by  $(A^T A)^{-1} A^T$ , we have the following

$$(A^T A)^{-1} A^T (b - Ax) = (A^T A)^{-1} A^T b - (A^T A)^{-1} A^T Ax$$

$$= \hat{x} - x$$

If ~~this~~ <sup>the</sup> residual can equal any of the following vectors

$$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix}$$

so ~~multiplying each of these~~ we note that the ~~closure~~ of all these

vectors is equal to  ~~$\begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$~~   $\begin{bmatrix} 4 & 4 & 4 \\ 4 & 4 & 4 \\ 4 & 4 & 4 \end{bmatrix} = 0$

In the same way the action of  $(A^T A)^{-1} A^T$  on each of these  
vectors would produce

$$\frac{1}{3} * 3, -3, 3, 1, 1, 1, -1, -1, -1$$

which when summed gives 700.

(14) Consider  $\underline{(b - Ax)(b - Ax)^T}$ , then + multiply by  
 $(A^T A)^{-1} A^T$  on the left +  $A(A^T A)^{-1}$  on the right, to obtain

$$(A^T A)^{-1} A^T (b - Ax) (b - Ax)^T A (A^T A)^{-1}$$

Also sin  $B^T C = (C^T B)^T$  the above becomes

$$\begin{aligned} & (\hat{x} - x) \left[ [A(A^T A)^{-1}]^T (b - Ax) \right]^T \\ &= (\hat{x} - x) (A^T A)^{-1} A^T (b - Ax) \end{aligned}$$

$$= (\hat{x} - x) (\hat{x} - x)^T$$

so that if the average of  $(b - Ax)(b - Ax)^T$  is  $\sigma^2 I$  we have  
 that the average of  $(\hat{x} - x)(\hat{x} - x)^T$  is  $(A^T A)^{-1} A^T (\sigma^2 I) A (A^T A)^{-1}$   
 to obtain  $\sigma^2 (A^T A)^{-1} A^T A (A^T A)^{-1} = \sigma^2 (A^T A)^{-1}$ .

(15) Expected error  $(\hat{x} - x)^2$  as  $B^2(A^T A)^{-1} = \frac{B^2}{m}$ .

So the variance drops significantly  $\propto \frac{1}{m}$

$$(16) \quad \frac{1}{100} b_{100} + \frac{99}{100} \hat{x}_{99} = \frac{1}{100} (\sum_i b_i)$$

$$(17) \quad \gamma = C + D(-1)$$

$$\gamma = C + D(1)$$

$$21 = C + D(2)$$

$$\Leftrightarrow \begin{bmatrix} 1 & -1 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 7 \\ 7 \\ 21 \end{bmatrix} \quad \xrightarrow{\text{L.S. sol}} \begin{bmatrix} 1 & 1 & 1 \\ -1 & 1 & 2 \\ 1 & 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ -1 & 1 & 2 \\ 1 & 1 & 2 \end{bmatrix} \begin{bmatrix} 7 \\ 7 \\ 21 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 3 & 2 \\ 2 & 6 \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 14+21 \\ 42 \end{bmatrix} = \begin{bmatrix} 35 \\ 42 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} C \\ D \end{bmatrix} = \frac{1}{18-4} \begin{bmatrix} 6 & -2 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} 35 \\ 42 \end{bmatrix} = \frac{1}{14} \begin{bmatrix} 6 & -2 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} 35 \\ 42 \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} 6 & -2 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} 5 \\ 6 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 30-12 \\ -10+18 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 18 \\ 8 \end{bmatrix}$$

$$= \begin{bmatrix} 9 \\ 4 \end{bmatrix}$$

Then the line is  $b = 9 + 4t$

$$(18) \quad P = A\hat{x} = \begin{bmatrix} 1 & -1 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 9 \\ 4 \end{bmatrix} = \begin{bmatrix} 9 - 4 \\ 9 + 4 \\ 9 + 8 \end{bmatrix} = \begin{bmatrix} 5 \\ 13 \\ 17 \end{bmatrix}$$

Gives the values on the closest line. The error vector  $e$  is

then given by  $e = b - p = \begin{bmatrix} 7 \\ 7 \\ 21 \end{bmatrix} - \begin{bmatrix} 5 \\ 13 \\ 17 \end{bmatrix} = \begin{bmatrix} 2 \\ -6 \\ 4 \end{bmatrix}$

$$(19) \quad \text{or matrix } A \text{ is still given by } A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \\ 1 & 2 \end{bmatrix}$$

Let now  $b = \begin{bmatrix} 2 \\ -6 \\ 4 \end{bmatrix}$  so that

$\hat{x} = (A^T A)^{-1} A^T b = 0$ . Each column of  $A$  is perpendicular to the error in the least squares solution and as such has  $A^T L = 0$ . Thus the projection is zero.

$$(20) \quad \text{when } b = \begin{bmatrix} 5 \\ 13 \\ 17 \end{bmatrix} \text{ we have}$$

$$\hat{x} = (A^T A)^{-1} A^T b = (A^T A)^{-1} \begin{bmatrix} 1 & 1 & 1 \\ -1 & 1 & 2 \end{bmatrix} \begin{bmatrix} 5 \\ 13 \\ 17 \end{bmatrix} = \begin{bmatrix} 35 \\ 42 \end{bmatrix}$$

$$= (A^T A)^{-1} \begin{bmatrix} 35 \\ 42 \end{bmatrix}$$

$$\Rightarrow \hat{x} = \frac{1}{4} \begin{bmatrix} 6 & -2 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} 35 \\ 42 \end{bmatrix} = \begin{bmatrix} 9 \\ 4 \end{bmatrix}$$

Then the closest line is given by  ~~$\hat{x}$~~   ~~$b$~~   $b = 9 + 4t$

$$+ e = b - A\hat{x} = \begin{bmatrix} 5 \\ 13 \\ 17 \end{bmatrix} - \begin{bmatrix} 5 \\ 13 \\ 17 \end{bmatrix} = 0$$

$e = 0$  because this  $b$  is in the column space of  $A$

(21) The error  $e$  must be perpendicular to the column space of  $A$  &  $\therefore$  is in the left nullspace of  $A$ .

$P$  must be in the column space of  $A$

$\hat{x}$  is in the row space of  $A$

The nullspace of  $A$  is the zero vector assuming that the columns of  $A$  are linearly independent. This is not generally true if  $m > n$ .

(22) ~~Step~~  $A = \begin{bmatrix} 1 & -2 \\ 1 & -1 \\ 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix}$  Form  $A^T A \hat{x} = A^T b$  +  
Solve for  $\hat{x}$ .

Not clear how  $\sum t_i = 0$  so

$$\dots \cancel{\text{cancel}} \cancel{\text{cancel}} \dots c = \frac{1}{m} \sum b_i = \frac{1}{5} 5 = 1$$

$$+ D = \frac{b_1 T_1 + \dots + b_m T_m}{T_1^2 + \dots + T_m^2} =$$

$$D = \frac{4 \cdot (-2) + 2(-1) + -1(0) + 0(1) + 0(2)}{4+1+0+1+4} = \dots$$

Then the least square line is  $\hat{y} = Dx + D$ .

(23)  $P = (x_1, x_2)$  +  $Q = (y, 3y, -1)$

$$\text{Then } \|P-Q\|^2 = (x-y)^2 + (x-3y)^2 + (x+1)^2$$

=

$$\text{To min this set } \frac{\partial \|P-Q\|^2}{\partial x} = 0$$

$$+ \frac{\partial \|P-Q\|^2}{\partial y} = 0 \quad \text{+ solve for } x \text{ + } y.$$

(24)  $e$  is orthogonal to  ~~$b$~~  any tug in the column space of  $A$   
so that would be  $p = Ax$ .

$$\|e\|^2 = (b-p)^T(b-p) = e^T(b-p) = e^T b - (b-p)^T b \\ = b^T b - b^T p.$$

(25) Since  $\|Ax-b\|^2 = \cancel{\|Ax\|^2 + 2b^T Ax + \|b\|^2}$

$$(Ax-b)^T(Ax-b) = (Ax)^T(Ax) - \cancel{(Ax)^T b + -b^T Ax} \\ + b^T b \\ = \|Ax\|^2 - 2b^T Ax + \|b\|^2$$

so the derivative of  $\|Ax-b\|^2$  are zero when

$$2A^T A x - 2A^T b = 0 \quad \text{or}$$

$$A^T A x = A^T b \quad (\text{the normal equations})$$

pg 203 Study

①

(a) check the dot product  $\begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$

$$\begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \end{bmatrix} = -1 \neq 0$$

+ the second vector does not have norm = 1, so these vectors are only independent

(b) check the dot product

$$\begin{bmatrix} -6 & .8 \end{bmatrix} \begin{bmatrix} .4 \\ -.3 \end{bmatrix} = .24 - .24 = 0$$

so they are orthogonal. The norm of each is given by

$$\|v_1\| = \sqrt{.36 + .64} = 1$$

$$+ \|v_2\| = \sqrt{.16 + .09} = \sqrt{.25} = .5$$

so they are not orthonormal, An orthonormal second vector would be given by

$$v_2/.5 = 2v_2$$

$$(c) v_1^T v_2 = -\cos\theta \sin\theta + \sin\theta \cos\theta = 0$$

$$= \begin{bmatrix} .8 \\ -.6 \end{bmatrix}$$

+  $\|v_1\| = \|v_2\| = 1$  so these two vectors are orthonormal.

$$② q_1 = \frac{1}{3} \begin{bmatrix} 2 \\ 2 \\ -1 \end{bmatrix}$$

$$\cancel{\text{Q}} = \cancel{\begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}}$$

$$\perp q_2 = \frac{1}{3} \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix}$$

$$Q = \begin{bmatrix} \frac{2}{3} & \frac{-1}{3} \\ \frac{2}{3} & \frac{2}{3} \\ \frac{-1}{3} & \frac{2}{3} \end{bmatrix}$$

$$\text{then } Q^T Q = \frac{1}{9} \begin{bmatrix} 2 & 2 & -1 \\ -1 & 2 & 2 \\ 2 & -1 & 2 \end{bmatrix} \begin{bmatrix} 2 & -1 & 1 \\ 2 & 2 & 2 \\ -1 & 2 & 2 \end{bmatrix}$$

$$= \frac{1}{9} \begin{bmatrix} 9 & -2+4-2 & -2+4-2 \\ -2+4-2 & 1+4+4 & 1+4+4 \end{bmatrix} = \frac{1}{9} \begin{bmatrix} 9 & 0 & 0 \\ 0 & 9 & 9 \end{bmatrix}$$

$$+ \quad QQ^T = \frac{1}{9} \begin{bmatrix} 2 & -1 \\ 2 & 2 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 2 & 2 & -1 \\ -1 & 2 & 2 \end{bmatrix}$$

$$= \frac{1}{9} \begin{bmatrix} 5 & 2 & -4 \\ 2 & 8 & 2 \\ -4 & 2 & 5 \end{bmatrix}$$

③ (a)  $A^T A$  would be the  $3 \times 3$  identity matrix times  $4^2 = 16$   
 $3 \times 4 \quad 4 \times 3$

$$(b) A^T A \text{ would be } \begin{bmatrix} 1^2 & 0 & 0 \\ 0 & 2^2 & 0 \\ 0 & 0 & 3^2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 9 \end{bmatrix}$$

④ (a) let  $Q = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$

then  $QQ^T = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

(b) let  $v_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + v_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

(c) let the basis basis be consist of

$$\begin{bmatrix} \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & -\frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \end{bmatrix}$$

⑤ All vectors that lie in the plane must ~~be in~~ be in the nullspace of  $A = \begin{bmatrix} 1 & 1 & 2 \end{bmatrix}$

which has a basis given by  $\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} \equiv v_1, v_2$

These vectors are not orthogonal as is

let  $w_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$  & let  $\cancel{w_2 = \cancel{v_1} v_2} = \overline{w_2} = \overline{\cancel{v_2}}^T$

$$W_2 = V_2 - \frac{(V_2^T w_1)}{\|w_1\|^2} w_1$$

$$= \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} - \frac{1}{\sqrt{2}} (2) \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} -2 + \sqrt{2} \\ -\sqrt{2} \\ 1 \end{bmatrix}$$

Since  $V_2^T w_1 = \frac{1}{\sqrt{2}} (2) = \sqrt{2}$

+  $\|w_1\|^2 = 1$

$$\text{so } \frac{(V_2^T w_1)}{\|w_1\|^2} w_1 = \sqrt{2} \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$\text{so } W_2 = \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ -1 \end{bmatrix}$$

+ ∵  $w_2 = \frac{1}{\|w_2\|} \begin{bmatrix} -1 \\ 0 \\ -1 \end{bmatrix} = \frac{1}{\sqrt{3}} \begin{bmatrix} -1 \\ 0 \\ -1 \end{bmatrix}$

pg 203 Strang

- ⑥ Consider  $(Q_1, Q_2)^T (Q_1, Q_2)$  which is equal to

$$Q_2^T Q_1^T Q_1 Q_2 = Q_2^T Q_2 = I$$

so  $Q_1, Q_2$  is orthogonal

- ⑦ The projection matrix is given by  $P = Q(Q^T Q)^{-1} Q^T$   
 $= Q I^{-1} Q^T$   
 $= QQ^T$

so the projection of  $b$  will be

$$P = Pb = Q Q^T b = Q \begin{bmatrix} q_1^T b \\ q_2^T b \\ \vdots \\ q_m^T b \end{bmatrix} = (q_1^T b) q_1 + (q_2^T b) q_2 + \dots + (q_m^T b) q_m$$

- ⑧ (a)  ~~$Q =$~~   $\begin{bmatrix} .8 & -.6 \\ -.6 & .8 \\ 0 & 0 \end{bmatrix}$  ~~.64 + .36~~

~~$Q =$~~   $QQ^T = \begin{bmatrix} .8 & -.6 \\ -.6 & .8 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} .8 & .6 & 0 \\ -.6 & .8 & 0 \end{bmatrix}$   
 $= \begin{bmatrix} .64 + .36 & 0 & 0 \\ .42 - .42 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

Then  $P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

$$\text{so } P^2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = P$$

(b)  $(QQ^T)(Q^T Q^T) = QQ^T Q Q^T = QQ^T$

Then  $P = QQ^T = (QQ^T)(Q^T Q^T)$  so that  $P = \overset{QQ^T}{P}$  is the projection matrix onto the columns of  $Q$ .

① (a)  $c_1 q_1 + c_2 q_2 + c_3 q_3 = 0$  taking the dot product with  $q_1$  gives  $c_1 q_1^T q_1 = 0 \Rightarrow c_1 = 0$ , sim for  $q_2 + q_3$ .

Thus the  $q$ 's are linearly independent.

(b) Acting  $Q = [q_1 q_2 q_3]$  then  $Qx = 0$

Multiplying by  $Q^T$  on both sides gives

$$Q^T Q x = 0$$

But  $Q^T Q = I$  by orthogonality so  $x = 0$

(10) To be in both planes we are looking for variables that  
 $\begin{bmatrix} x \\ y \end{bmatrix}$

$$A = \begin{bmatrix} 1 & -6 \\ 3 & 6 \\ 4 & 0 \\ 5 & 0 \\ 7 & 0 \end{bmatrix}$$

$$\text{let } V_1 = \begin{bmatrix} 1 \\ 3 \\ 4 \\ 5 \\ 7 \end{bmatrix} \text{ so that } V_1 = \frac{1}{\sqrt{1+9+16+25+49}} \begin{bmatrix} 1 \\ 3 \\ 4 \\ 5 \\ 7 \end{bmatrix}$$

$$= \frac{1}{10} \begin{bmatrix} 1 \\ 3 \\ 4 \\ 5 \\ 7 \end{bmatrix}$$

$$\text{Then } V_2 = \begin{bmatrix} -6 \\ 6 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 1 & 3 & 4 & 5 & 7 \end{bmatrix} \begin{bmatrix} -6 \\ 6 \\ 0 \\ 0 \\ 0 \end{bmatrix} \left( \frac{1}{10^2} \right) \begin{bmatrix} 1 \\ 3 \\ 4 \\ 5 \\ 7 \end{bmatrix}$$

$$= \begin{bmatrix} -6 \\ 6 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \frac{(-6+18+32+56)}{10^2} \begin{bmatrix} 1 \\ 3 \\ 4 \\ 5 \\ 7 \end{bmatrix}$$

$$\frac{88}{100} = \frac{18}{100} = \frac{9}{100}$$

$$= \begin{bmatrix} -6 \\ 6 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \cancel{\frac{9}{10}} \begin{bmatrix} 1 \\ 3 \\ 4 \\ 5 \\ 7 \end{bmatrix} = \begin{bmatrix} -16 \\ -24 \\ -32 \\ -50 \\ -62 \end{bmatrix} \neq \cancel{\frac{9}{10}} \begin{bmatrix} 8 \\ 12 \\ 16 \\ 20 \\ 28 \end{bmatrix}$$

B-20

$$= \begin{bmatrix} -7 \\ 3 \\ 4 \\ -5 \\ 1 \end{bmatrix} \quad \text{Normalizing we have}$$

$$v_2 = \frac{1}{\sqrt{49+9+16+25+1}} \begin{bmatrix} -7 \\ 3 \\ 4 \\ -5 \\ 1 \end{bmatrix} = \frac{1}{10} \begin{bmatrix} -7 \\ 3 \\ 4 \\ -5 \\ 1 \end{bmatrix}$$

(b) The vector closest to  $(1, 0, 0, 0, 0)$  is given by

$$P = q_1(q_1^T b) + q_2(q_2^T b)$$

$$= \frac{1}{10} \begin{bmatrix} 1 \\ 3 \\ 4 \\ -5 \\ 1 \end{bmatrix} \frac{1}{10} + \frac{1}{10} \begin{bmatrix} -7 \\ 3 \\ 4 \\ -5 \\ 1 \end{bmatrix} \frac{-7}{10}$$

$$= \frac{1}{100} \left( \begin{bmatrix} 1 \\ 3 \\ 4 \\ -5 \\ 1 \end{bmatrix} - \begin{bmatrix} -7 \\ 3 \\ 4 \\ -5 \\ 1 \end{bmatrix} \right) = \frac{1}{100} \begin{bmatrix} 1+49 \\ 3-21 \\ 4-28 \\ -5+35 \\ 1-7 \end{bmatrix} = \frac{1}{100} \begin{bmatrix} 50 \\ -18 \\ -24 \\ 30 \\ 0 \end{bmatrix}$$

$$= \frac{1}{100} \begin{bmatrix} 25 \\ -9 \\ -12 \\ 20 \\ 0 \end{bmatrix} +$$

$$\textcircled{11} \quad (q_1^T b) q_1 + (q_2^T b) q_2$$

\textcircled{12} (a) If  $a_i$ 's are orthogonal

$$Ax = b$$

$$\Rightarrow \begin{bmatrix} a_1 & a_2 & a_3 \end{bmatrix} x = b \quad \text{Multiplying by } A^T \text{ (which is the inverse of } A\text{)}$$

$$A^T A x = A^T b$$

$$x = \begin{bmatrix} a_1^T b \\ a_2^T b \\ a_3^T b \end{bmatrix}$$

(b) If  $a_i$ 's are ~~orthogonal~~ orthogonal then

$$A^T A = \begin{bmatrix} a_1^T \\ a_2^T \\ a_3^T \end{bmatrix} \begin{bmatrix} a_1 & a_2 & a_3 \end{bmatrix} = \begin{bmatrix} a_1^T a_1 & a_1^T a_2 & a_1^T a_3 \\ a_2^T a_1 & a_2^T a_2 & a_2^T a_3 \\ a_3^T a_1 & a_3^T a_2 & a_3^T a_3 \end{bmatrix}$$

$$= \begin{bmatrix} a_1^T a_1 & 0 & 0 \\ 0 & a_2^T a_2 & 0 \\ 0 & 0 & a_3^T a_3 \end{bmatrix}$$

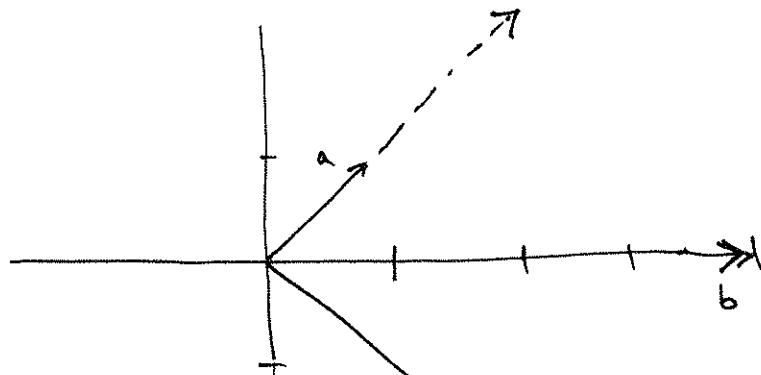
So

$$A^T A x = A^T b = \begin{bmatrix} a_1^T b \\ a_2^T b \\ a_3^T b \end{bmatrix}$$

$$\Rightarrow x = \begin{bmatrix} \frac{a_1^T b}{a_1^T a_1} \\ \frac{a_2^T b}{a_2^T a_2} \\ \frac{a_3^T b}{a_3^T a_3} \end{bmatrix}$$

(C) or independent  $x_1$  is the 1st row of  $A^T$  times  $b$ 

(B)



$$A = a$$

$$B = b - \frac{a^T b}{a^T a} a = \begin{bmatrix} 4 \\ 0 \end{bmatrix} - \left(\frac{4}{2}\right) \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 4 \\ 0 \end{bmatrix} - \begin{bmatrix} 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ -2 \end{bmatrix}$$

We need to subtract "2" times  $a$  to make the result orthogonal to  $a$ .

$$(14) \quad q_1 = \frac{a}{\|a\|} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$q_2 = \frac{B}{\|B\|} = \frac{1}{\sqrt{4+4}} \begin{bmatrix} 2 \\ -2 \end{bmatrix} = \frac{1}{2\sqrt{2}} \begin{bmatrix} 2 \\ -2 \end{bmatrix}$$

$$= \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\frac{1}{\sqrt{B}} = \frac{1}{2\sqrt{2}}$$

Then  $\begin{bmatrix} 1 & 4 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} \sqrt{2} & q_1^T b \\ 0 & 2\sqrt{2} \end{bmatrix}$

with  $q_1^T b = \frac{1}{\sqrt{2}} [1 \ 1] \begin{bmatrix} 4 \\ 0 \end{bmatrix} = \frac{1}{\sqrt{2}} 4 = \frac{4}{\sqrt{2}}$

$$\Rightarrow \begin{bmatrix} 1 & 4 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} \sqrt{2} & \frac{4}{\sqrt{2}} \\ 0 & 2\sqrt{2} \end{bmatrix}$$

We can check by multiplying the matrices ~~together~~ together

$$\begin{bmatrix} 1 & \frac{4}{2} + 2 \\ 1 & \frac{4}{2} - 2 \end{bmatrix} = \begin{bmatrix} 1 & 4 \\ 1 & 0 \end{bmatrix} \quad \text{yes.}$$

⑯ a) with  $A = \begin{bmatrix} 1 & 1 \\ 2 & -1 \\ -2 & 4 \end{bmatrix}$

let  $a = \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix}$  then  $q_1 = \frac{1}{3} \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix}$

let  $b = \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix}$

Then  $B = b - \frac{a^T b}{a^T a} a = \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix} - \frac{(1-2-8)}{(1+4+4)} \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix}$   
 $= \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix} + \frac{9}{9} \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix}$

Then  $q_2 = \frac{B}{\|B\|} = \frac{1}{\sqrt{4+1+4}} \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix}$

Then for  $q_3$  we pick a 3rd vector say  $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$  that is

linearly independent with the rest we then have

$$C = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} - \frac{C^T a}{a^T a} a - \frac{C^T b}{b^T b} b$$

$$= \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} - \frac{1}{9} \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix} - \frac{1}{18} \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix}$$

$$c = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} - \frac{1}{18} \begin{bmatrix} 2 \\ 4 \\ 4 \end{bmatrix} - \frac{1}{18} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} - \underbrace{\frac{1}{18} \begin{bmatrix} 3 \\ 3 \\ 0 \end{bmatrix}}_{\frac{1}{6} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}} + \frac{1}{6} \begin{bmatrix} 6-1 \\ -1 \\ 0 \end{bmatrix} = \frac{1}{6} \begin{bmatrix} 5 \\ -1 \\ 0 \end{bmatrix}$$

$$\text{Then } q_3 = \frac{1}{\sqrt{26}} \begin{bmatrix} 5 \\ -1 \\ 0 \end{bmatrix}$$

(b)  $q_3$  must be orthogonal to the columns of  $A$  in the left nullspace.

$$(c) P = [1 \ 2 \ 7]^T \begin{bmatrix} \frac{2}{3} \\ \frac{1}{3} \\ \frac{1}{3} \end{bmatrix} \begin{bmatrix} \frac{2}{3} \\ \frac{1}{3} \\ \frac{1}{3} \end{bmatrix} + [1 \ 2 \ 7]^T \begin{bmatrix} \frac{1}{3} \\ \frac{2}{3} \\ -\frac{2}{3} \end{bmatrix} \begin{bmatrix} \frac{1}{3} \\ \frac{2}{3} \\ -\frac{2}{3} \end{bmatrix}$$

$$= \frac{1}{9} (2+2+14) \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix} + \frac{1}{9} (1+4-14) \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix}$$

$$= \frac{1}{9} 2 \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix} + -1 \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix} = \begin{bmatrix} 4-1 \\ 2-2 \\ 4+2 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ 6 \end{bmatrix}$$

or solving the normal equations we have

$$\hat{A}^T A \hat{x} = A^T b$$

$$\text{L} A^T A = \begin{bmatrix} 1 & 2 & -2 \\ 1 & -1 & 4 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 2 & -1 \\ -2 & 4 \end{bmatrix} = \begin{bmatrix} 9 & 1-2-B \\ 1-2-B & 1+1+16 \end{bmatrix}$$

$$= \begin{bmatrix} 9 & -9 \\ -9 & 1B \end{bmatrix} = 9 \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix}$$

$$\text{L} A^T b = \begin{bmatrix} 1+4-14 \\ 1-2+20 \end{bmatrix} = \begin{bmatrix} 15 \\ 27 \end{bmatrix}$$

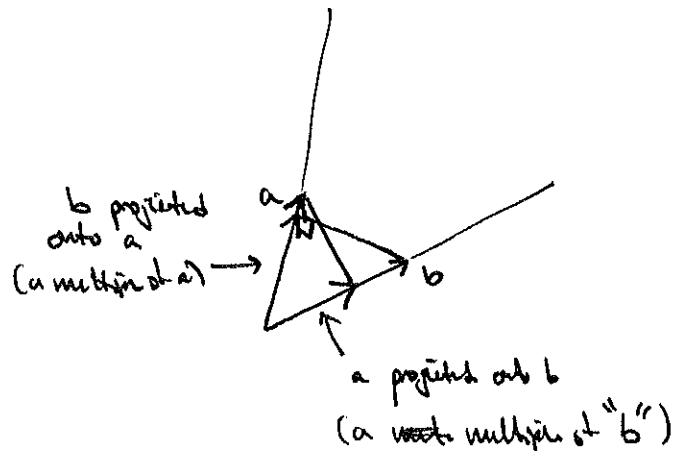
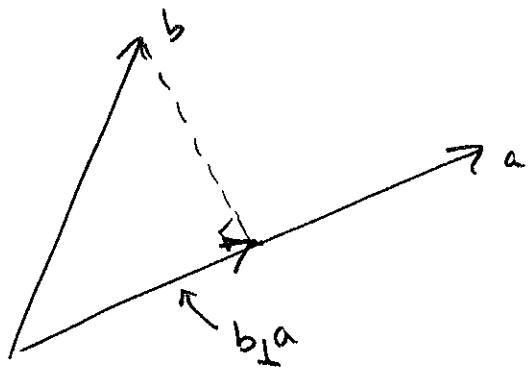
Then

~~$$\hat{x} = \frac{1}{9(2-1)} \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 15 \\ 27 \end{bmatrix}$$~~

$$= \frac{1}{3} \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 5 \\ 9 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 19 \\ 14 \end{bmatrix}$$

pg 204 Strong

- (16) Find the projection of  $b$  onto  $a$



$$x = \frac{b^T a}{a^T a} a = \frac{(4+10)}{16+25+4+4} = \frac{14}{49} = \frac{2}{7}$$

To find orthonormal vectors let

$$q_1 = \frac{1}{\sqrt{16+25+4+4}} \begin{bmatrix} 4 \\ 5 \\ 2 \\ 2 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} 4 \\ 5 \\ 2 \\ 2 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 \\ 2 \\ 0 \\ 0 \end{bmatrix} - \frac{b^T a}{a^T a} \begin{bmatrix} 4 \\ 5 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 0 \\ 0 \end{bmatrix} - \frac{14}{49} \begin{bmatrix} 4 \\ 5 \\ 2 \\ 2 \end{bmatrix}$$

$$= \frac{1}{49} \begin{bmatrix} 49 - 56 \\ 98 - 70 \\ -28 \\ -28 \end{bmatrix} = \frac{1}{49} \begin{bmatrix} -7 \\ 28 \\ -28 \\ -28 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} -1 \\ 4 \\ -4 \\ -4 \end{bmatrix}$$

$$\text{so } q_2 = \frac{1}{\sqrt{1+3(16)}} \begin{bmatrix} -1 \\ 4 \\ -4 \\ -4 \end{bmatrix} =$$

$$\left\{ \begin{array}{l} 8 \\ 16 \\ 25 \\ 4 \\ 49 \\ 40 \\ 16 \\ 4 \\ 5 \\ 28 \\ 16 \\ 49 \\ 7 \end{array} \right\}$$

$$\frac{16}{30} = \frac{2 \cdot 4}{3 \cdot 16} = \frac{4}{16}$$

$$= \frac{1}{4} \sqrt{3} \begin{bmatrix} 1 \\ -\frac{1}{4} \\ \frac{1}{4} \\ -\frac{1}{4} \end{bmatrix} \quad \dots \text{maybe error check me...}$$

(1)  $P = \frac{b^T a}{a^T a} a = \frac{(1+3+5)}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

$$e = b - p = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix} - \begin{bmatrix} 3 \\ 3 \\ 3 \end{bmatrix} = \begin{bmatrix} -2 \\ 0 \\ 2 \end{bmatrix}$$

$$q_1 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \quad + \quad q_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} -2 \\ 0 \\ 2 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

(2)  $A = QR$ , then  $A^T A = \cancel{R^T Q^T} (R^T Q^T)(QR)$   
 $= R^T R$   
 $= \text{lower triangular} * \text{upper triangular}$

$\therefore$  from Schmidt on  $A$  corresponds to elimination on  $A^T A$ .

If  $A$  is as given then  $A^T A = \begin{bmatrix} 3 & 9 \\ 9 & 35 \end{bmatrix}$

Then  $A^T A \Rightarrow \begin{bmatrix} 3 & 9 \\ 0 & 35-27 \end{bmatrix} = \begin{bmatrix} 3 & 9 \\ 0 & 8 \end{bmatrix}$

which has pivots equal to  $\|x\|^2$   $\|y\|^2$   $\|z\|^2$  respectively

(19) (a) True since the inverse of an orthogonal matrix is its transpose, ~~unless zero~~

(b) False, let  $Q = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$  then If  $Q$  has orthogonal columns then Yes

$$\|Qx\|^2 = \|Qx\|^2 = (Qx)^T(Qx) = x^T Q^T Q x = x^T x = \|x\|^2$$

(20) B let  $q_1 = \frac{1}{\sqrt{4}} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$

$$\text{let } B = \begin{bmatrix} -4 \\ -3 \\ 3 \\ 0 \end{bmatrix} - \frac{(-2+1+3)}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -8-1 \\ -6-1 \\ 6-1 \\ -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -9 \\ -7 \\ 5 \\ -1 \end{bmatrix}$$

$\underbrace{\begin{array}{|c|c|c|c|} \hline 1 & 1 & 1 & 1 \\ \hline \end{array}}_{2}$

$$\text{Then } q_2 = \frac{1}{\sqrt{81+49+25+1}} \begin{bmatrix} -9 \\ -7 \\ 5 \\ -1 \end{bmatrix}$$

~~81~~ ~~49~~ ~~25~~ ~~1~~ ~~130~~  
~~49~~ ~~25~~ ~~1~~ ~~26~~  
~~25~~ ~~1~~ ~~2~~ ~~26~~  
~~1~~ ~~2~~ ~~2~~ ~~26~~  
~~26~~ ~~26~~ ~~26~~ ~~26~~

$$\text{let } B = \begin{bmatrix} -2 \\ 0 \\ 1 \\ 3 \end{bmatrix} - \frac{(-2+1+3)}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} -2 \\ 0 \\ 1 \\ 3 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} -4 & -1 \\ 0 & -1 \\ 2 & -1 \\ 3 & -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -5 \\ -1 \\ -1 \\ -5 \end{bmatrix}.$$

$$\text{Then } q_2 = \frac{\mathbf{B}}{\|\mathbf{B}\|} = \frac{1}{\sqrt{25+1+1+4}} \begin{bmatrix} -5 \\ -1 \\ -1 \\ -5 \end{bmatrix} = \frac{1}{\sqrt{31}} \begin{bmatrix} -5 \\ -1 \\ -1 \\ -5 \end{bmatrix} = \frac{1}{\sqrt{52}} \begin{bmatrix} -5 \\ -1 \\ -1 \\ -5 \end{bmatrix}$$

Then projecting  $\mathbf{b}$  onto the column space of  $\mathbf{A}$  is equivalent to computing

$$\begin{aligned} p &= (q_1^T \mathbf{b}) q_1 + (q_2^T \mathbf{b}) q_2 \\ &= \frac{1}{2}(-4-3+3) \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \frac{1}{\sqrt{52}} \cdot (20+3+3) \frac{1}{\sqrt{52}} \begin{bmatrix} -5 \\ -1 \\ -1 \\ -5 \end{bmatrix} \\ &= \begin{bmatrix} -1 \\ -1 \\ -1 \\ -1 \end{bmatrix} + \frac{2\mathbf{b}}{\sqrt{52}} \begin{bmatrix} -5 \\ -1 \\ -1 \\ -5 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -2-5 \\ -2-1 \\ -2+1 \\ -2+5 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -7 \\ -3 \\ -1 \\ 3 \end{bmatrix} \\ &\quad \Downarrow \frac{\mathbf{B}}{2\mathbf{b}} \\ &\quad \Downarrow \frac{1}{2} \end{aligned}$$

$$\text{Then } e = b - p = \frac{1}{2} \begin{bmatrix} -8+7 \\ -6+3 \\ 6+1 \\ -3 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -1 \\ -3 \\ 7 \\ -3 \end{bmatrix}$$

$$\text{so } e^T A(:,1) = \frac{1}{2} (-1 - 3 + 7 - 3) = 0 \quad \checkmark$$

$$+ \quad e^T A(:,2) = \frac{1}{2} (2 + 0 + 7 - 9) = 0 \quad \checkmark$$

$$\textcircled{21} \quad A = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} \quad \text{so } q_1 = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$$

$$B = \cancel{\begin{bmatrix} 1 & 1 & 2 \\ 1 & 1 & 2 \\ 2 & 1 & 1 \end{bmatrix}} - \cancel{\begin{bmatrix} 1 & 1 & 2 \\ 1 & 1 & 2 \\ 2 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}} \cdot \cancel{\frac{A^T}{A^T A} A}$$

$$= \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \frac{(1-1)}{A^T A} \cdot A = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$C = V - \frac{A^T}{A^T A} A - \frac{B^T}{B^T B} B$$

$$= \begin{bmatrix} 1 \\ 0 \\ 4 \end{bmatrix} - \frac{1}{6} \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 0 \\ 4 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\Rightarrow C = \frac{1}{2} \begin{bmatrix} 2 & -3 & -1 \\ 0 & -3 & +1 \\ 8 & -6 & +0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -2 \\ -2 \\ 2 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$$

(22) One could do this by performing elimination on  $A^T A$  as in problem 18 or just simply do ~~gaussian~~ perform gram-schmidt on the columns of the matrix  $A$ . We have

$$A = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + q_1 = A$$

with  $V = \boxed{\text{?}} [2 \ 0 \ 3]^T$  we have

$$B = V - \frac{V^T A}{A^T A} A = \begin{bmatrix} 2 \\ 0 \\ 3 \end{bmatrix} - \frac{2}{1} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix}$$

$$\text{so } q_2 = \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix}$$

Then if  $v = [4 \ 5 \ 6]^T$  we have a 3rd orthogonal vector  $C$

as

$$C = V - \frac{A^T V}{A^T A} A - \frac{B^T V}{B^T B} B = V \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} - \frac{4}{1} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} - 6 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ 5 \\ 0 \end{bmatrix}$$

$$\text{so that } A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 4 \\ 0 & 3 & 6 \\ 0 & 0 & 5 \end{bmatrix}$$

Pg 205 Soln

- (23) (a) The basis for a subspace for the plane given by

$$x_1 + x_2 + x_3 - x_4 = 0$$

Consider the matrix  $A = \begin{bmatrix} 1 & 1 & 1 & -1 \end{bmatrix}$  then ~~the span of~~ we need to consider the Nullspace, assign <sup>one</sup> ~~one~~ free variables to ones + zero.

$$x_2 = 1, x_3 = 0, x_4 = 0 \Rightarrow x = \begin{bmatrix} -1 & 1 & 0 & 0 \end{bmatrix}^T$$

$$x_2 = 0, x_3 = 1, x_4 = 0 \Rightarrow x = \begin{bmatrix} -1 & 0 & 1 & 0 \end{bmatrix}^T$$

$$x_2 = 0, x_3 = 0, x_4 = 1 \Rightarrow x = \begin{bmatrix} 1 & 0 & 0 & 1 \end{bmatrix}^T$$

This is a basis.

- (b) The orthogonal complement to  $S$  are all vectors <sup>y</sup> that

~~are~~ or orthogonal to each component of the Nullspace of

$A$ . This is the vector  $\begin{bmatrix} 1 & 1 & 1 & -1 \end{bmatrix}^T$ .

- (c) If ~~if~~  $b = (1, 1, 1, 1)^T$

Then to decompose  $b$  into  $b_1 + b_2$  consider the unit vector of the ~~orthogonal component~~ vector that spans the orthogonal complement i.e

$$q_2 = \frac{1}{2}(1, 1, 1, -1)^T \quad \text{Then}$$

$$b_2 = \cancel{(q_2^T b)} q_2 = \frac{1}{2}(2) \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 1 \\ -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 1 \\ -1 \end{bmatrix}$$

$$\text{Then } b_1 = b - b_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 1 \\ -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 2-1 \\ 2-1 \\ 2-1 \\ 2+1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 3 \end{bmatrix}$$

$$\textcircled{24} \quad A = QR \quad \text{with}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} =$$

$$q_1 = \frac{1}{\sqrt{a^2+c^2}} \begin{bmatrix} a \\ c \end{bmatrix}$$

$$B = \begin{bmatrix} b \\ d \end{bmatrix} - \begin{bmatrix} b & d \end{bmatrix} \frac{1}{\sqrt{a^2+c^2}} \begin{bmatrix} a \\ c \end{bmatrix} \cdot \frac{1}{\sqrt{a^2+c^2}} \begin{bmatrix} a \\ c \end{bmatrix}$$

$$= \begin{bmatrix} b \\ d \end{bmatrix} - \frac{1}{(a^2+c^2)} (ab+dc) \begin{bmatrix} a \\ c \end{bmatrix}$$

$$= \begin{bmatrix} b \\ d \end{bmatrix} - \left( \frac{ab+dc}{a^2+c^2} \right) \begin{bmatrix} a \\ c \end{bmatrix} = \frac{1}{a^2+c^2} \begin{bmatrix} b(a^2+c^2) - a(ab+dc) \\ d(a^2+c^2) - c(ab+dc) \end{bmatrix}$$

$$= \frac{1}{a^2+c^2} \begin{bmatrix} bc^2 - adc \\ da^2 - cab \end{bmatrix} = \frac{1}{(a^2+c^2)} \begin{bmatrix} c(bc-ad) \\ a(ad-cb) \end{bmatrix}$$

$$= \frac{(ad-bc)}{(a^2+c^2)} \begin{bmatrix} -c \\ a \end{bmatrix} \quad \text{is orthogonal to } \begin{bmatrix} a \\ c \end{bmatrix}$$

+ has a unit vector given by

$$\frac{1}{\sqrt{a^2+c^2}} \begin{bmatrix} -c \\ a \end{bmatrix}$$

So the matrix  $Q$  in the QR decomposition of  $A$  is given

~~$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$~~ 

$$Q = \frac{1}{\sqrt{a^2+c^2}} \begin{bmatrix} a & -c \\ c & a \end{bmatrix}$$

Then  $R$  is given by

$$R = \begin{bmatrix} q_1^T A(:,1) & q_1^T A(:,2) \\ q_2^T A(:,2) \end{bmatrix} = \frac{1}{\sqrt{a^2+c^2}} \begin{bmatrix} a^2+c^2 & ab+cd \\ 0 & -cb+ad \end{bmatrix}$$

So the decomposition is given by

$$A = \frac{1}{\sqrt{a^2+c^2}} \begin{bmatrix} a & -c \\ c & a \end{bmatrix} \frac{1}{\sqrt{a^2+c^2}} \begin{bmatrix} a^2+c^2 & ab+cd \\ 0 & ad-cb \end{bmatrix}$$

If  $a, b, c, d = 2, 1, 1, 1$  then we obtain

$$\begin{aligned} A &= \frac{1}{\sqrt{5}} \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \frac{1}{\sqrt{5}} \begin{bmatrix} 5 & 2+1 \\ 0 & 2-1 \end{bmatrix} \\ &= \frac{1}{\sqrt{5}} \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \frac{1}{\sqrt{5}} \begin{bmatrix} 5 & 3 \\ 0 & 1 \end{bmatrix} \end{aligned}$$

If  $a, b, c, d = 1, 1, 1, 1$  then we obtain

$$A = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \frac{1}{\sqrt{2}} \begin{bmatrix} 2 & 2 \\ 0 & 0 \end{bmatrix}$$

From which we see that the (2,2) element of  $R$  is zero.

$$\textcircled{25} \quad \text{Eq 8 is given by } C = C - \frac{A^T C}{A^T A} A - \frac{B^T C}{B^T B} B$$

The 1st equation in 12 is given by

$$r_{kj} = \sum_{i=1}^m q_{ik} a_{ij} \quad \text{is the expression for the dot product between}$$

The  $k$ th column of  $A$  + the ~~other~~  $j$ th column of  $A$ .

Then  $\cancel{q_{ik}} a_{ij} = a_{ij} - q_{ik} r_{kj}$  subtracts the projection onto the basis function

$\textcircled{26}$   $a + b$  may not be orthogonal so by subtracting the projections along non orthogonal vectors one may be stable certianly.

$\textcircled{27}$  See Matlab code prob/R chep4-set-4-4-prob-27.m

$\textcircled{28}$  Eq 11 involves  $m$  multiplications for the summation +  $m$  divisions for  $q_{ik} = \frac{a_{ik}}{r_{kk}} = O(2m)$

Then Eq 12 involves  $O(2m)$  multiplications

~~thus~~ Each of these multiplications are performed without tiles  
Thus we have

$$\begin{aligned}
 & \sum_{k=1}^n 2m + \sum_{j=k+1}^n 2m = \boxed{\cancel{2m}} + 2mn + \sum_{k=1}^n 2m(n-k-1+1) \\
 & = 2mn + 2m \sum_{k=1}^{n-1} (n-k) = 2mn + 2m \sum_{k=1}^{n-1} k \\
 & = 2mn + 2m \left( \frac{n(n-1)}{2} \right) = 2mn + mn(n-1) = mn^2 - mn + 2mn \\
 & = mn^2 + mn \quad \text{which is the required # of flops}
 \end{aligned}$$

(29) (a) Check that  $Q^T Q = I$ , when carrying this product we have

$$\begin{aligned}
 Q^T Q &= \cancel{c^2} / 4 \quad c^2 \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & -1 & -1 & -1 \end{bmatrix} \begin{bmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & -1 & 1 & 1 \\ -1 & -1 & -1 & 1 \end{bmatrix} \\
 &= c^2 \begin{bmatrix} 4 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix} \quad \text{By multiplying } \cancel{c^2} \Rightarrow c = \frac{1}{2}
 \end{aligned}$$

(b)  $Q = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & -1 & 1 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -1 & -1 \end{bmatrix}$  which will be orthogonal if  $c = \frac{1}{2}$  as below

~~Q = P + Q\_perp~~

$$\textcircled{30} \quad q_1^T b = \frac{1}{2}(-2) = -1 \quad \text{onto the 1st column of } Q \text{ we have}$$

$$+ q_2^T b = \frac{1}{2}(-2) = -1$$

$$q_1^T b = \frac{1}{2}(-2) = -1 \quad \text{then we have}$$

$$P = -\frac{1}{2} \begin{bmatrix} 1 \\ -1 \\ -1 \end{bmatrix} = -\frac{1}{2} \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

To project onto the 1st 2 columns of the matrix A we give

$$(q_1^T b) = -1$$

$$+ q_2^T b = \frac{1}{2}(-2) = -1$$

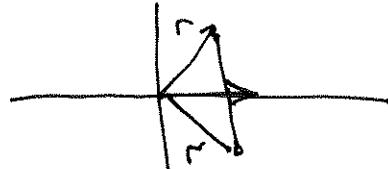
Then  $P = -\frac{1}{2} \begin{bmatrix} +1 \\ -1 \\ -1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} = -\frac{1}{2} \begin{bmatrix} 1-1 \\ -1+1 \\ -1-1 \end{bmatrix} = -\frac{1}{2} \begin{bmatrix} 0 \\ 0 \\ -2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix}$

pg 206 Slag

(8)  $Q = I - 2uv^T$  is a reflection matrix.

$$\text{If } v = (0, 1) \text{ then } vv^T = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\text{then } Q = I - \begin{bmatrix} 0 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$



$$\text{If } r = \begin{bmatrix} x \\ y \end{bmatrix} \text{ then } Qr = \begin{bmatrix} x \\ -y \end{bmatrix}$$

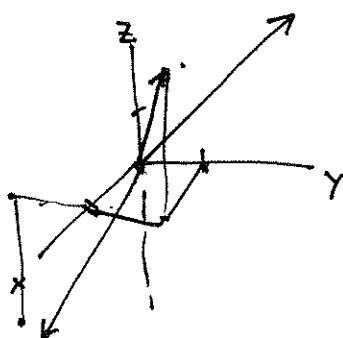
$$\text{If } v = (0, Y_2, Y_2) \text{ then}$$

$$vv^T = \begin{bmatrix} 0 \\ Y_2 \\ Y_2 \end{bmatrix} \begin{bmatrix} 0 & Y_2 & Y_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & Y_2 & Y_2 \\ 0 & Y_2 & Y_2 \end{bmatrix}$$

$$\text{so } Q = I - 2vv^T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$

so given  $(x, y, z)$  we see that

$$Q \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \\ -z \\ -y \end{bmatrix}$$



$$\textcircled{32} \quad Q = I - 2vw^T \quad \text{then} \quad v^T v = 0 \quad 1$$

$$(a) \quad \text{Then} \quad Qv = v - 2vv^Tv = v - 2v = -v$$

$$(b) \quad \text{If} \quad Qv = v^T v = 0 \quad \text{then}$$

$$Qv = v - 2vv^T v = v$$

\textcircled{33} \quad If the columns of  $W$  are orthonormal, the inverse of  $W$  is  
in its transpose

$$W^{-1} = W^T = \frac{1}{2} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & -1 & -1 \\ \sqrt{2}/2 & 0 & 0 & 0 \\ 0 & 0 & \sqrt{2} & -\sqrt{2} \end{bmatrix}$$